

好みを学習して支援するデザイン支援システム

小山 裕己（産業技術総合研究所）

2023-07-25 | 第67回AIセミナー「HCI × AI：人工知能で進化するHCI研究の最前線」

自己紹介



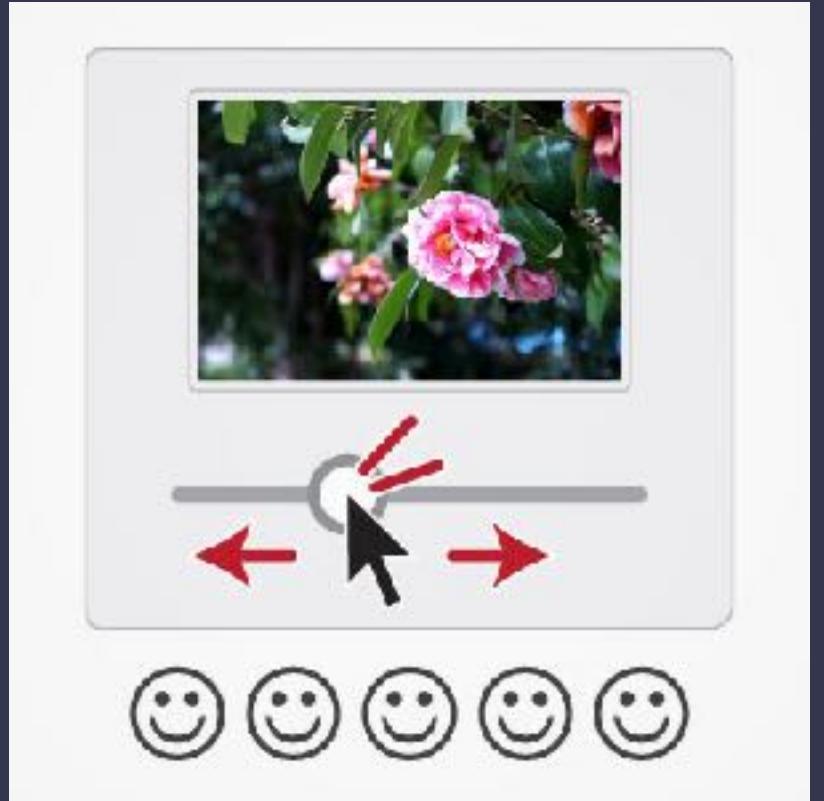
Yuki Koyama

小山 裕己

<https://koyama.xyz/>

- 専門分野
 - Computer Graphics (CG)
 - 最適化計算に基づくデザイン・コンテンツ創作支援
(Computational Design)
 - Human-Computer Interaction (HCI)
 - 数理技術に基づくインタラクション
(Computational Interaction)
- 最近の研究トピック
 - Human-in-the-Loopベース最適化

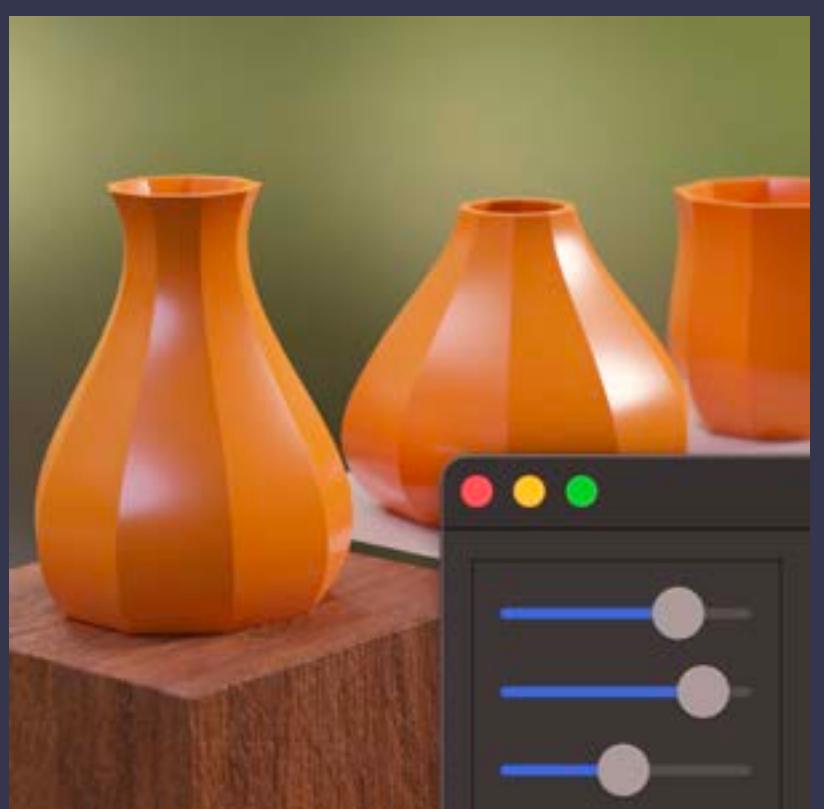
- 研究背景とアプローチ
- 研究 1 : Sequential Line Search [SIGGRAPH 2017]
- 研究 2 : Sequential Gallery [SIGGRAPH 2020]
- 研究 3 : BO as Assistant [UIST 2022]
- まとめと議論



Sequential Line Search
[SIGGRAPH 2017]



Sequential Gallery
[SIGGRAPH 2020]

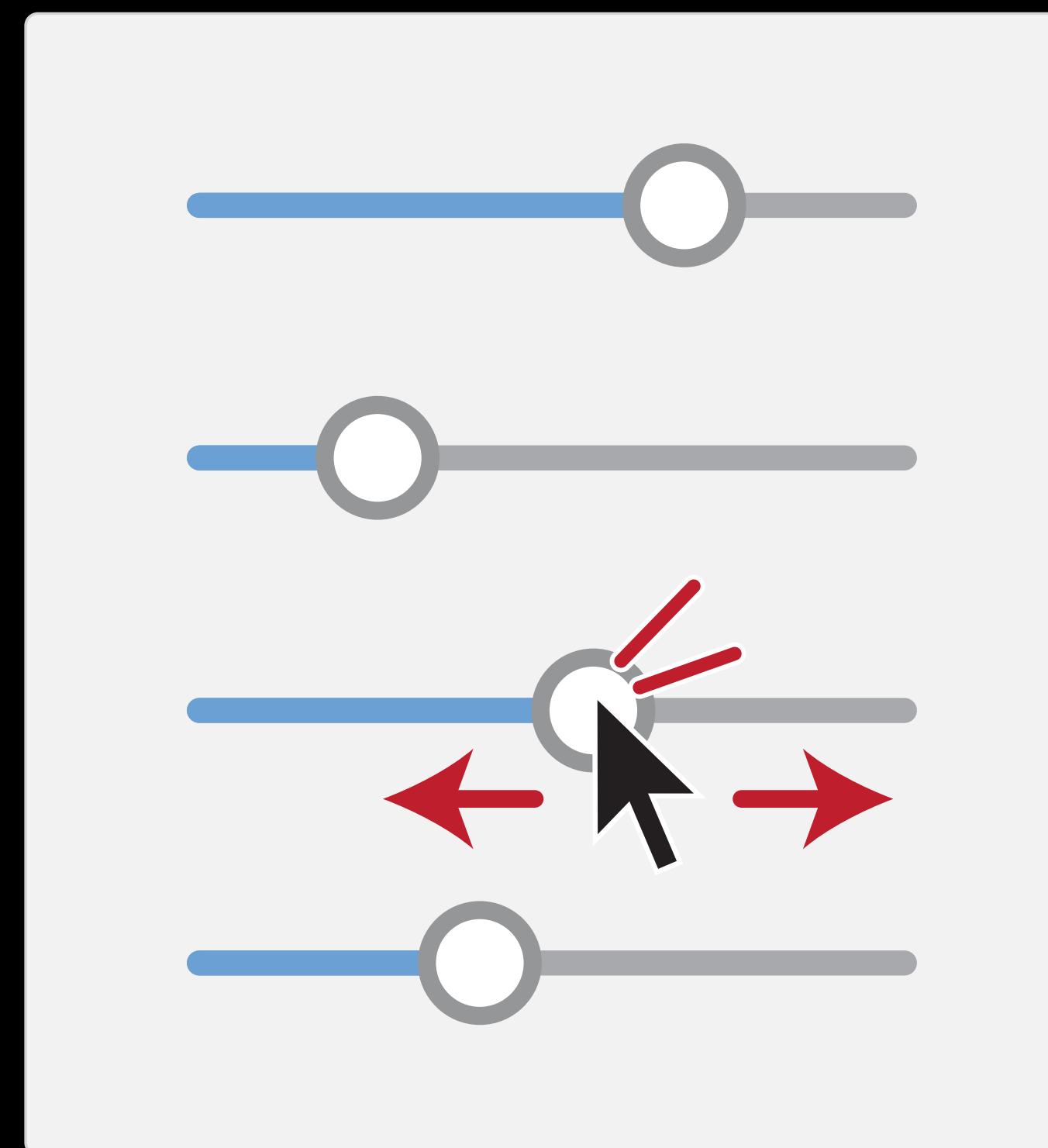


BO as Assistant
[UIST 2022]

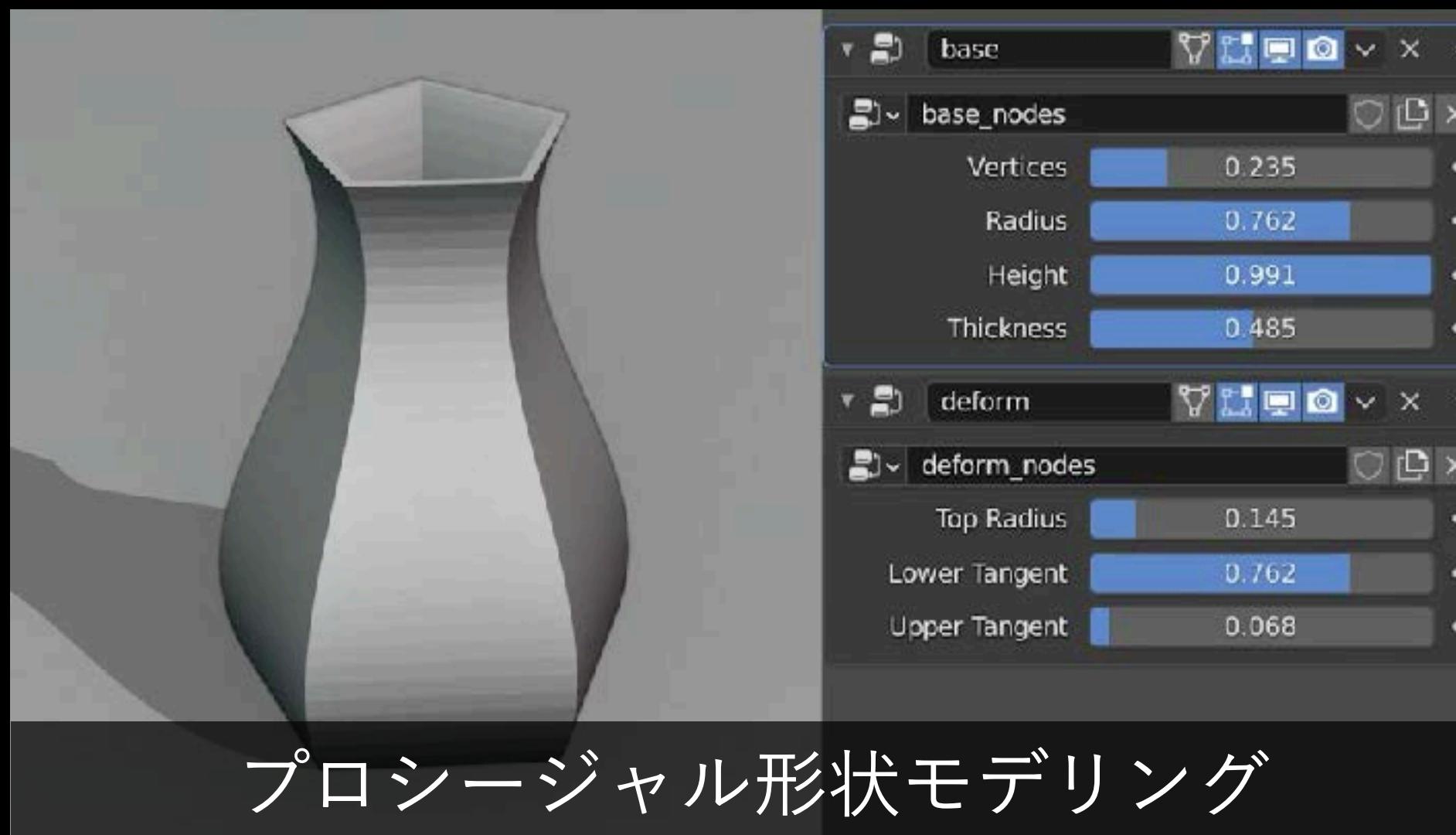
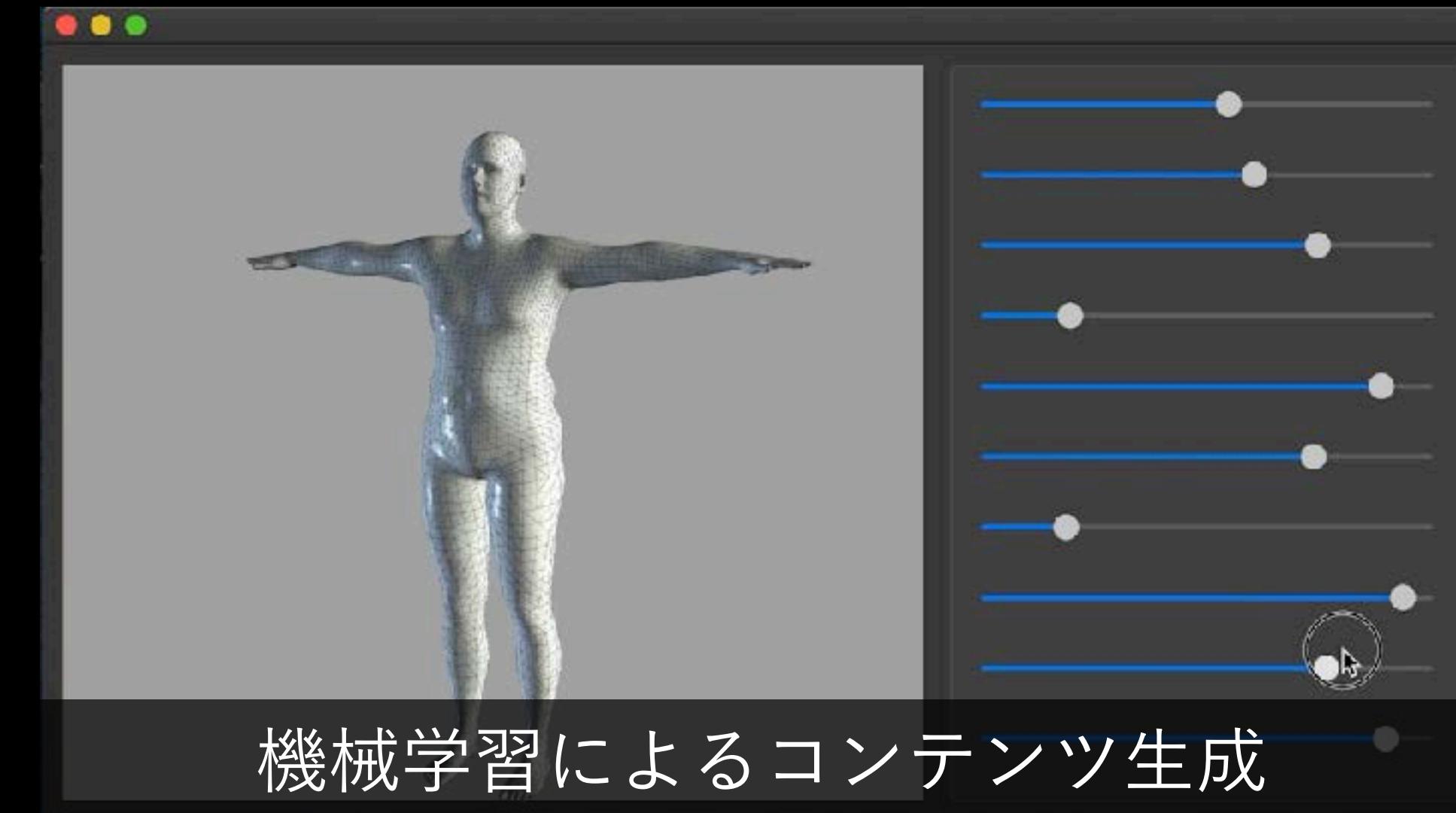
研究背景とアプローチ

Human-in-the-Loopデザイン最適化

パラメタ調整タスクは様々なデザインの文脈に共通して登場する

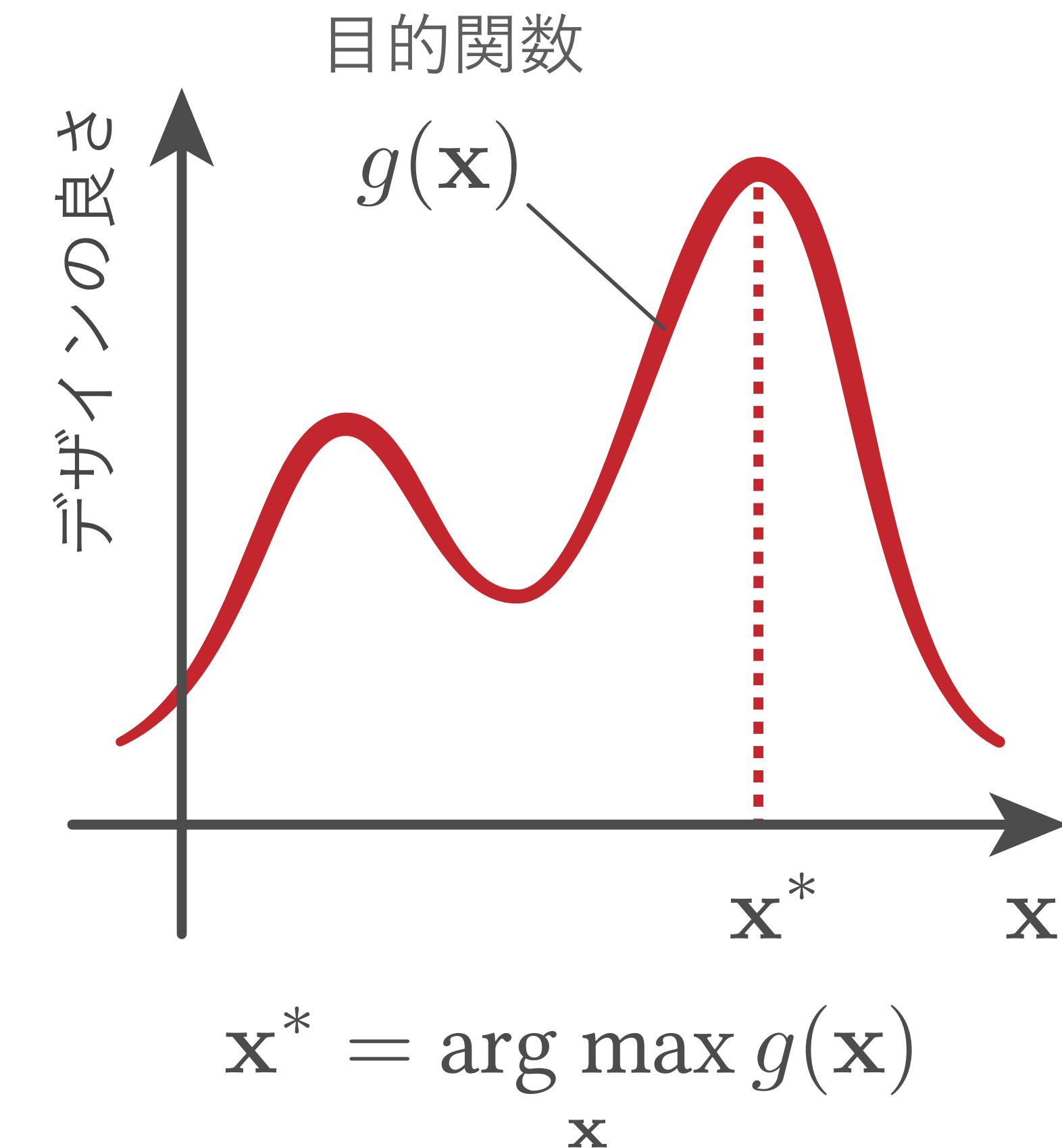
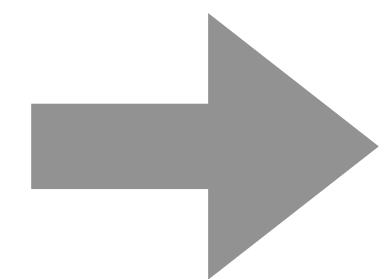
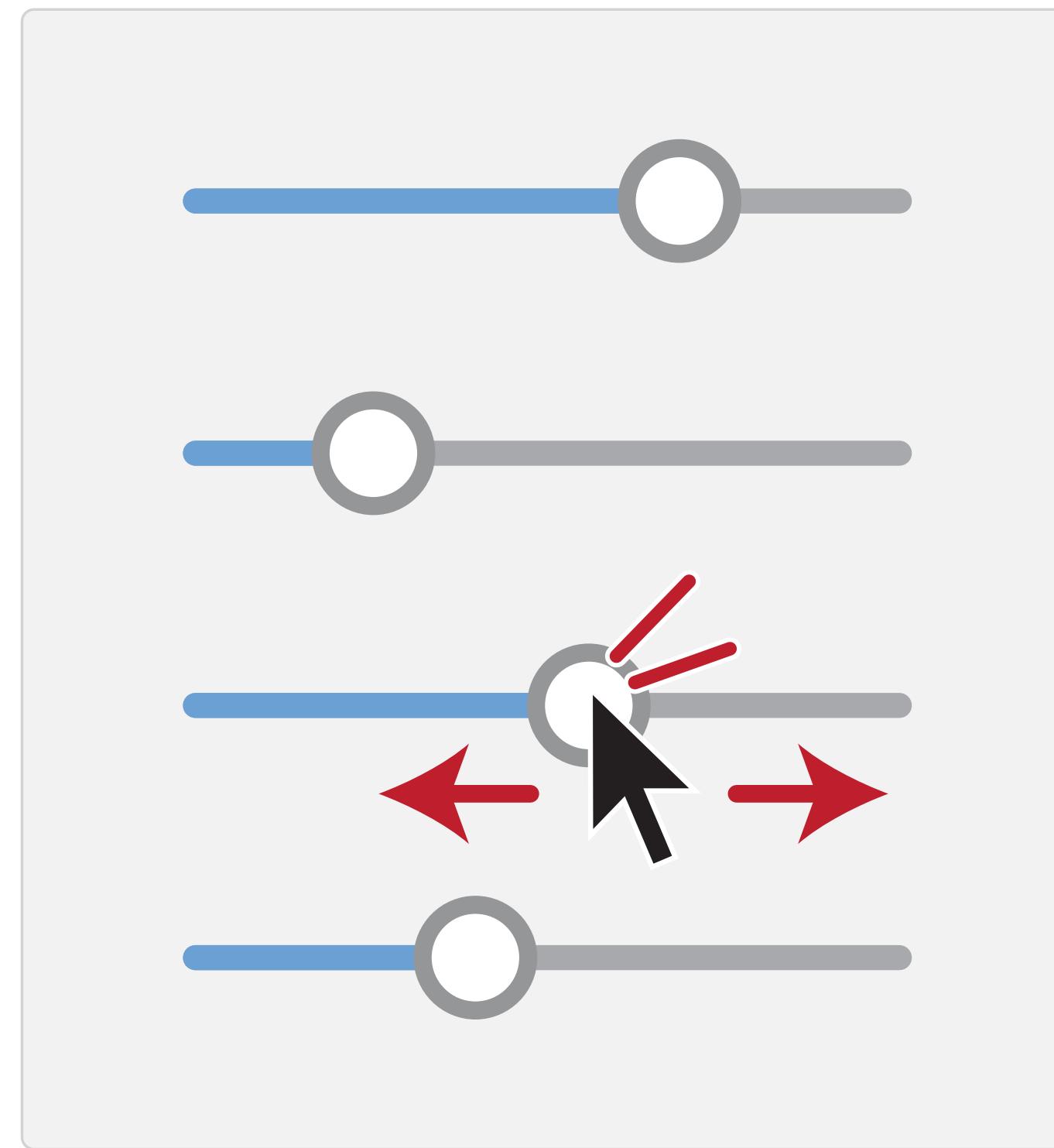


パラメタ調整タスクは様々なデザインの文脈に共通して登場する



数学的な解釈（モデル化）

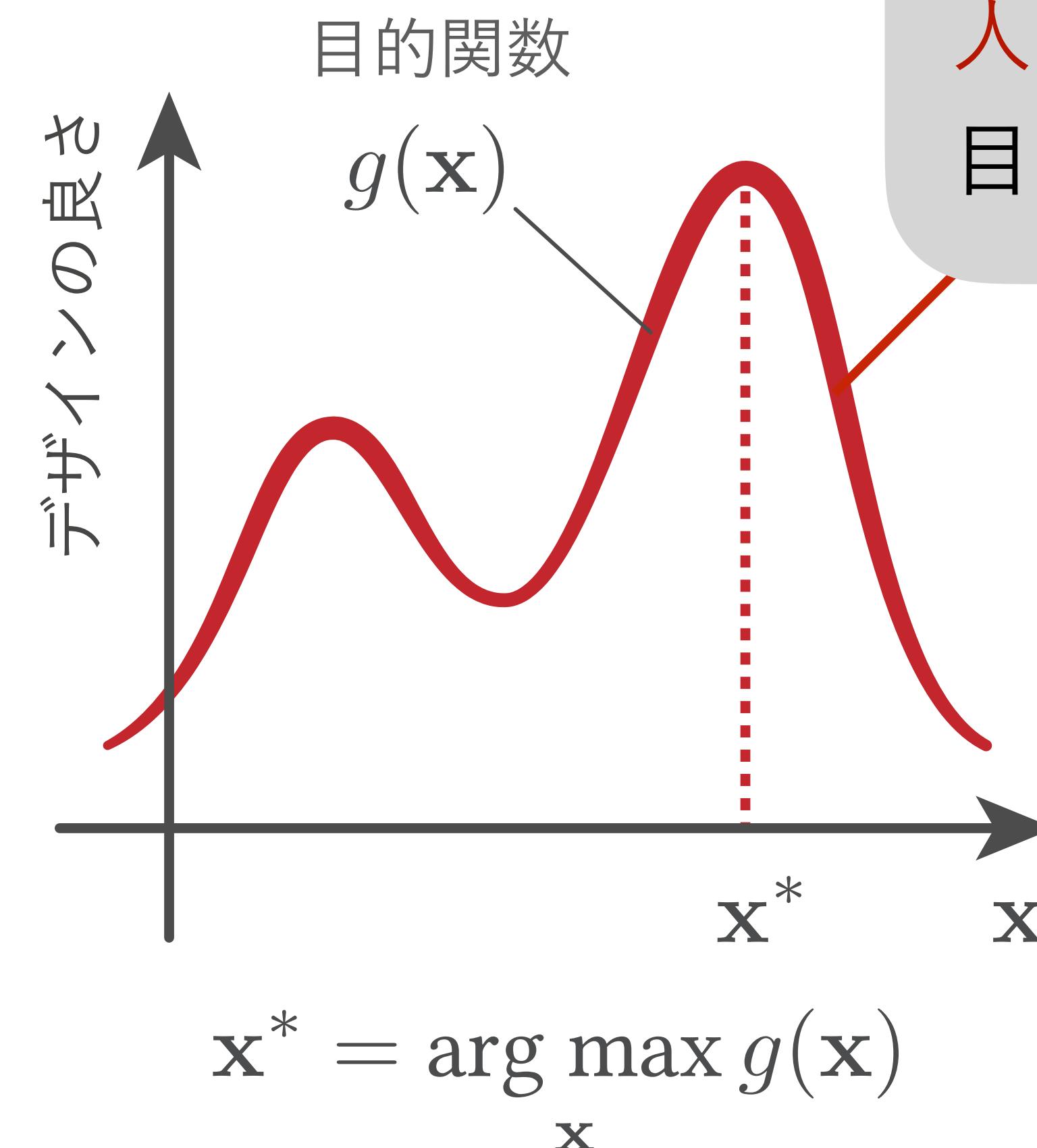
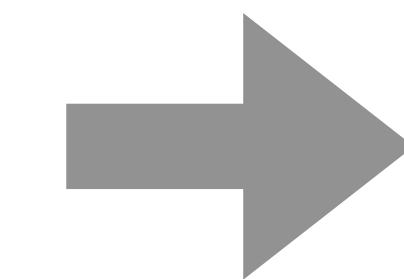
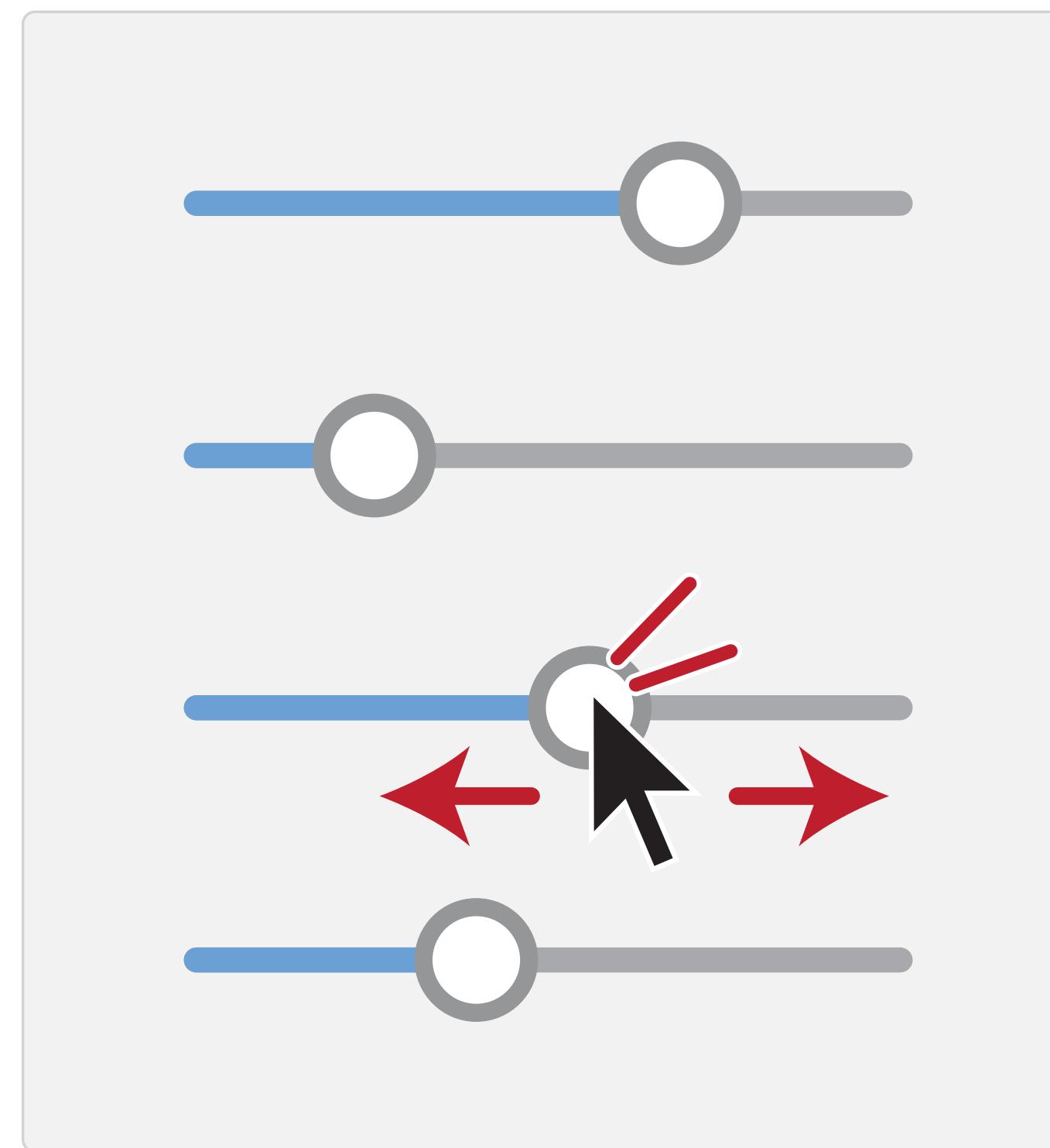
[*]



デザインにおけるパラメタ調整

最適化問題

数学的な解釈（モデル化）^[*]



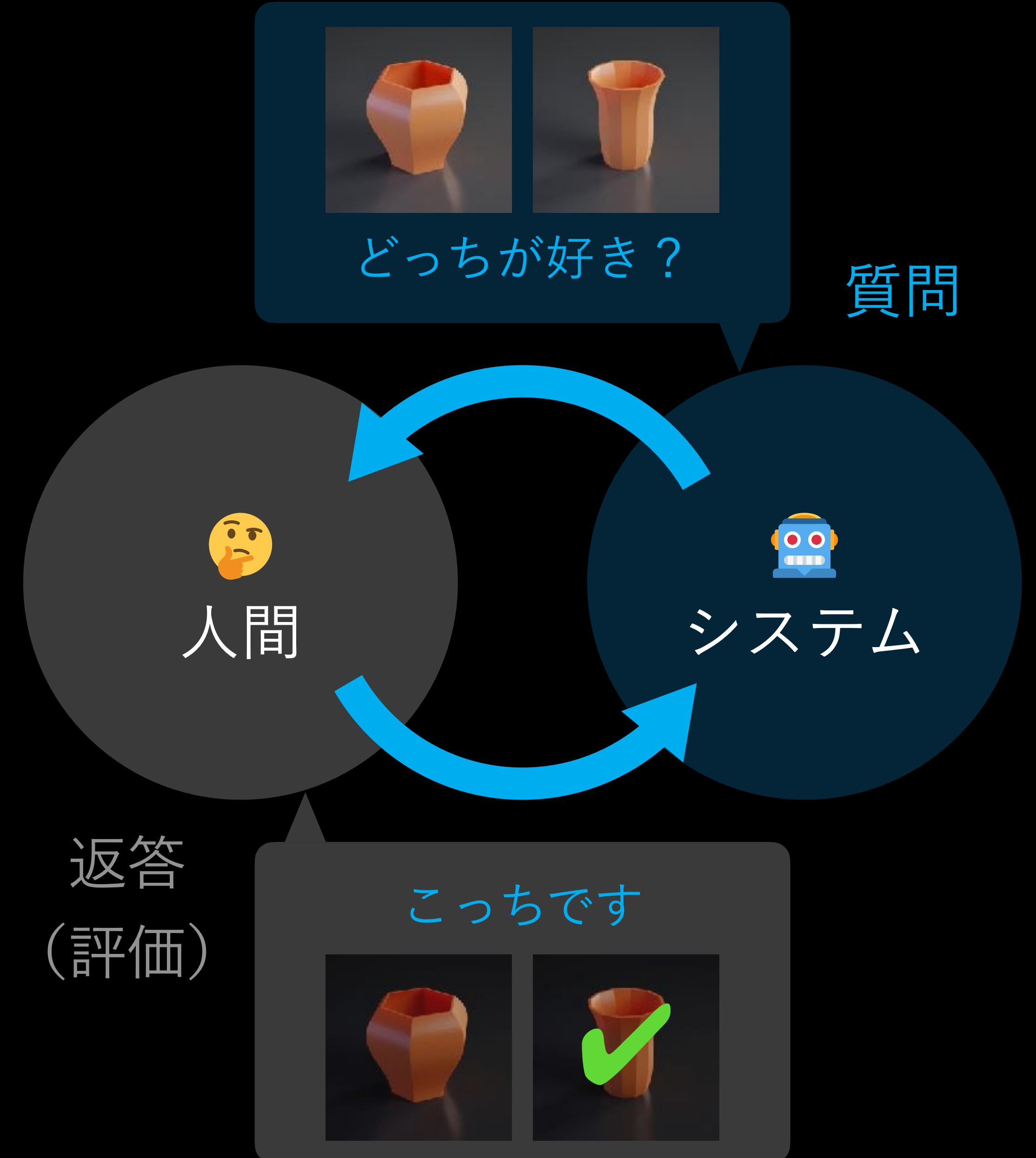
難しさ：
人間の評価によって
目的関数が定義される

デザインにおけるパラメタ調整

最適化問題

Human-in-the-loop最適化

人間の評価が必要な目的関数を
対象とする最適化問題を解く
ためのアプローチ

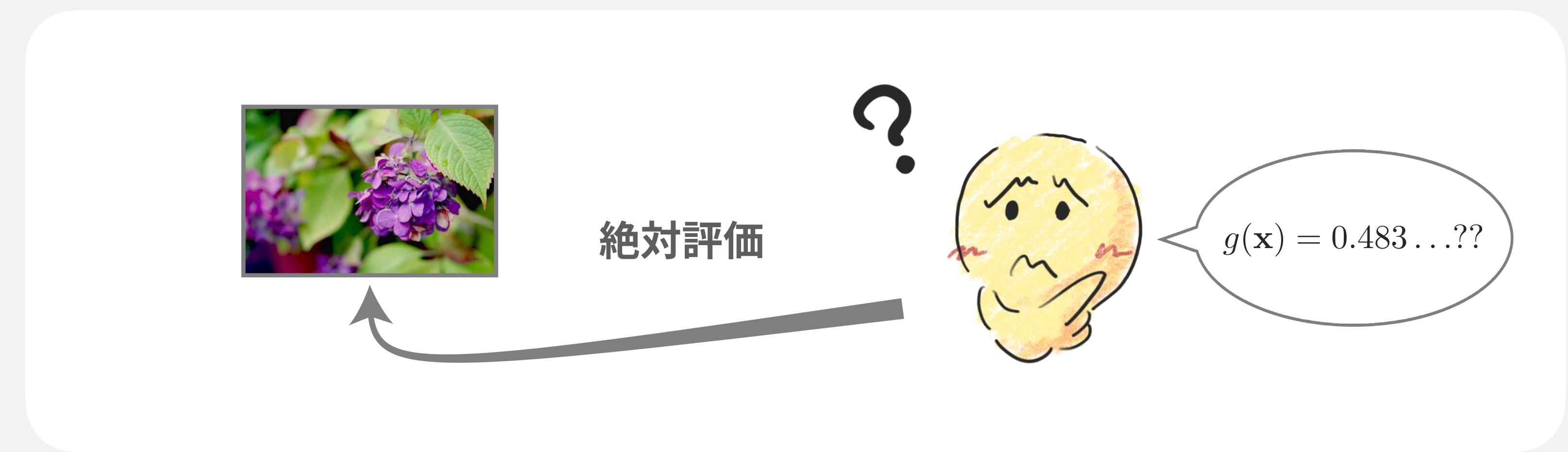


Human-in-the-Loop最適化の要件 [1/2]

絶対評価を用いるのは
好ましくない：

ユーザは関数の値を安定に
答えることができない

[Brochu+10; Koyama+18]



相対評価を用いるのが
好ましい：

ユーザは複数の選択肢の
中から相対的に良いものを
安定に選ぶことができる



Human-in-the-Loop最適化の要件 [2/2]

- 全体の反復回数が十分に少ない必要がある
 - 人間のレスポンスは遅い
 - 人間は疲れてしまう



選好ベイズ最適化 Preferential Bayesian Optimization (PBO)

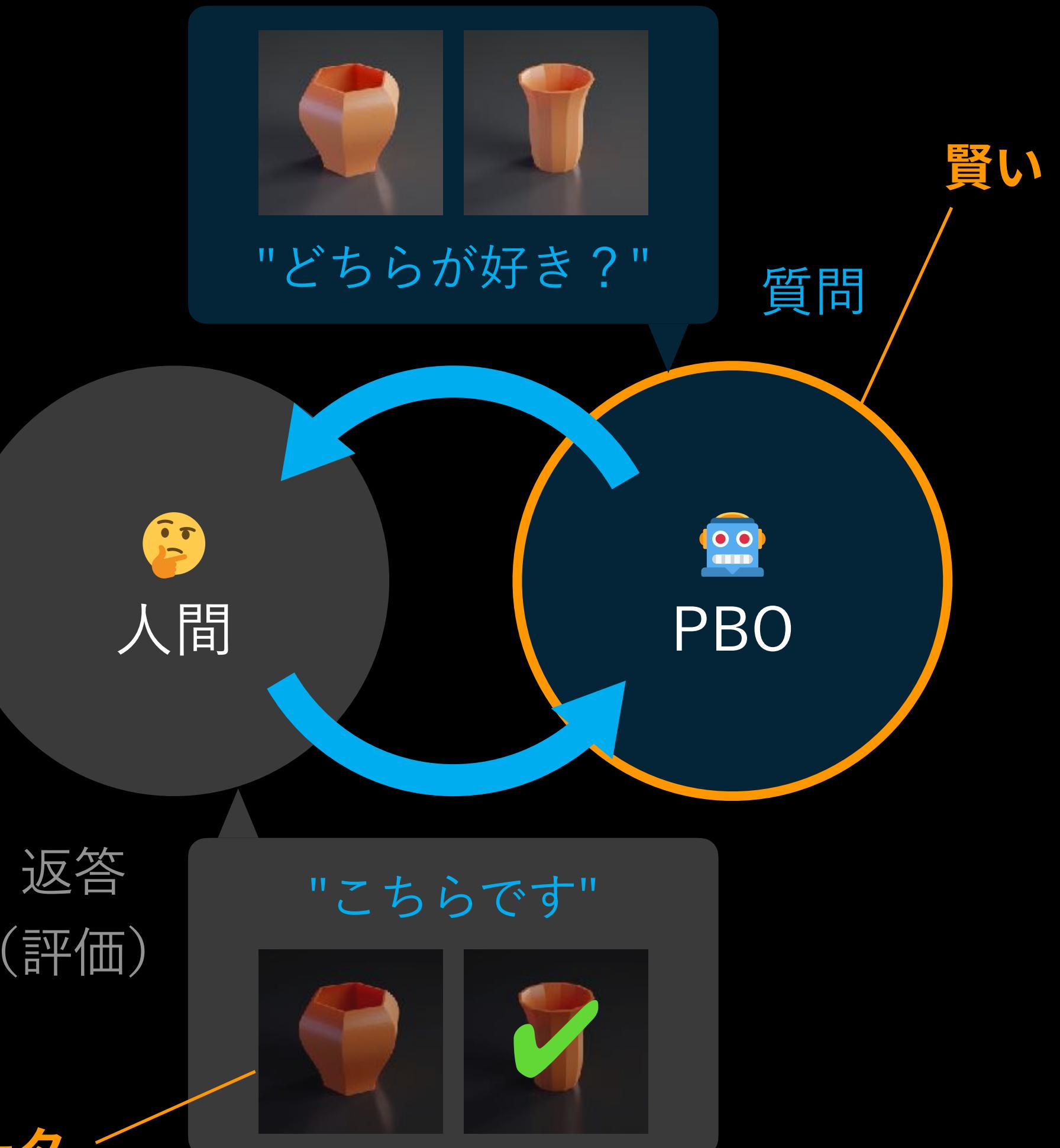
ベイズ最適化 (BO) の派生手法 [Brochu+, NIPS 2007]

- 賢いサンプリング戦略で質問を生成

特徴：

- 相対比較データ（絶対評価データではなく）から好みを推定して最適化を実行
- 少ない反復回数で解を見つける性質

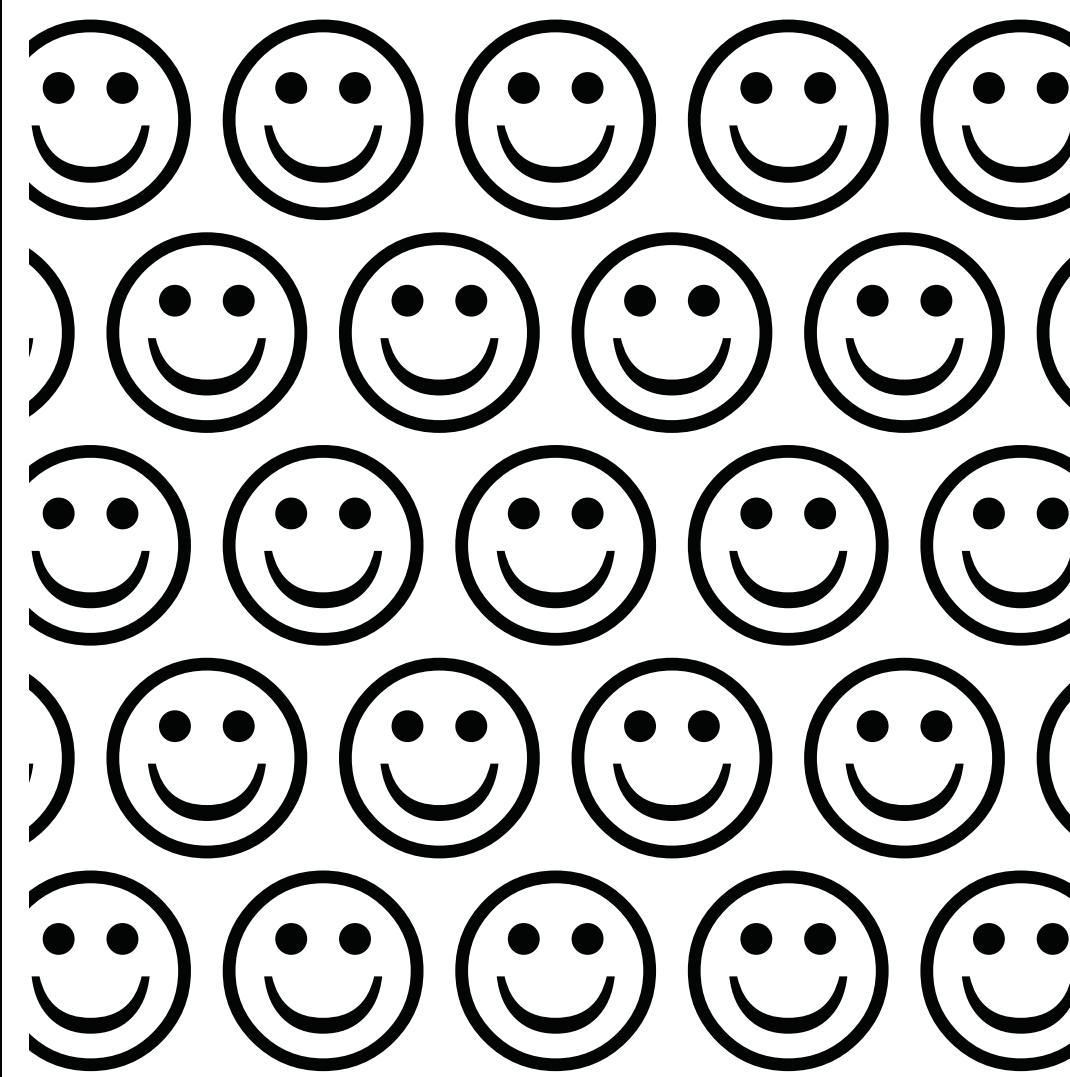
→ Human-in-the-Loop最適化と相性が良い



研究事例 1

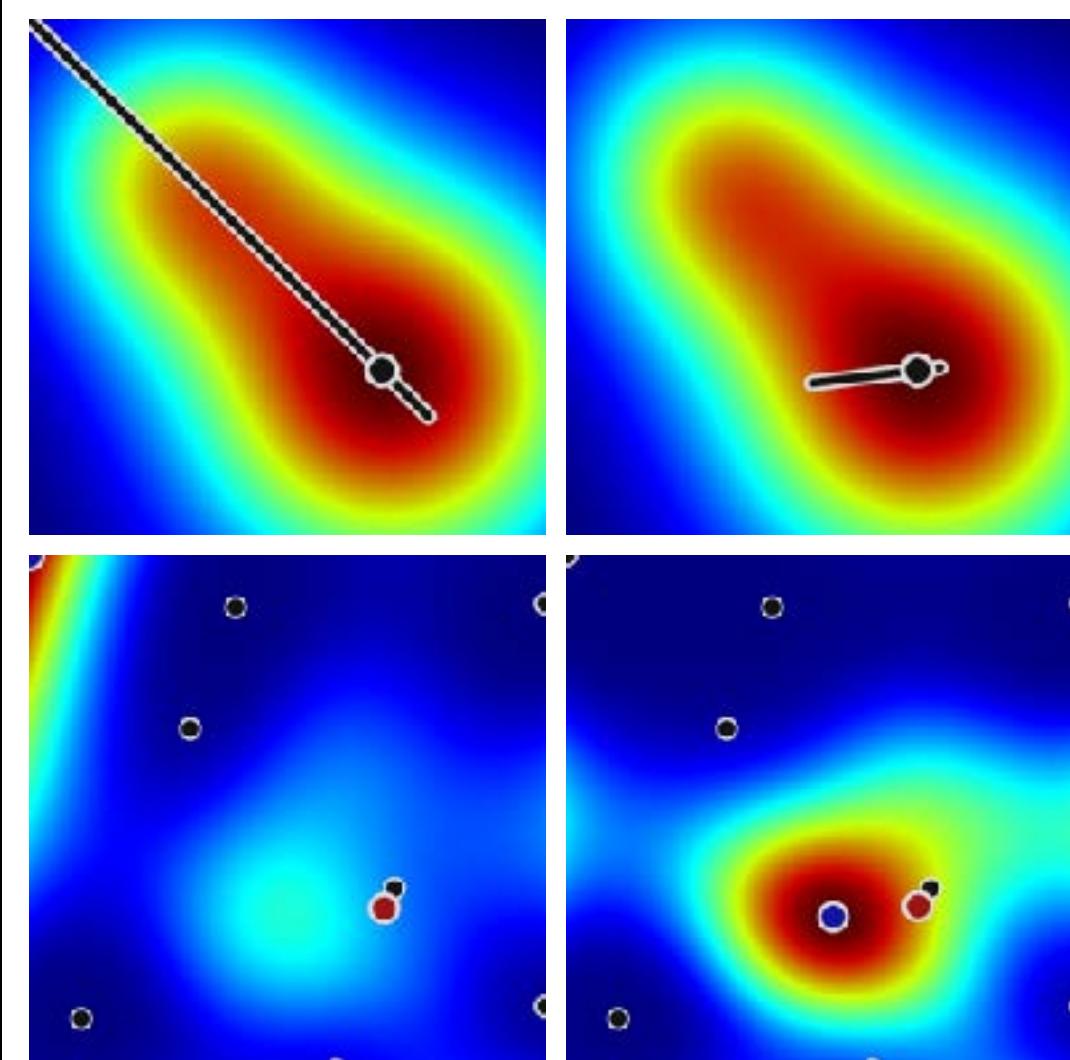
Sequential Line Search [SIGGRAPH 2017]

研究の貢献



コンセプト提案：Crowd-in-the-Loop最適化

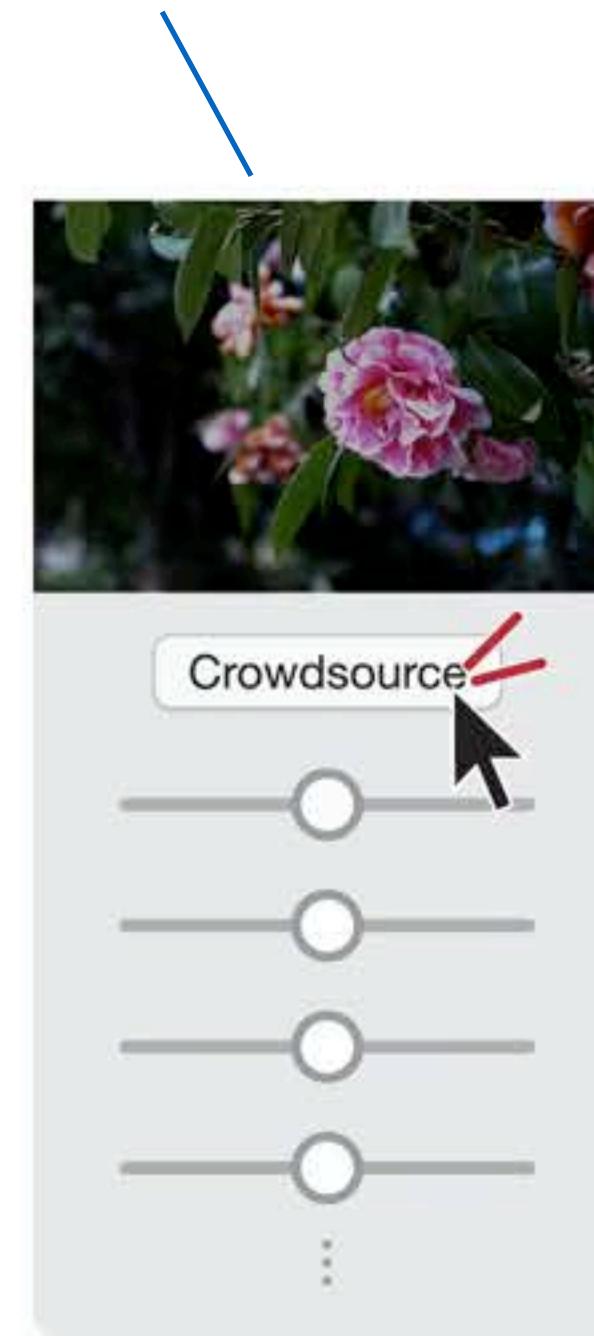
クラウドワーカー力を計算資源とみなして最適化を実行する
仕組み



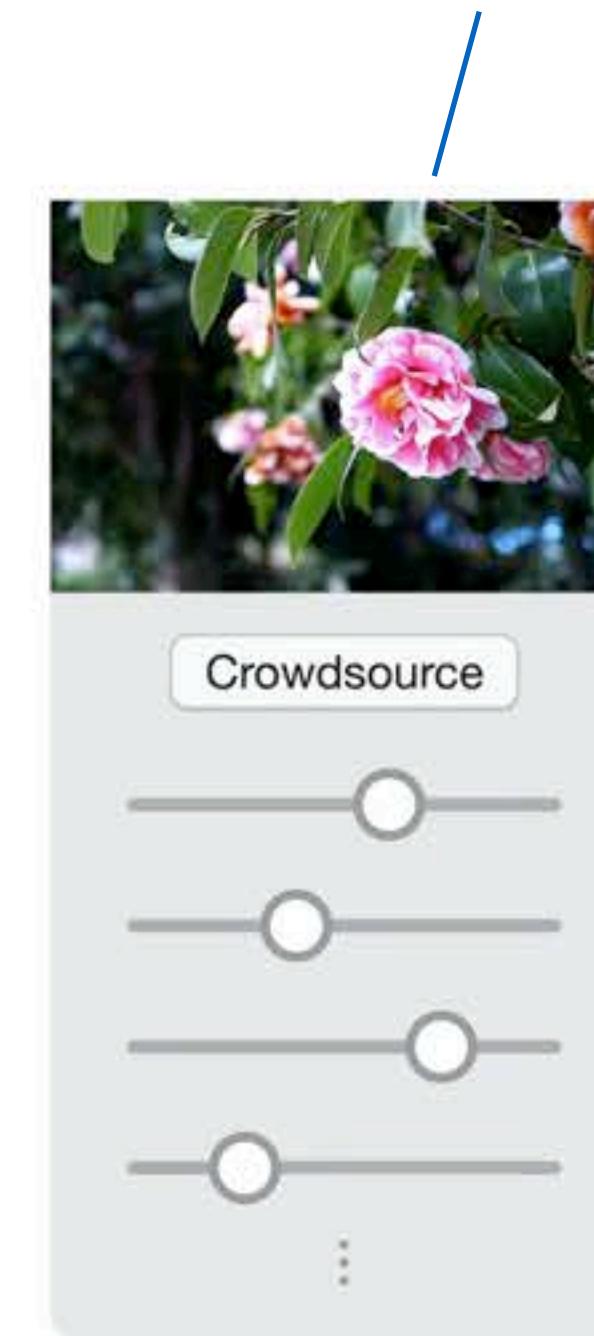
技術提案：Sequential Line Search法

選好ベイズ最適化 (PBO) を拡張して "Line Search" の
質問方式を扱えるようにすることで効率性を向上

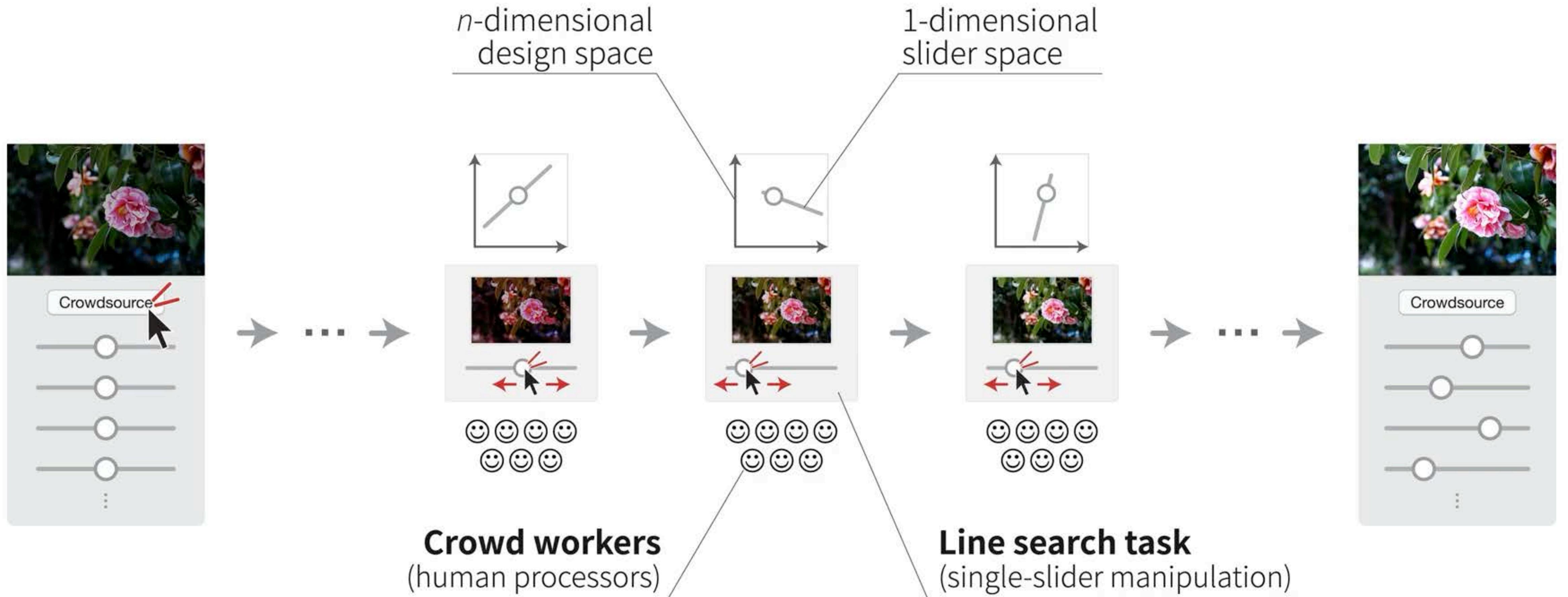
「クラウド最適化」ボタン



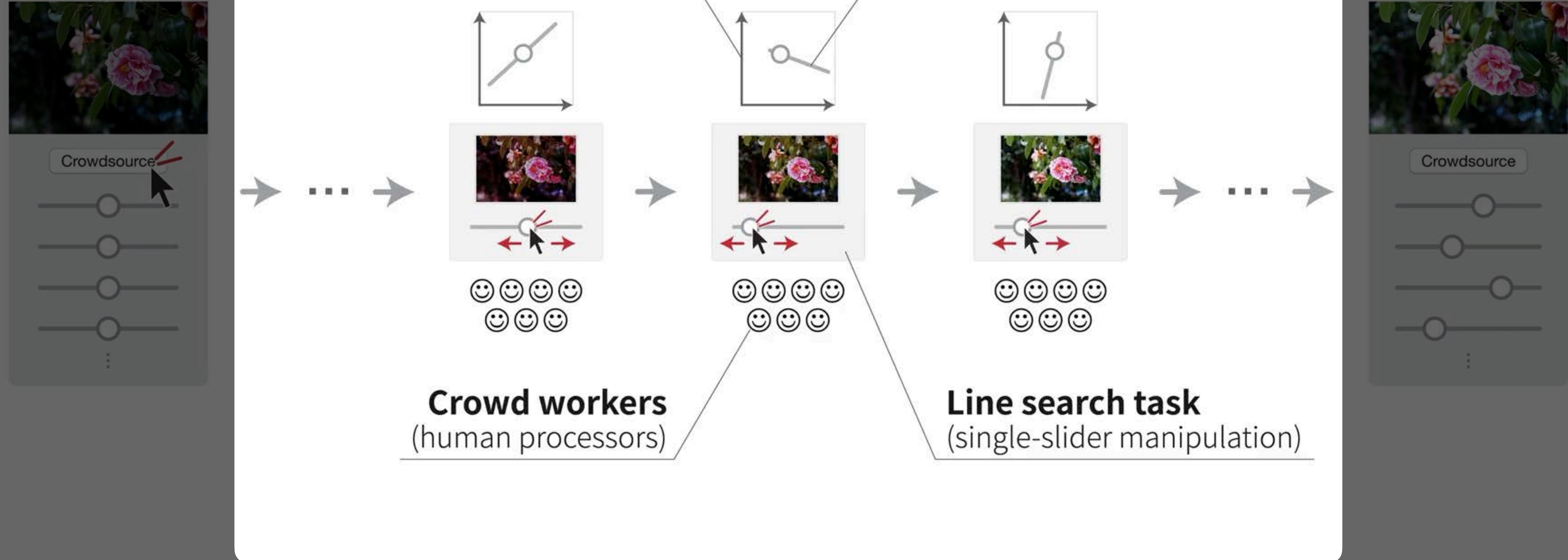
“People’s Choice”
最適なスライダ値



Crowd-in-the-Loop最適化

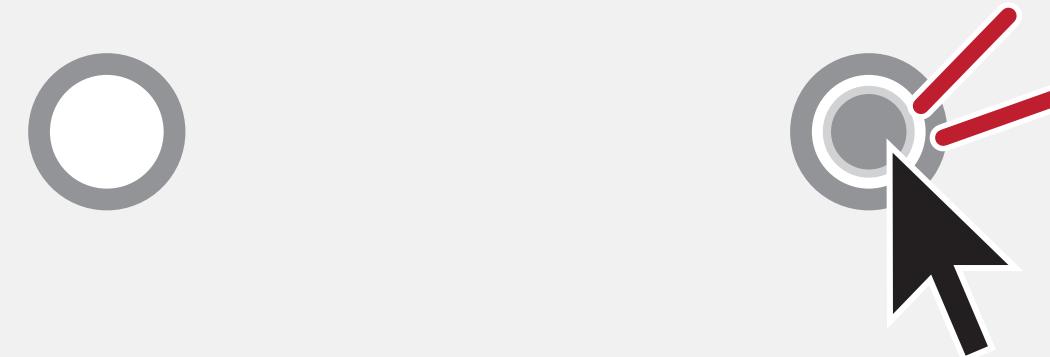
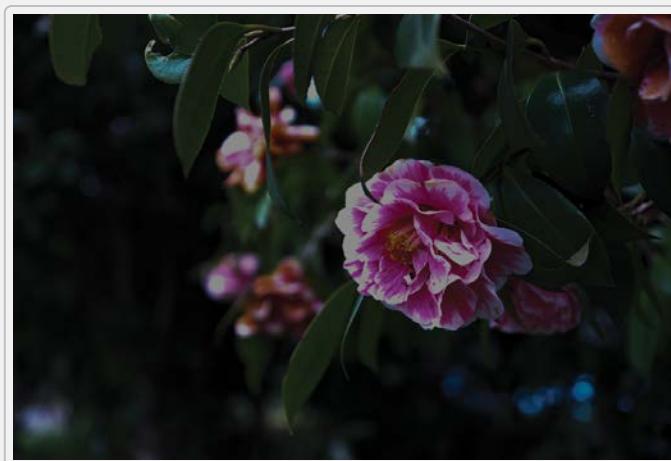


Sequential Line Search法 (本研究で提案する選好ベイズ最適化の新しい拡張)



相対比較に関する質問方式の設計の工夫

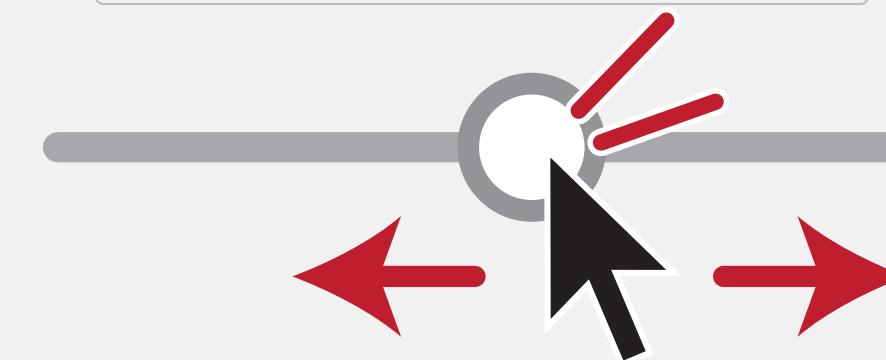
Task: Choose the image that looks better



基本：一对比較

(e.g., [Brochu+, NIPS 2007])

Task: Adjust the slider so that the image looks the best



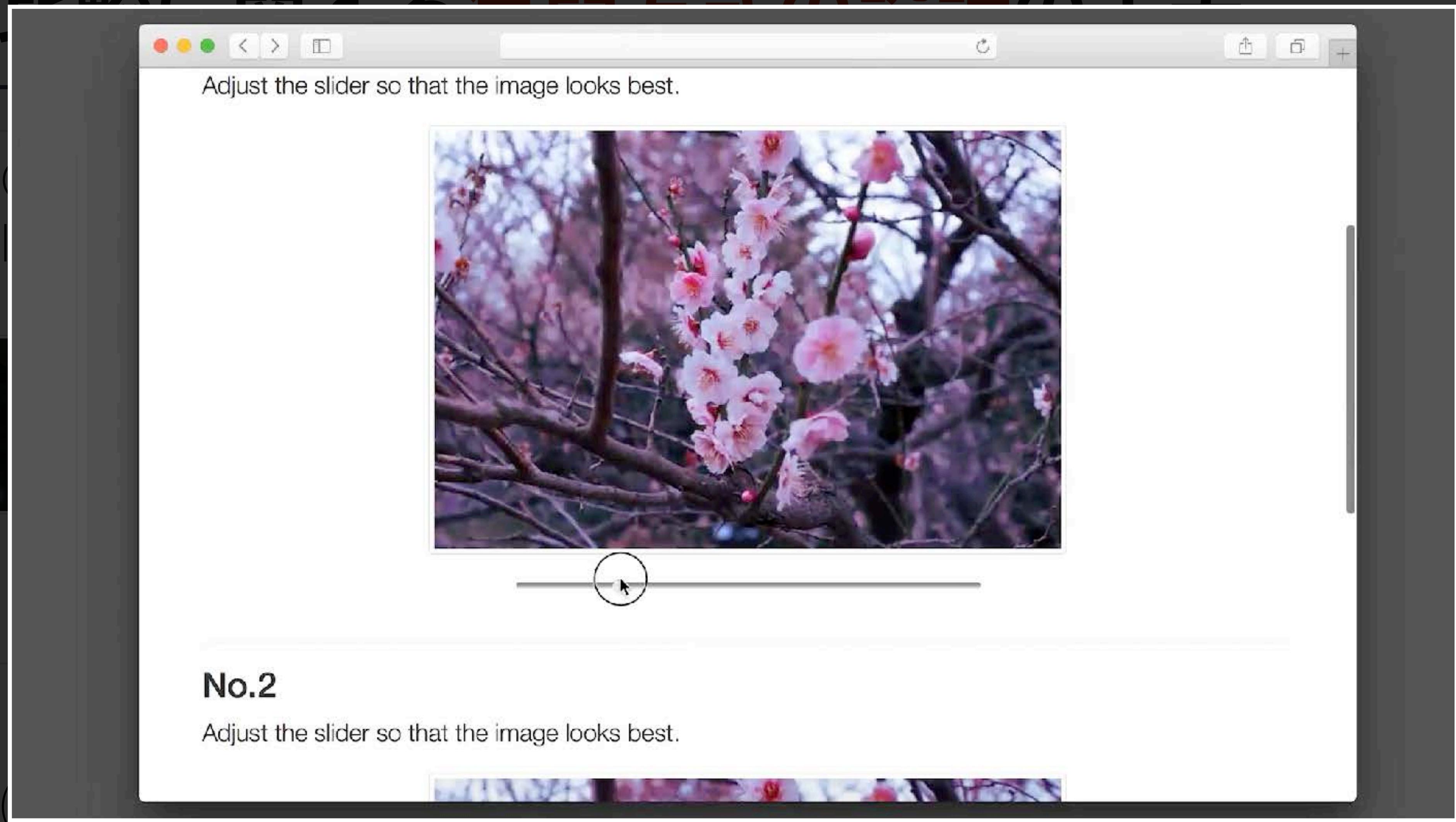
本研究で提案：一つのスライダを操作

(一度により多くの情報を得られる)

→ より少ない反復回数で解を発見

相対トレスホー問題と近似法による解の発見

Task:

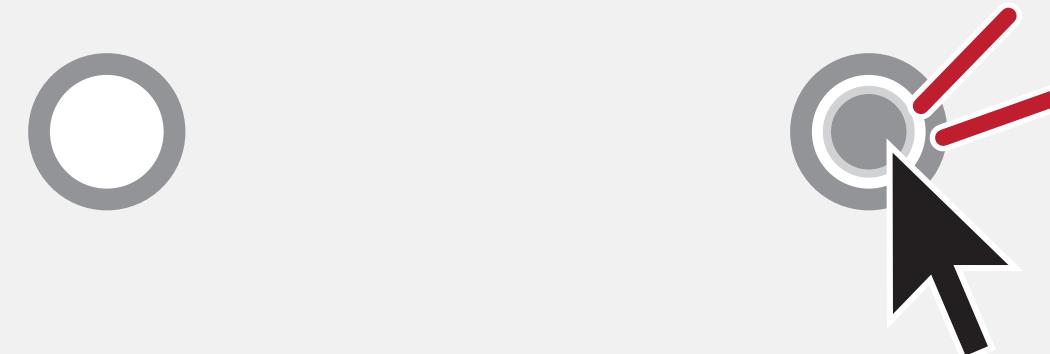
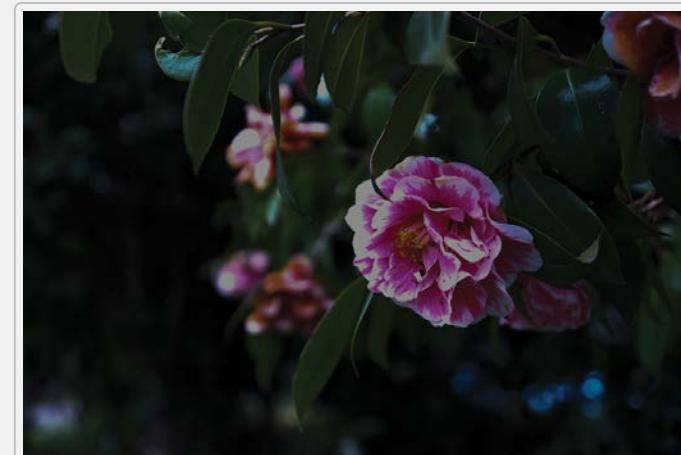


実際の回答の様子

→ より少ない反復回数で解を発見

相対比較に関する質問方式の設計の工夫

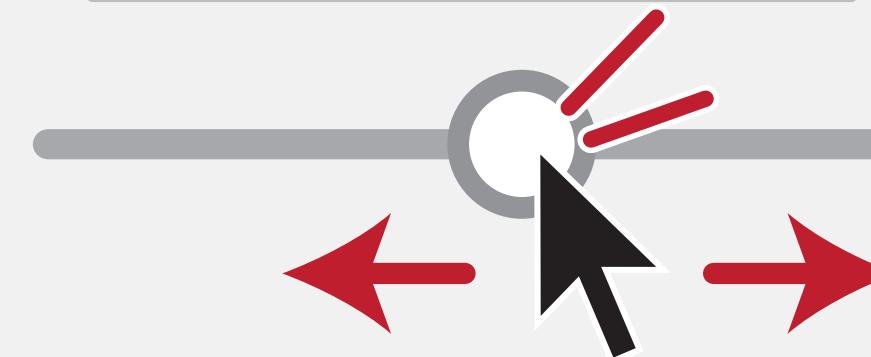
Task: Choose the image that looks better



基本：一对比較

(e.g., [Brochu+, NIPS 2007])

Task: Adjust the slider so that the image looks the best

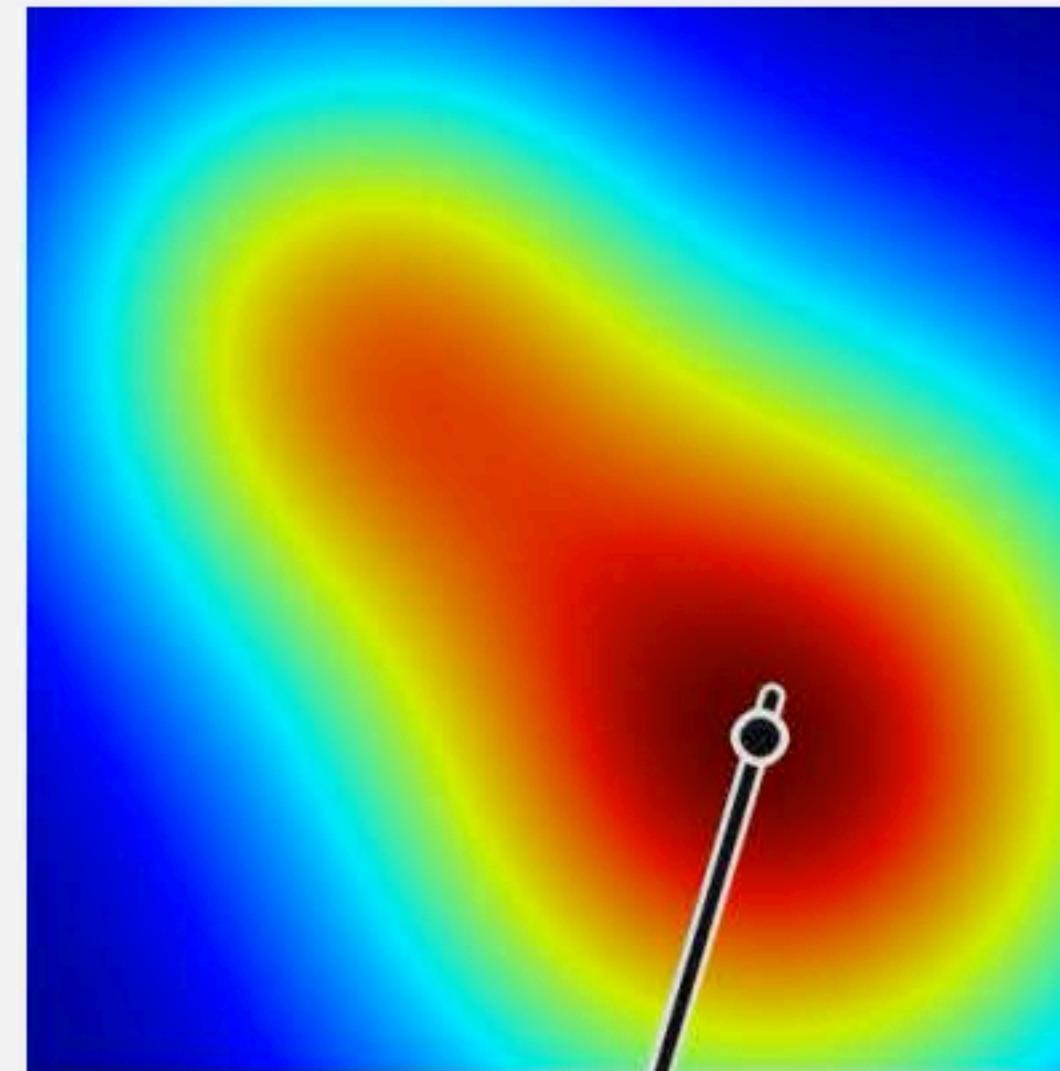


本研究で提案：一つのスライダを操作

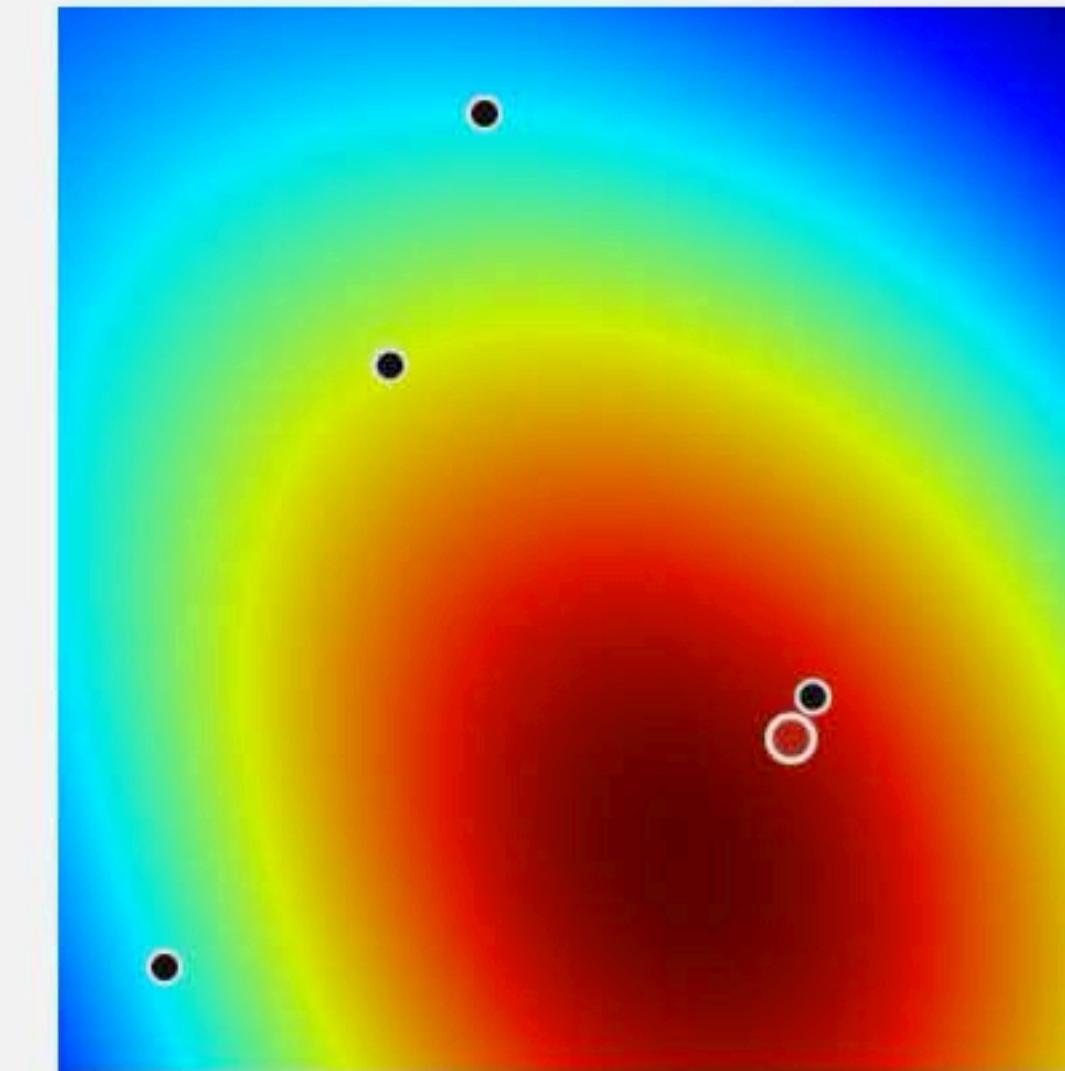
(一度により多くの情報を得られる)

→ より少ない反復回数で解を発見

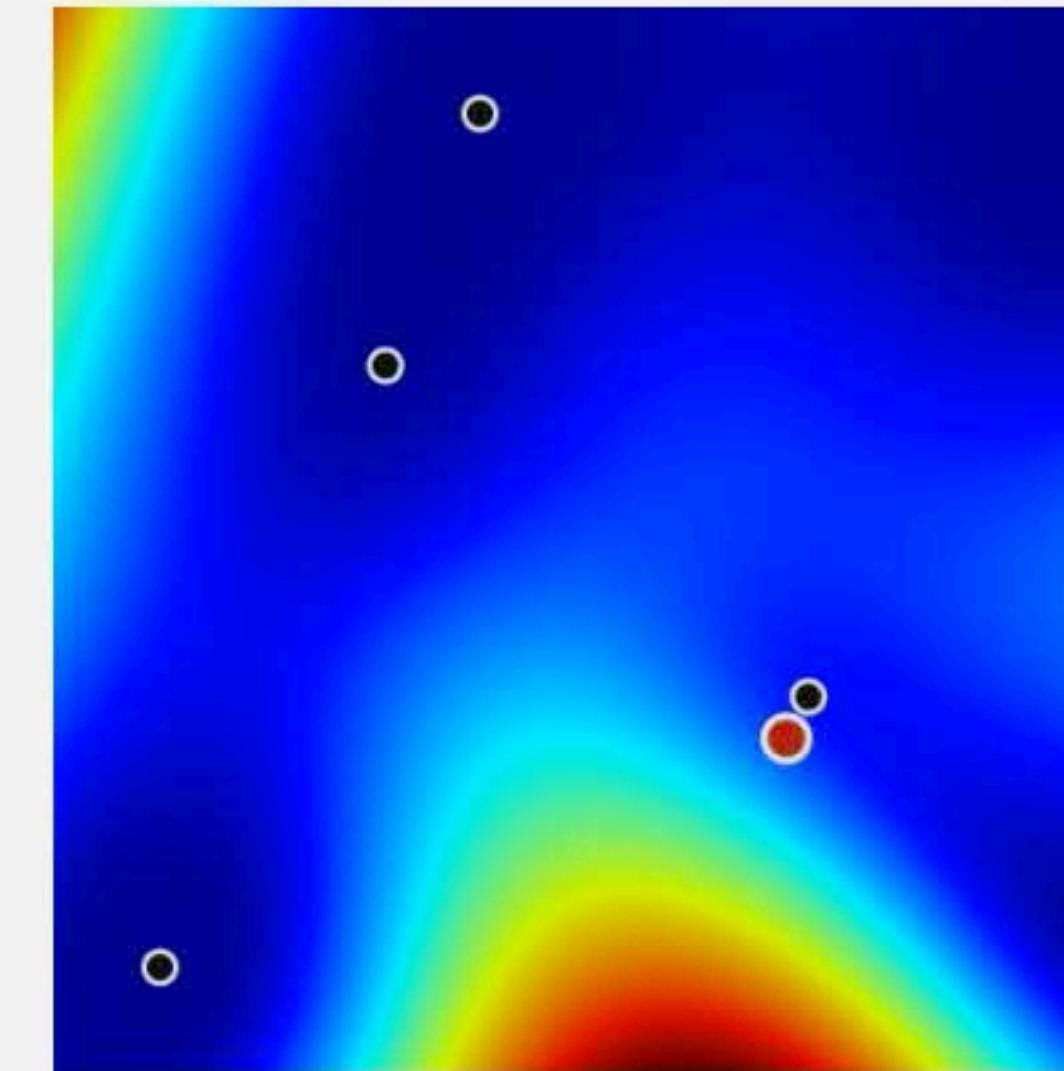
スライダ操作に基づく相対比較を扱えるよう選好ベイズ最適化を拡張 (Sequential Line Search法)



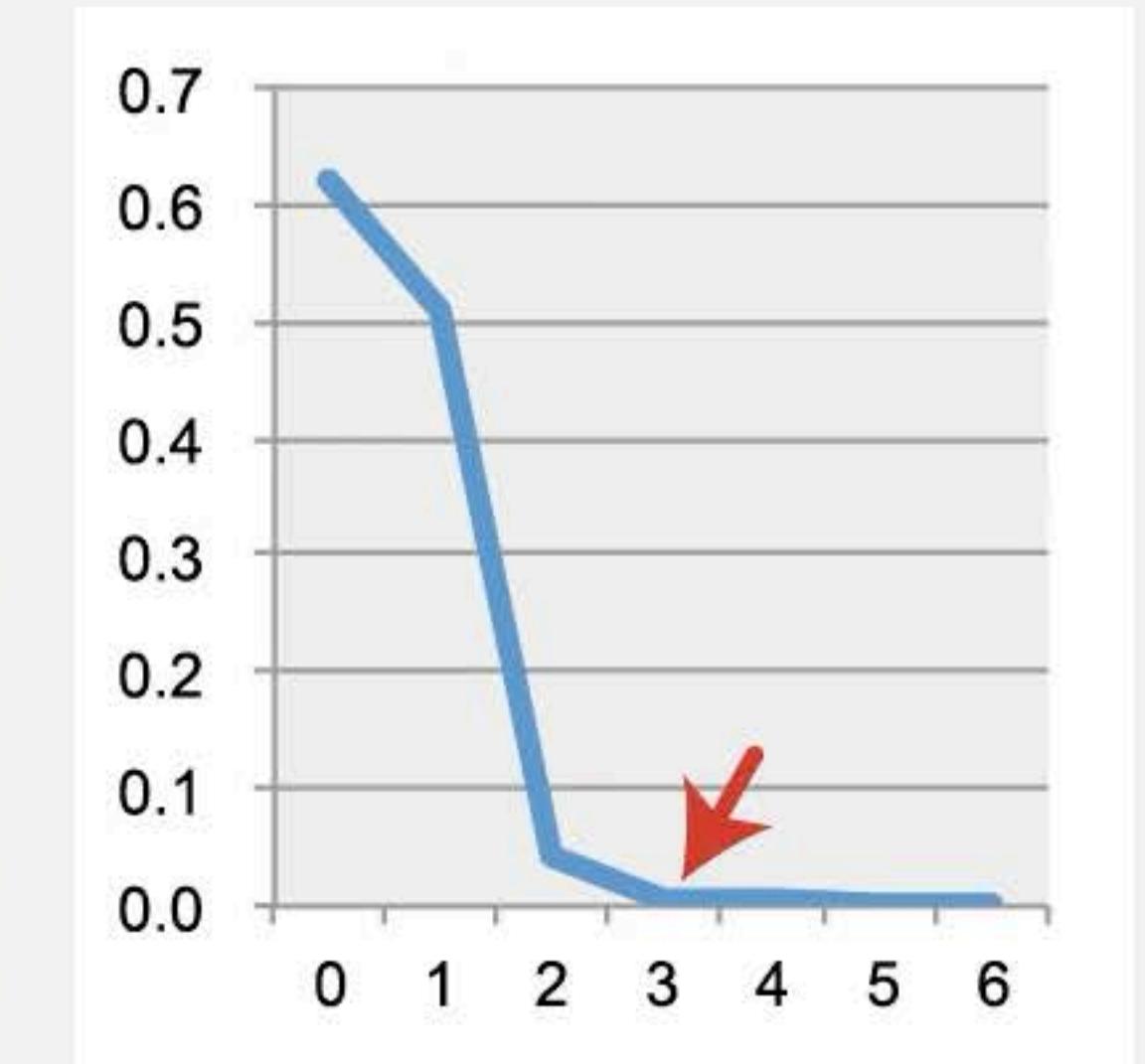
Objective
function



Estimated
function



Expected
improvement



Residuals
over iterations

詳細は [Koyama+, SIGGRAPH 2017] を参照

Applications

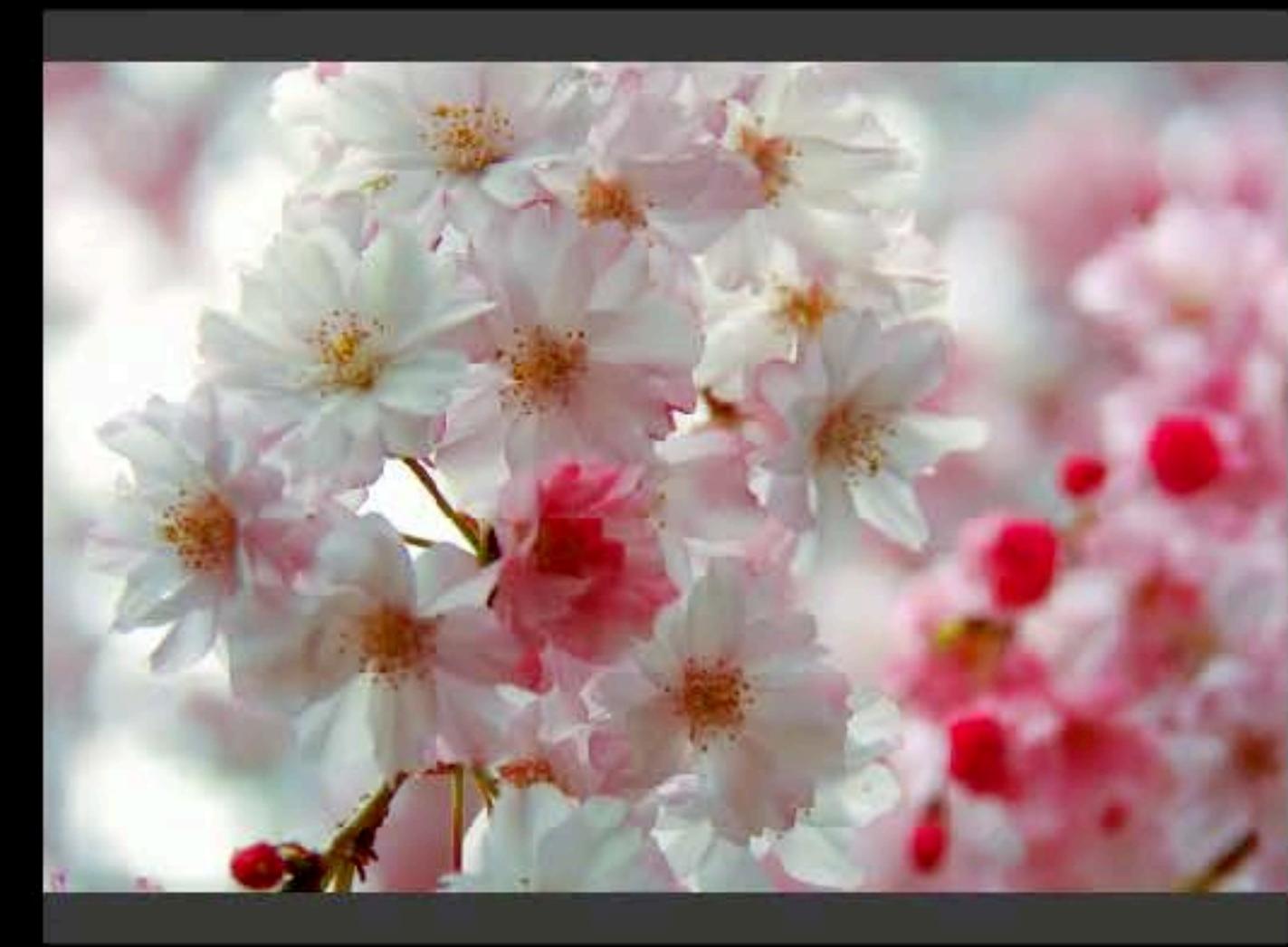
写真の色調補正 (6D)

Original Photographs



For each photo, it runs **15 iterations**, cost **5.25 USD** in total, and took **68 min** in average

Results



For each photo, it runs **15 iterations**, cost **5.25 USD** in total, and took **68 min** in average

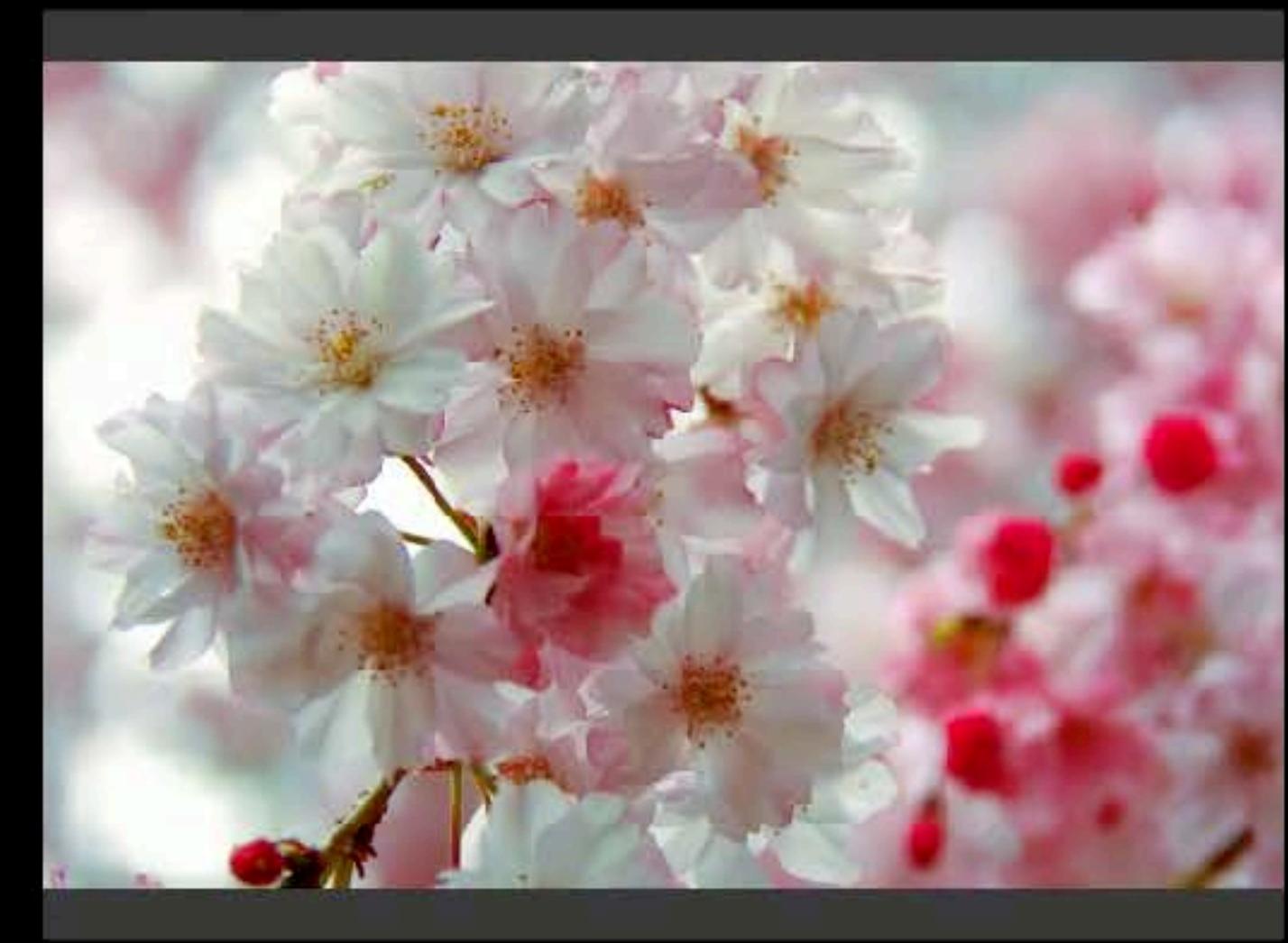
Replay

Original Photographs



For each photo, it runs **15 iterations**, cost **5.25 USD** in total, and took **68 min** in average

Results



For each photo, it runs **15 iterations**, cost **5.25 USD** in total, and took **68 min** in average

Evaluation: Crowdsource Voting

Q. Which one do you like?

Original



By Crowds



By Photoshop



By Lightroom



Baselines

Original



Crowds



Photoshop



Lightroom



Preferred by:

2

26

2

3



Preferred by:

0

32

0

1

Original



Crowds



Photoshop



Lightroom



Preferred by:

0

29

1

3



Preferred by:

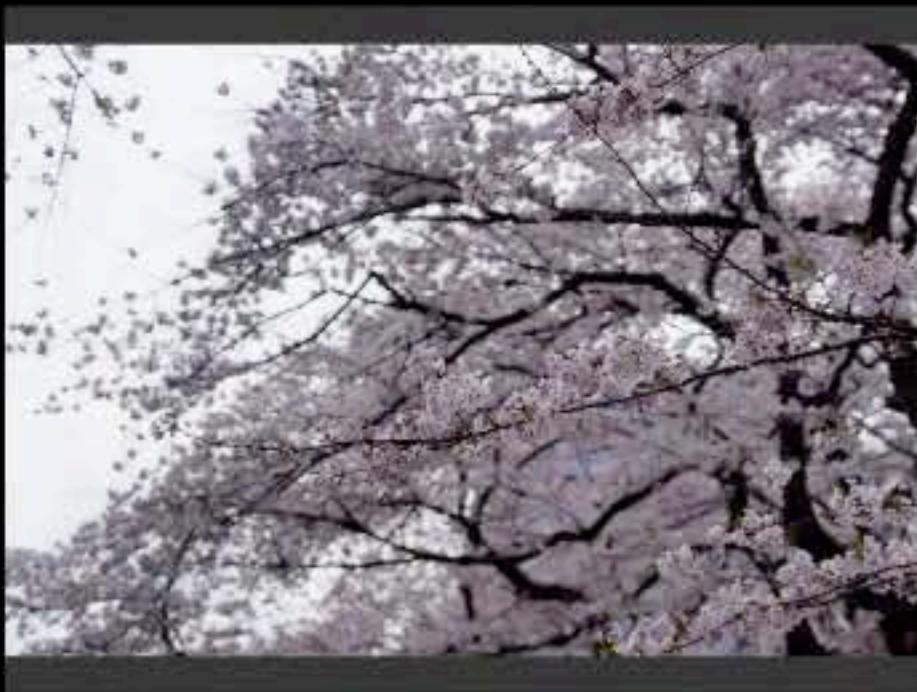
1

23

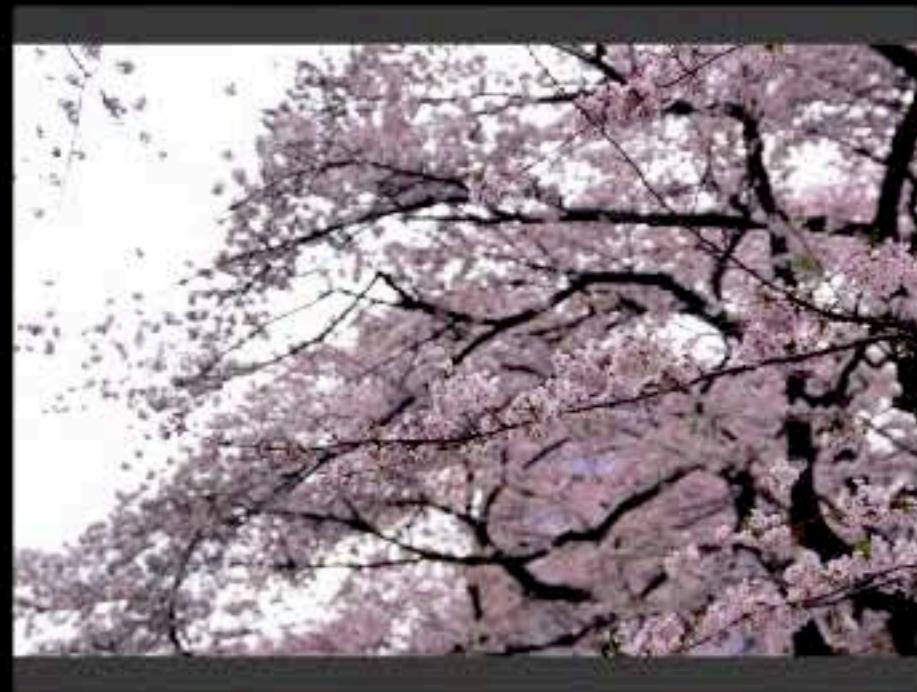
3

6

Original



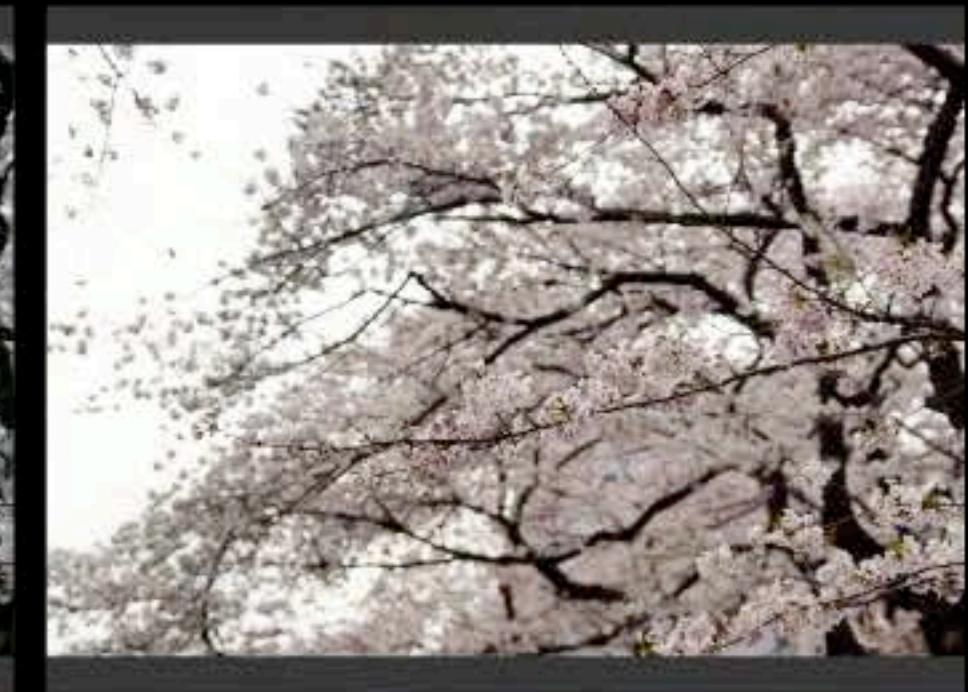
Crowds



Photoshop



Lightroom



Preferred by:

0

29

3

1

Preferred by:

0

31

0

2

Q. Which one do you like?

Original



By Crowds



By Photoshop



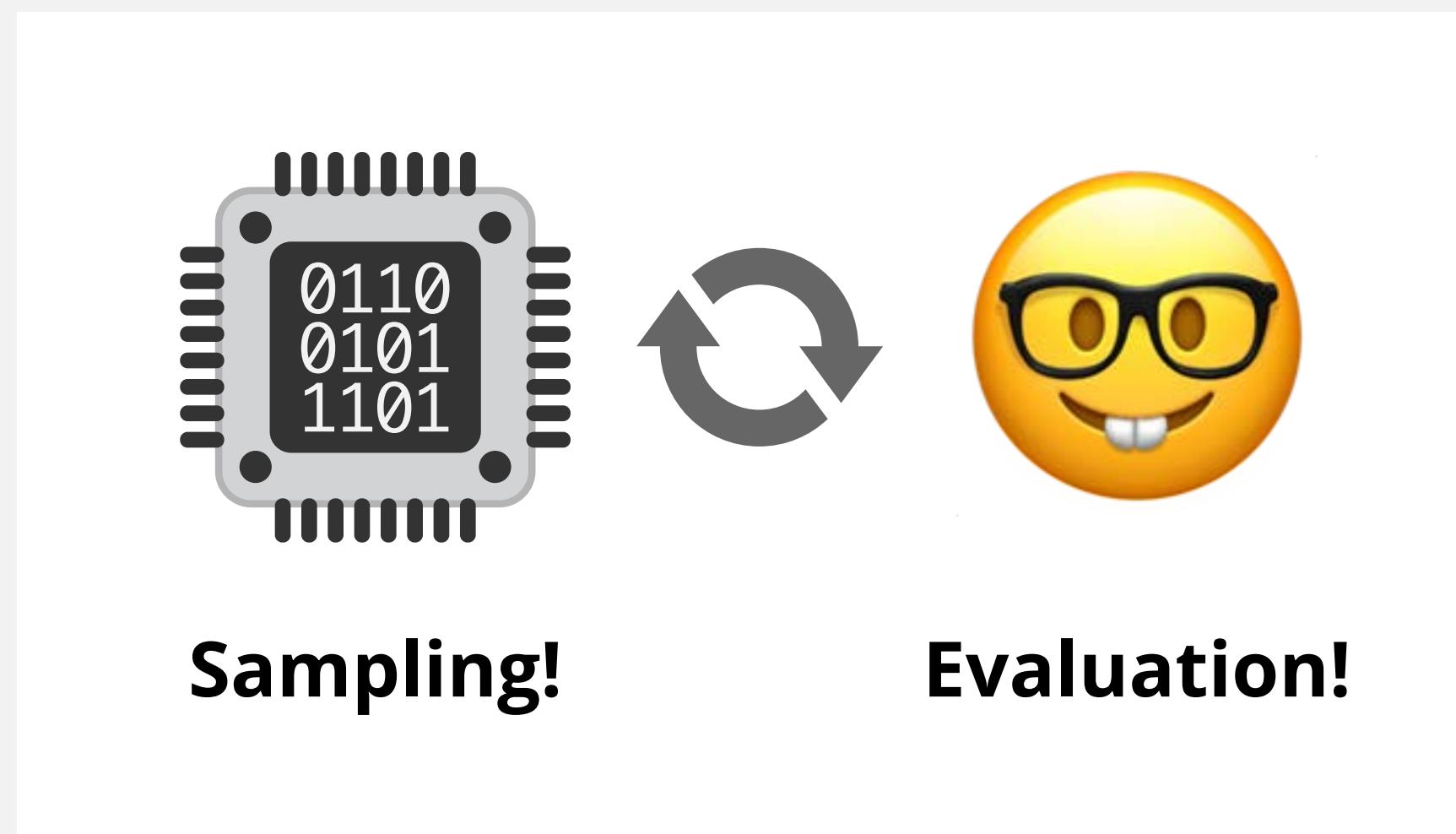
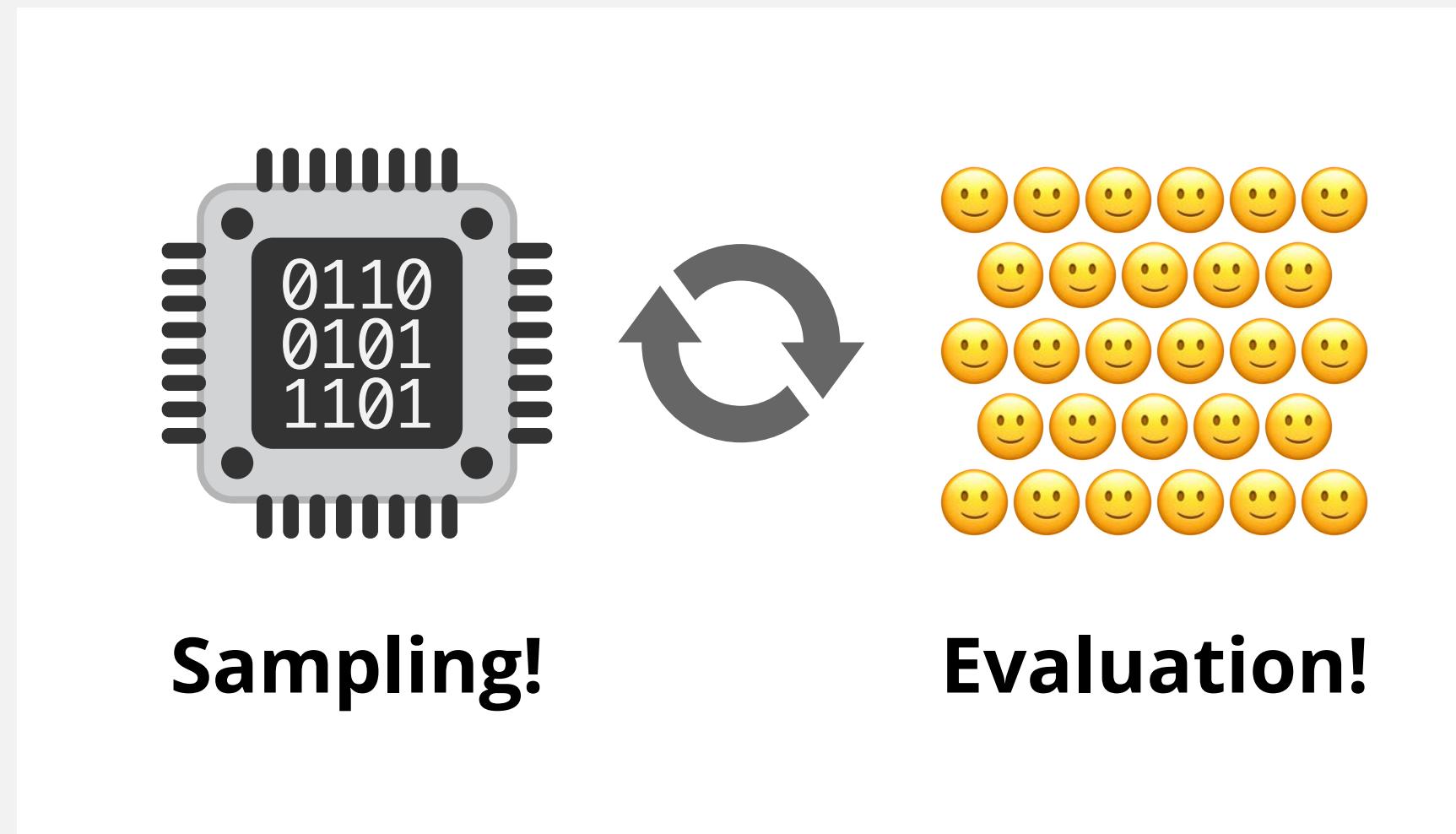
By Lightroom



→ 大衆の好みに基づいて最適化した (“people's choice”) ため、大衆に好まれる

- Crowd-in-the-Loop最適化を実現
- 一対比較ではなく一つのスライダを操作するタスクを採用することで必要な反復回数を削減
- そのために選好ベイズ最適化 (PBO) を拡張
 - Sequential Line Search法

評価者



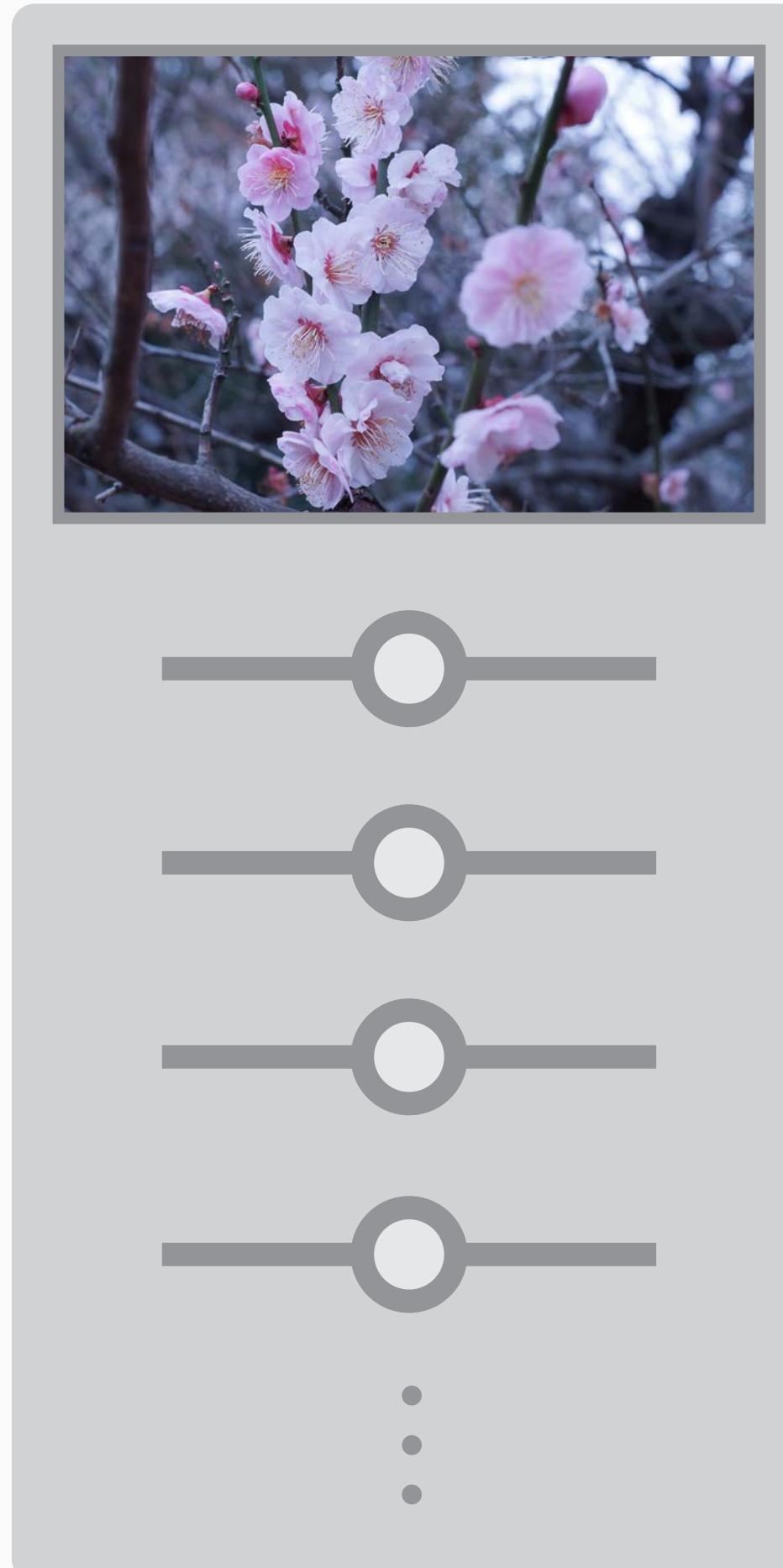
- **Crowd-in-the-Loop最適化**
- 特徴：
 - 大衆の好み
 - クラウドソーシングで自動実行が可能

- **User-in-the-Loop最適化**
- 特徴：
 - 個人の好み
 - 対話的な実行

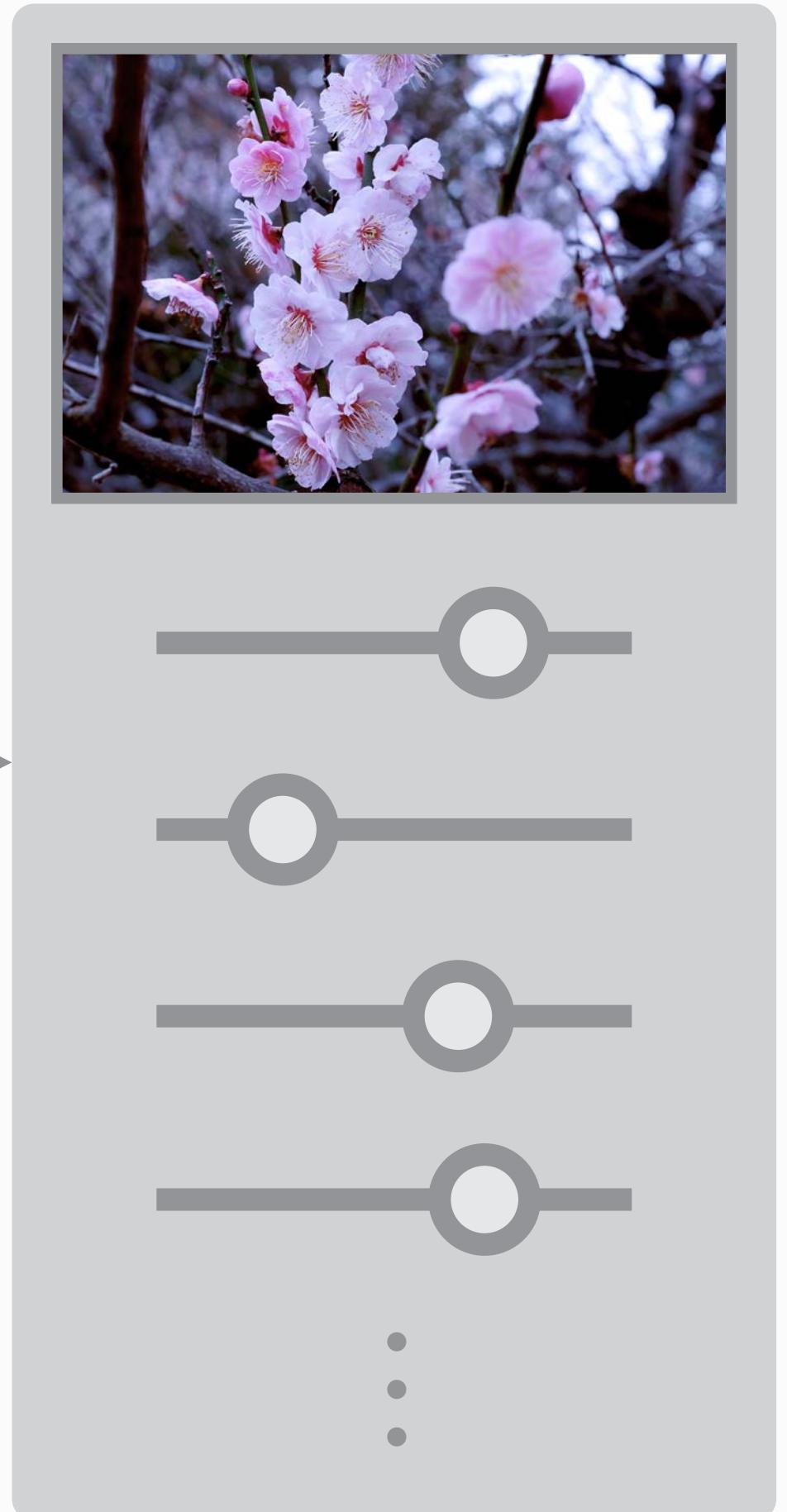
研究事例 2

Sequential Gallery [SIGGRAPH 2020]

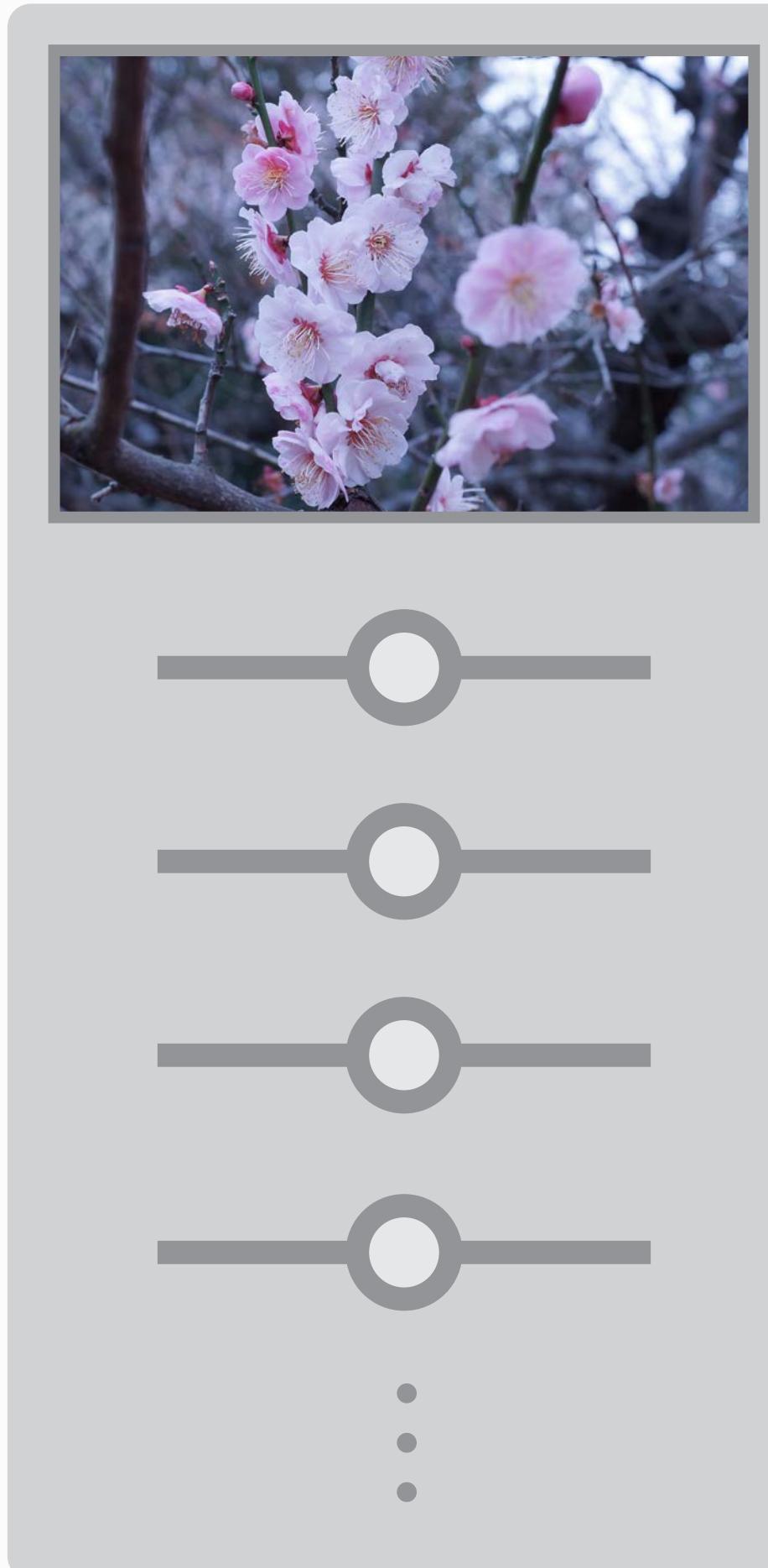
Target:
 n design parameters
(e.g., photo enhance)



Output:
An optimal
parameter set

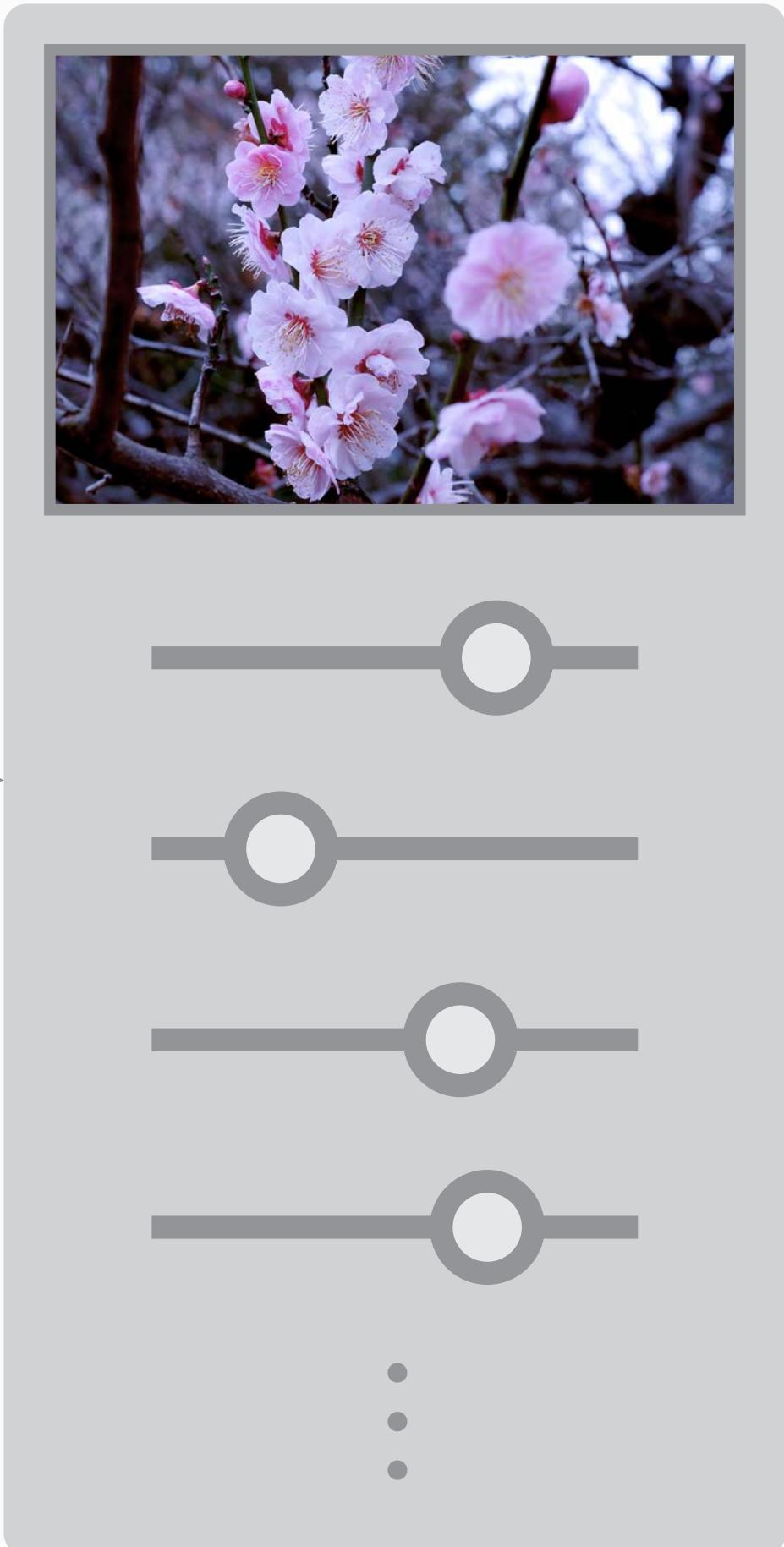


Target:
 n design parameters
(e.g., photo enhance)

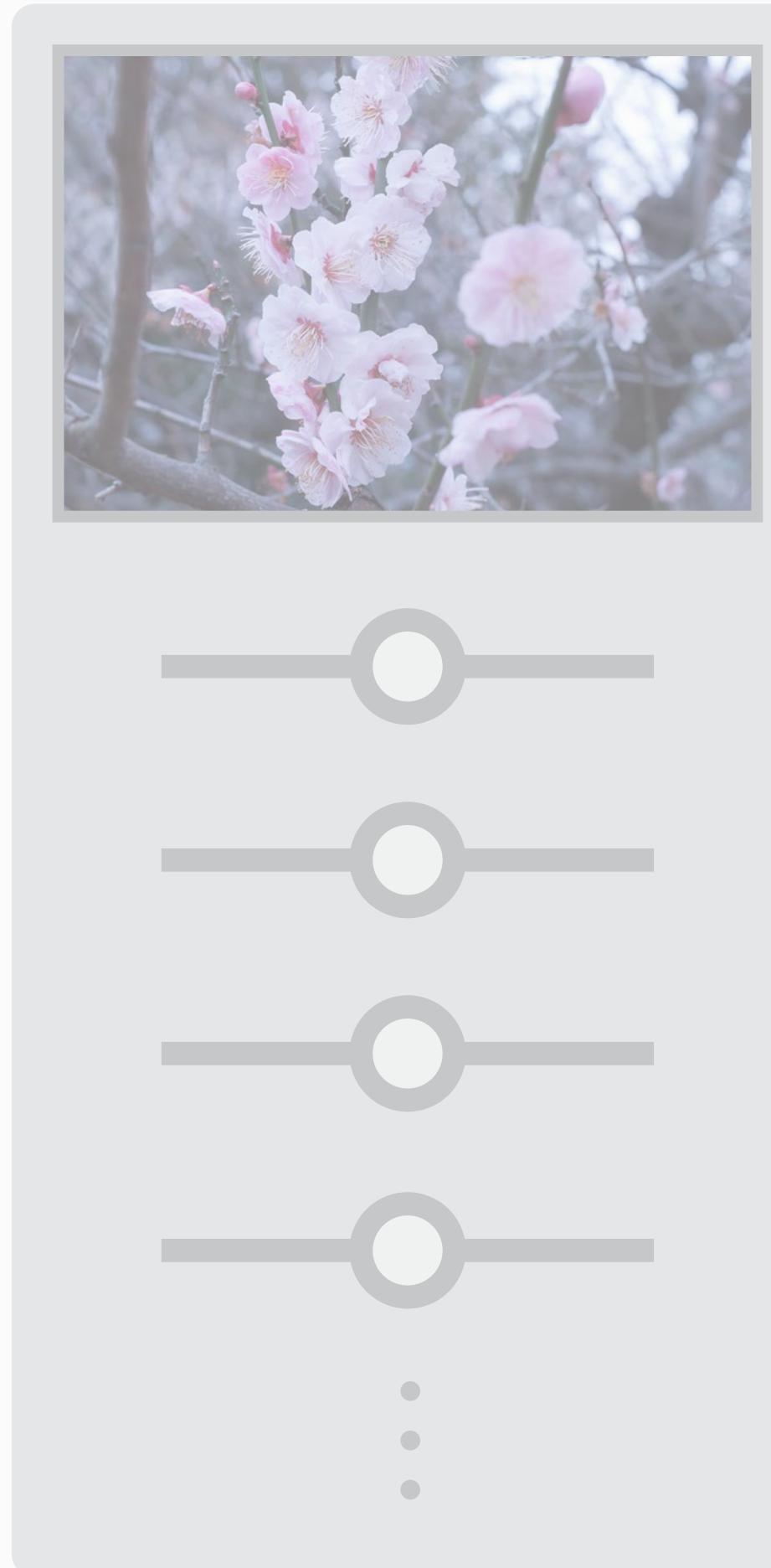


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

Output:
An optimal
parameter set



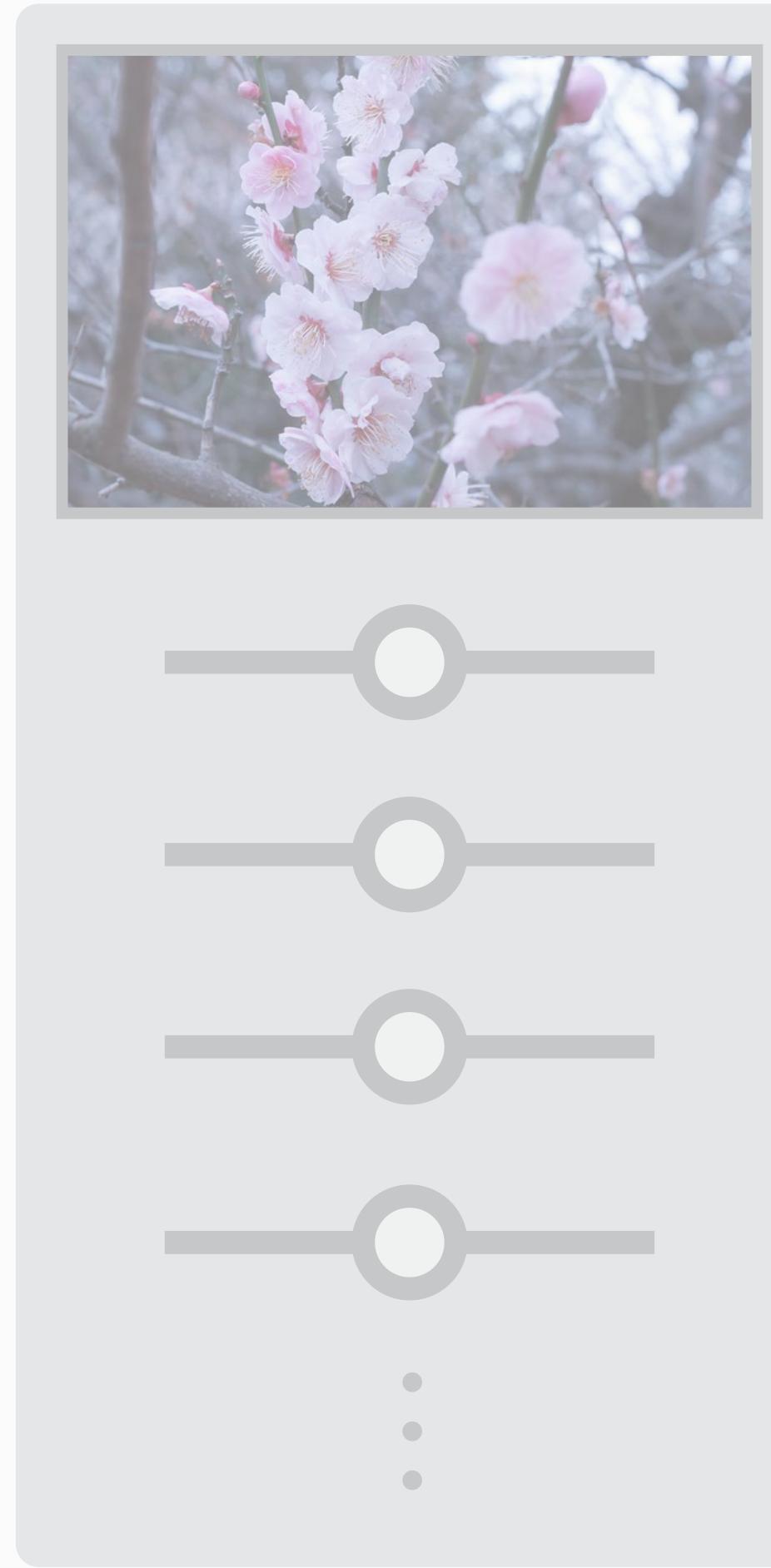
Target:
 n design parameters
(e.g., photo enhance)



Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

Output:
An optimal
parameter set

Target:
 n design parameters
(e.g., photo enhance)

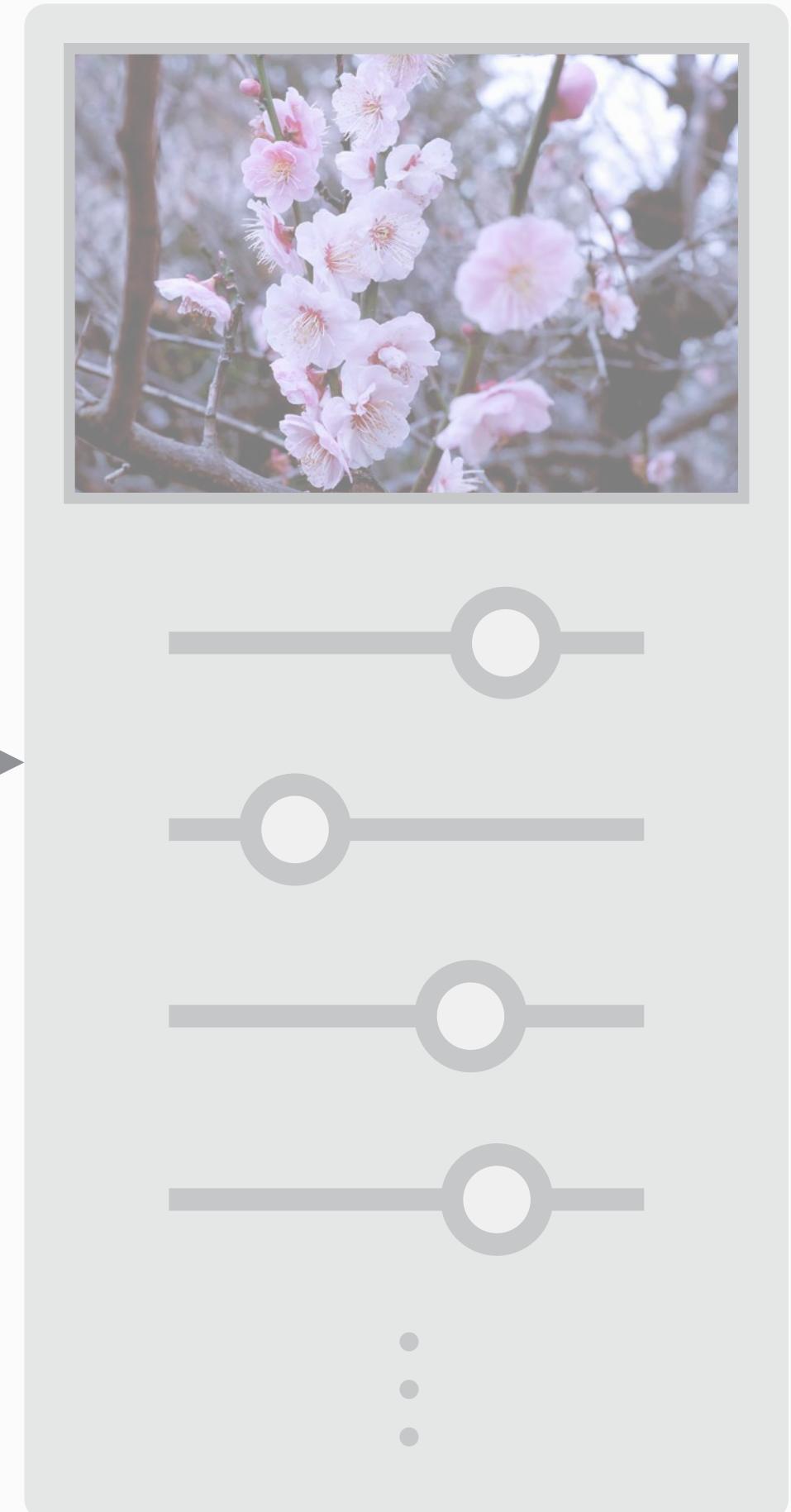


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

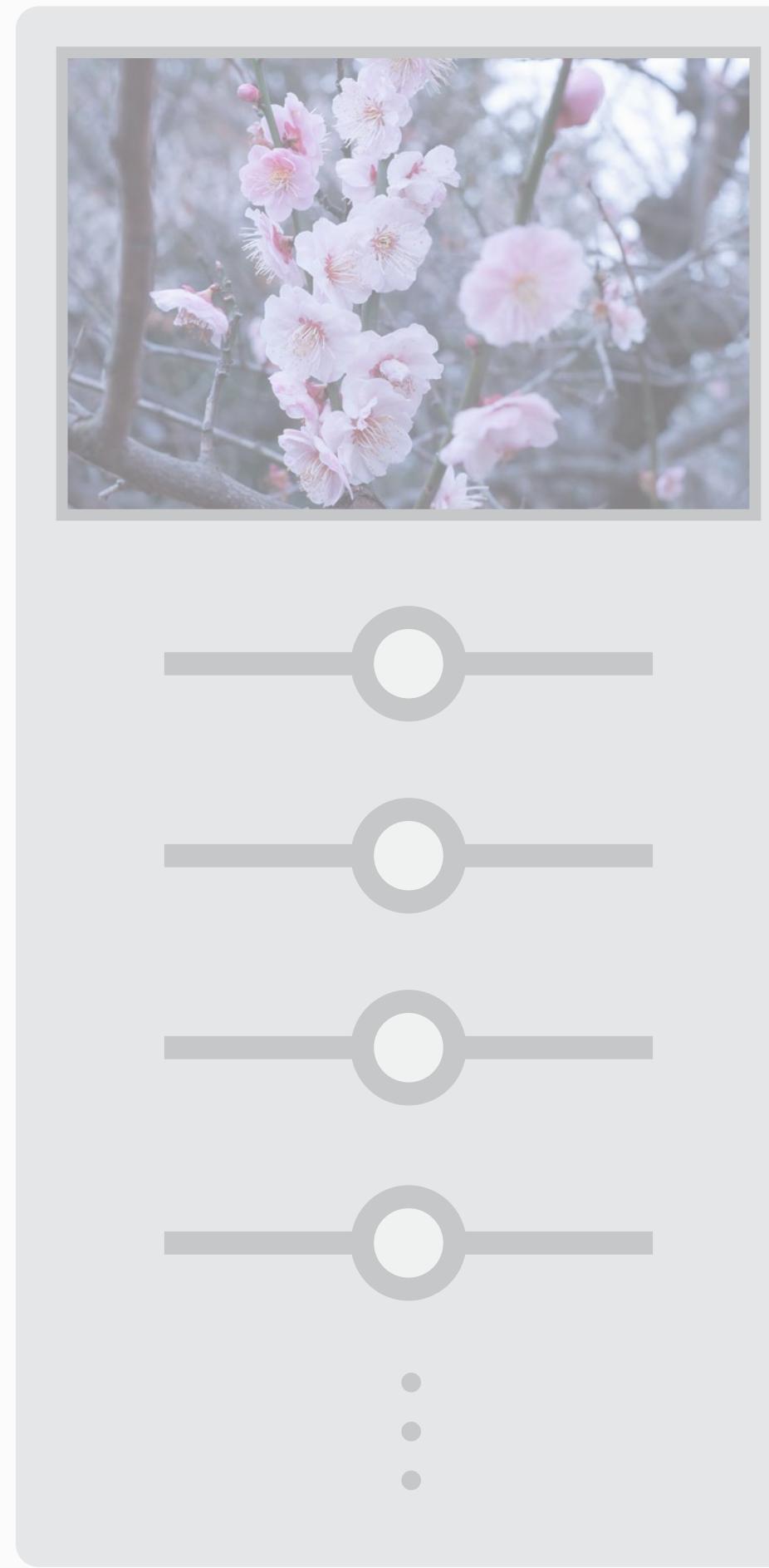


2D search subtask #1

Output:
An optimal
parameter set



Target:
 n design parameters
(e.g., photo enhance)

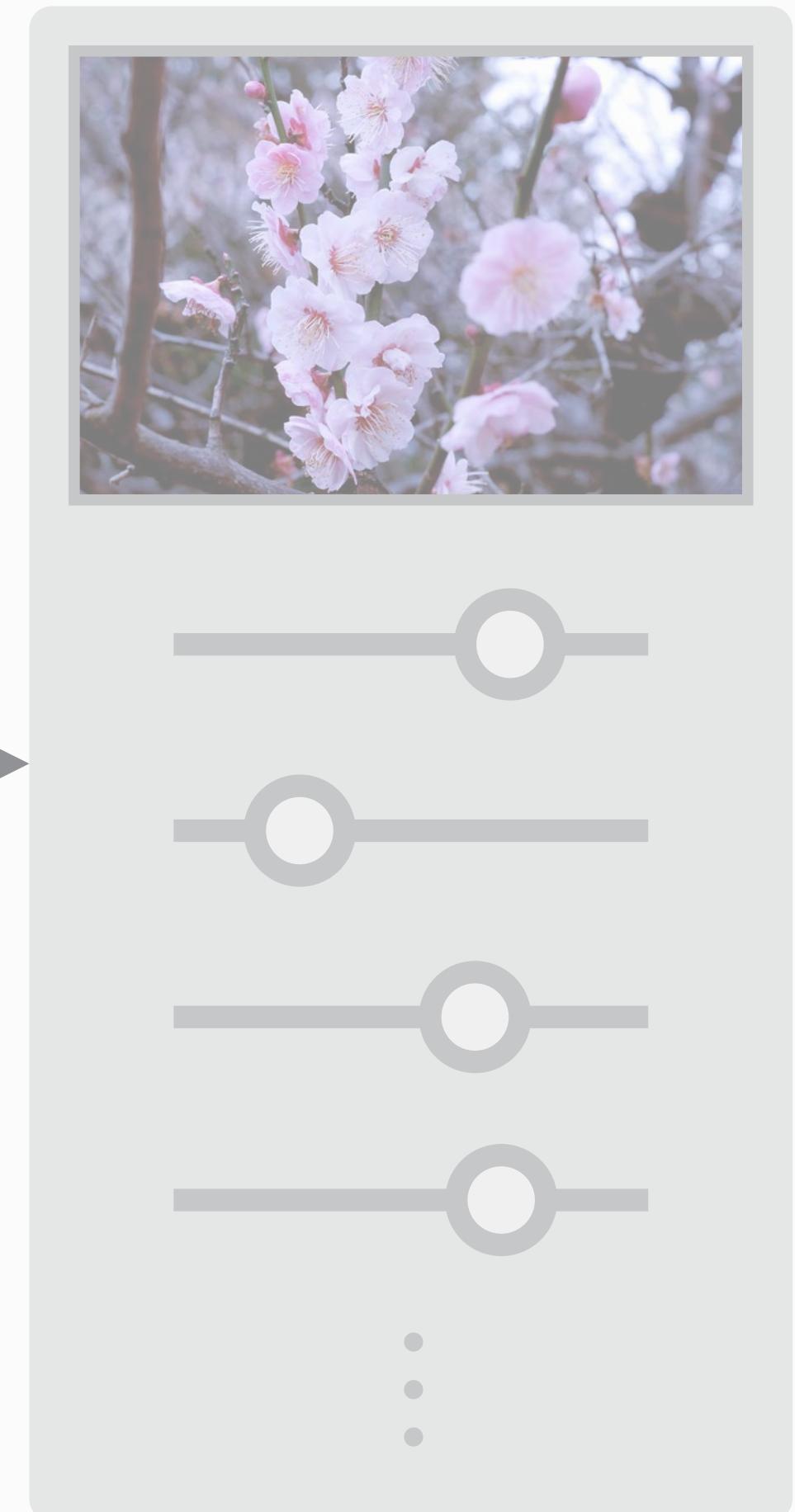


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

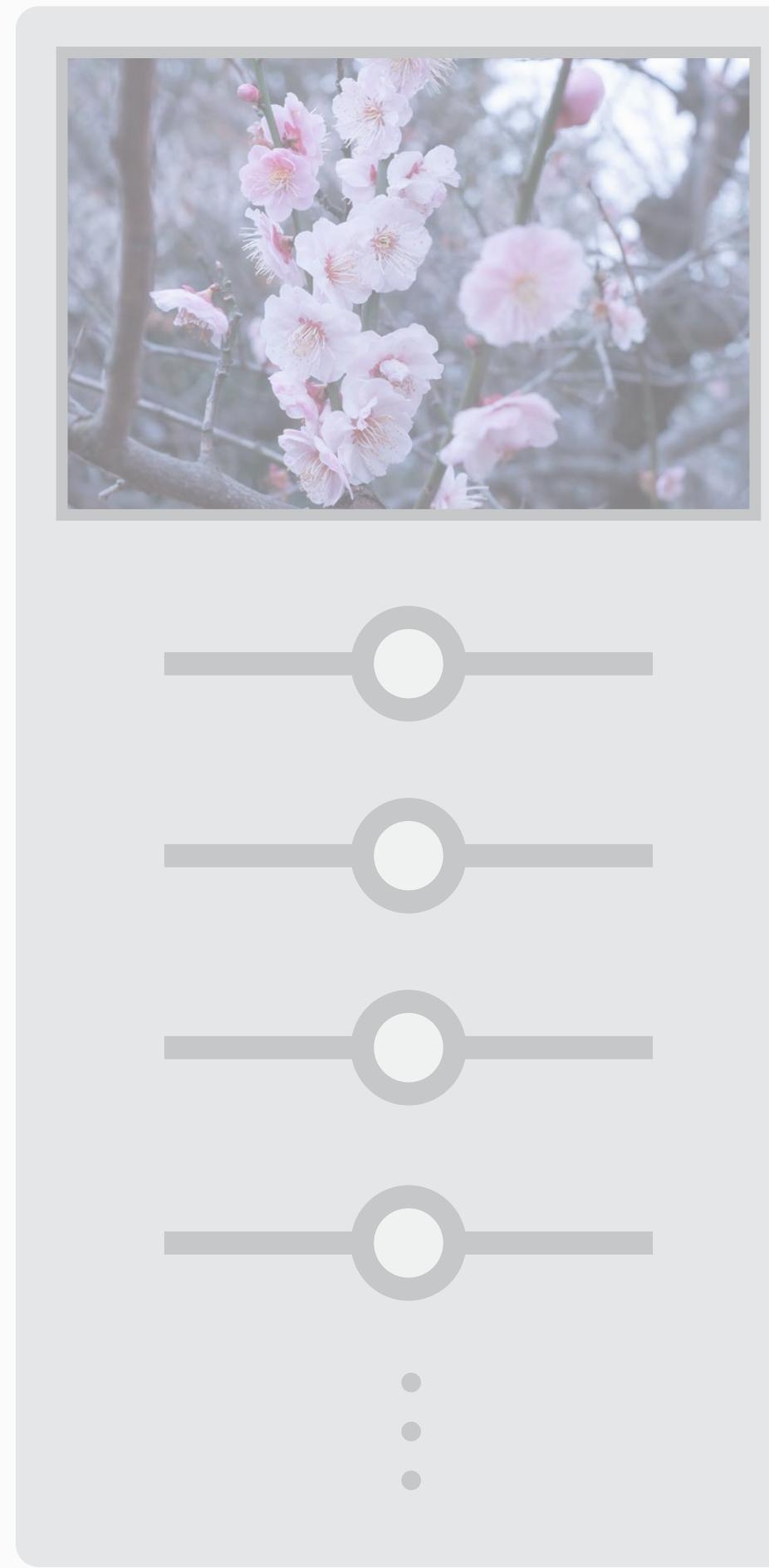


2D search subtask #1

Output:
An optimal
parameter set



Target:
 n design parameters
(e.g., photo enhance)

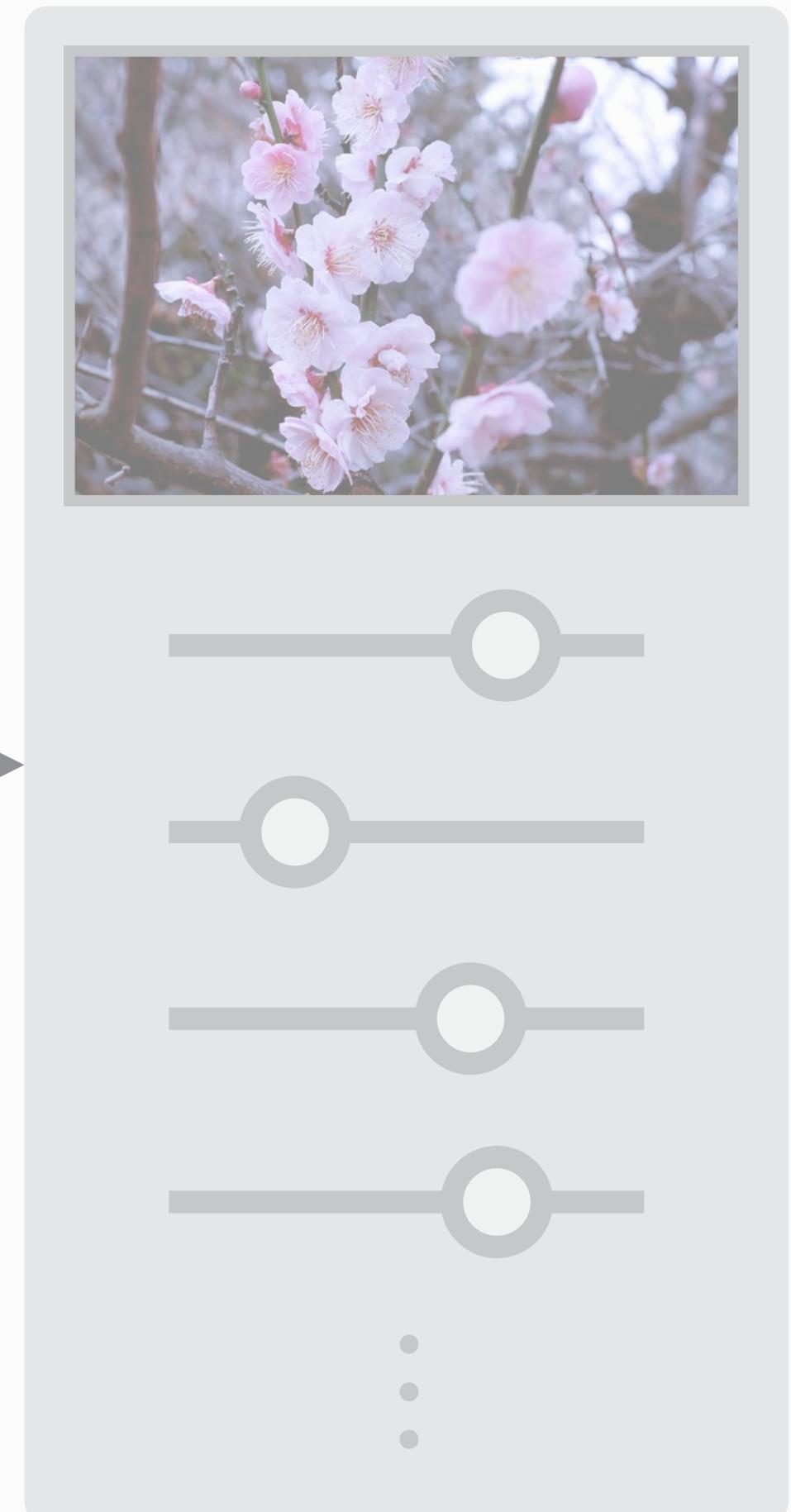


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

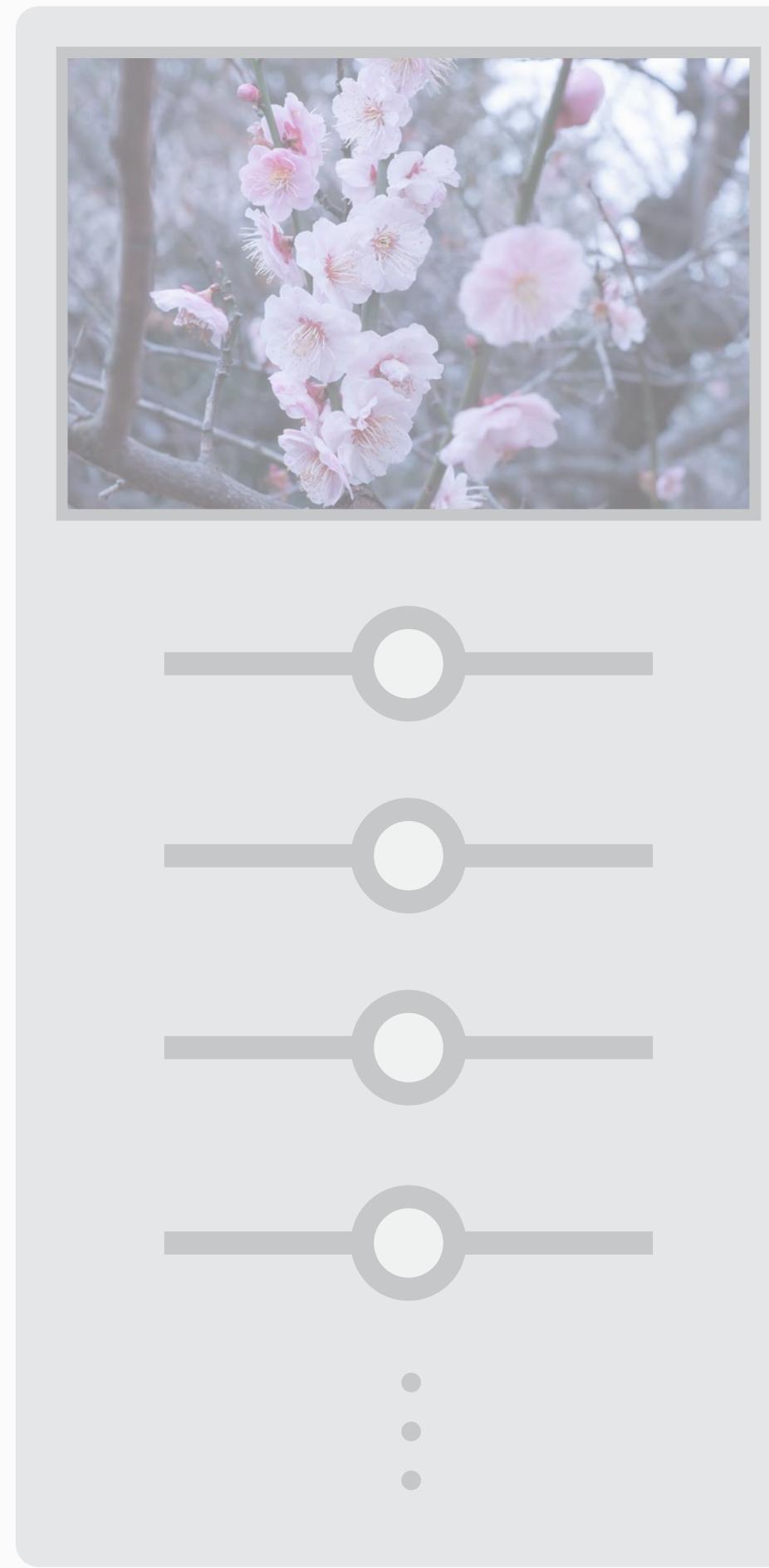


2D search subtask #2

Output:
An optimal
parameter set



Target:
 n design parameters
(e.g., photo enhance)

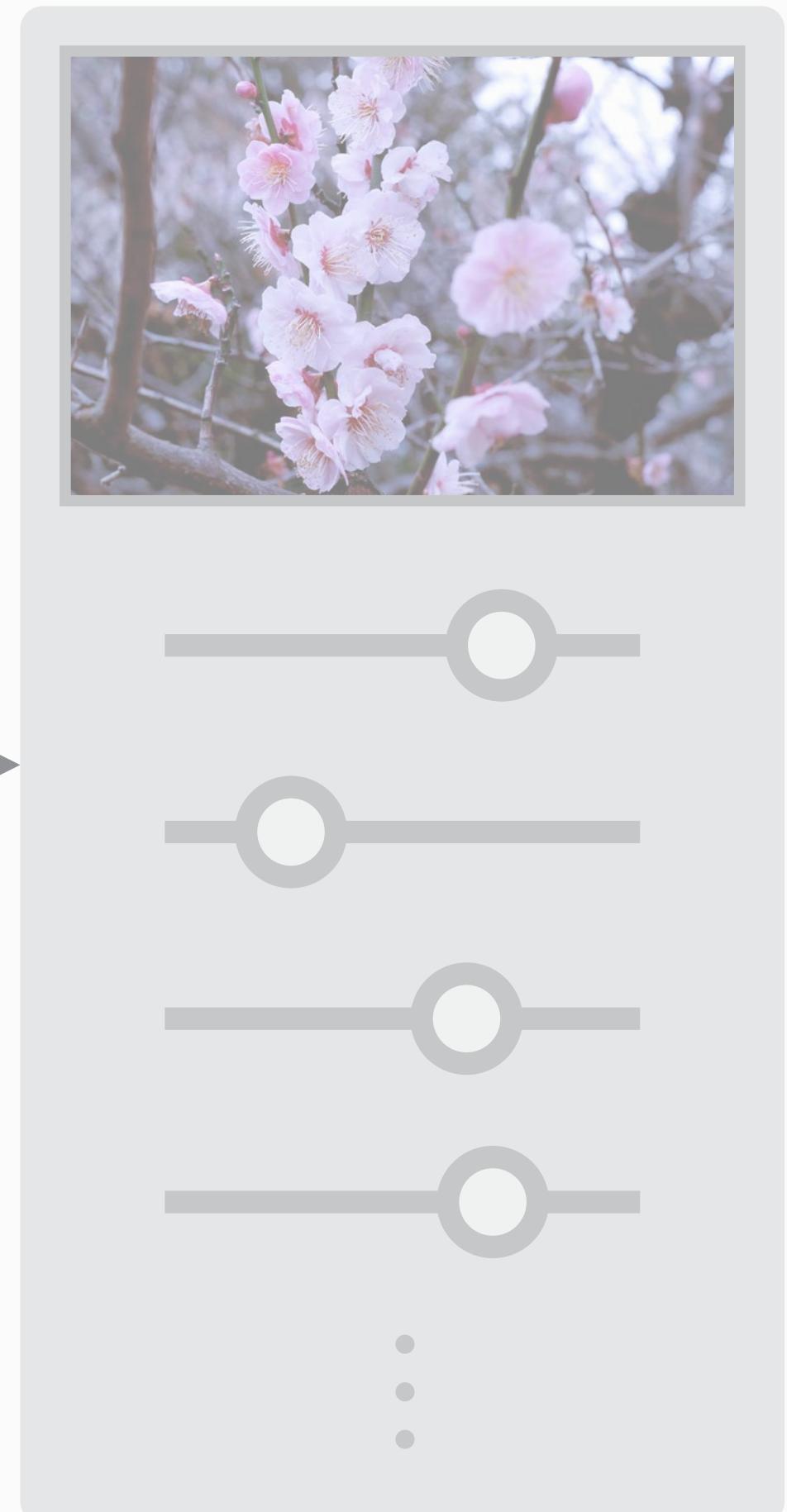


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

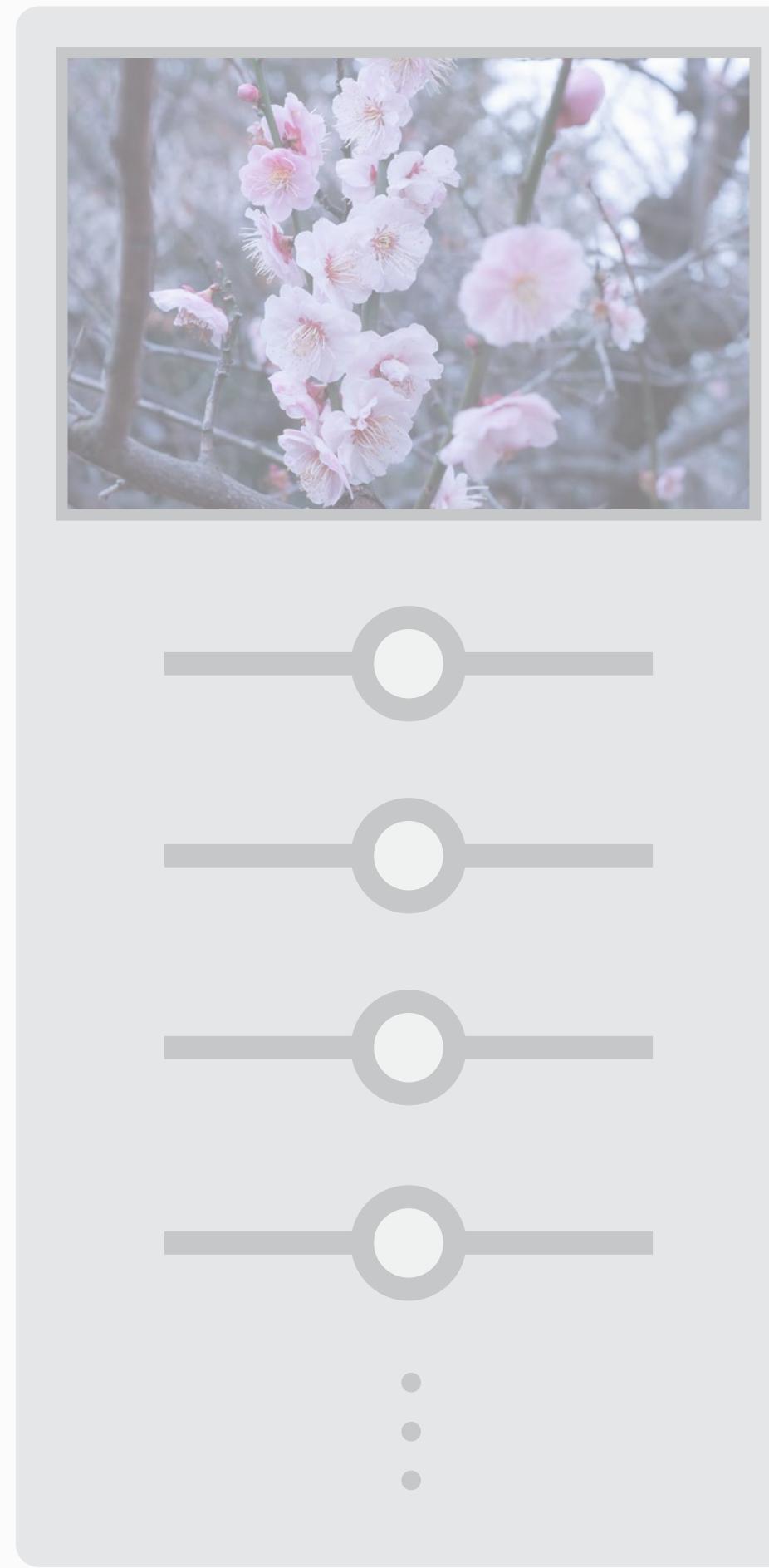


2D search subtask #3

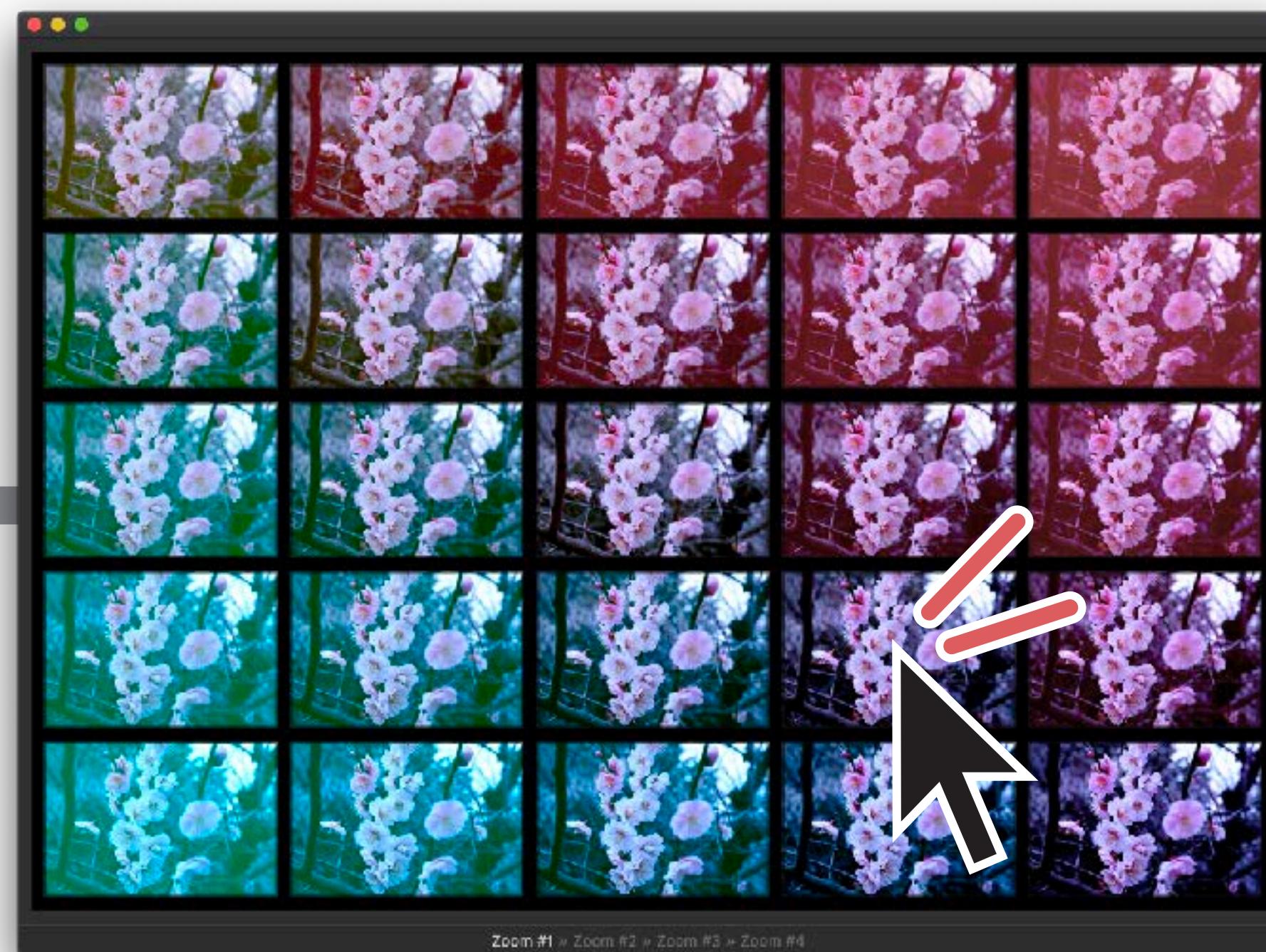
Output:
An optimal
parameter set



Target:
 n design parameters
(e.g., photo enhance)

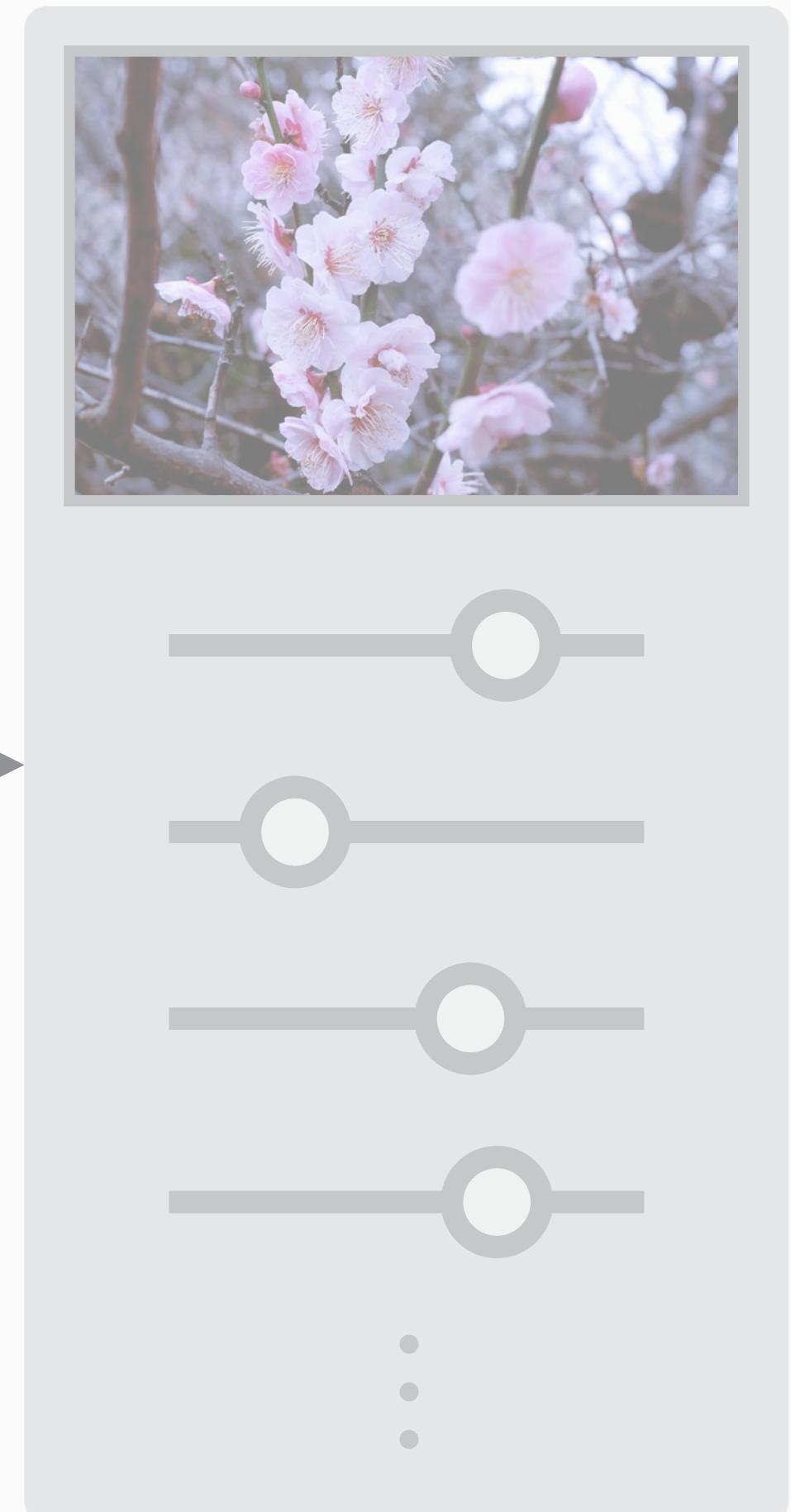


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

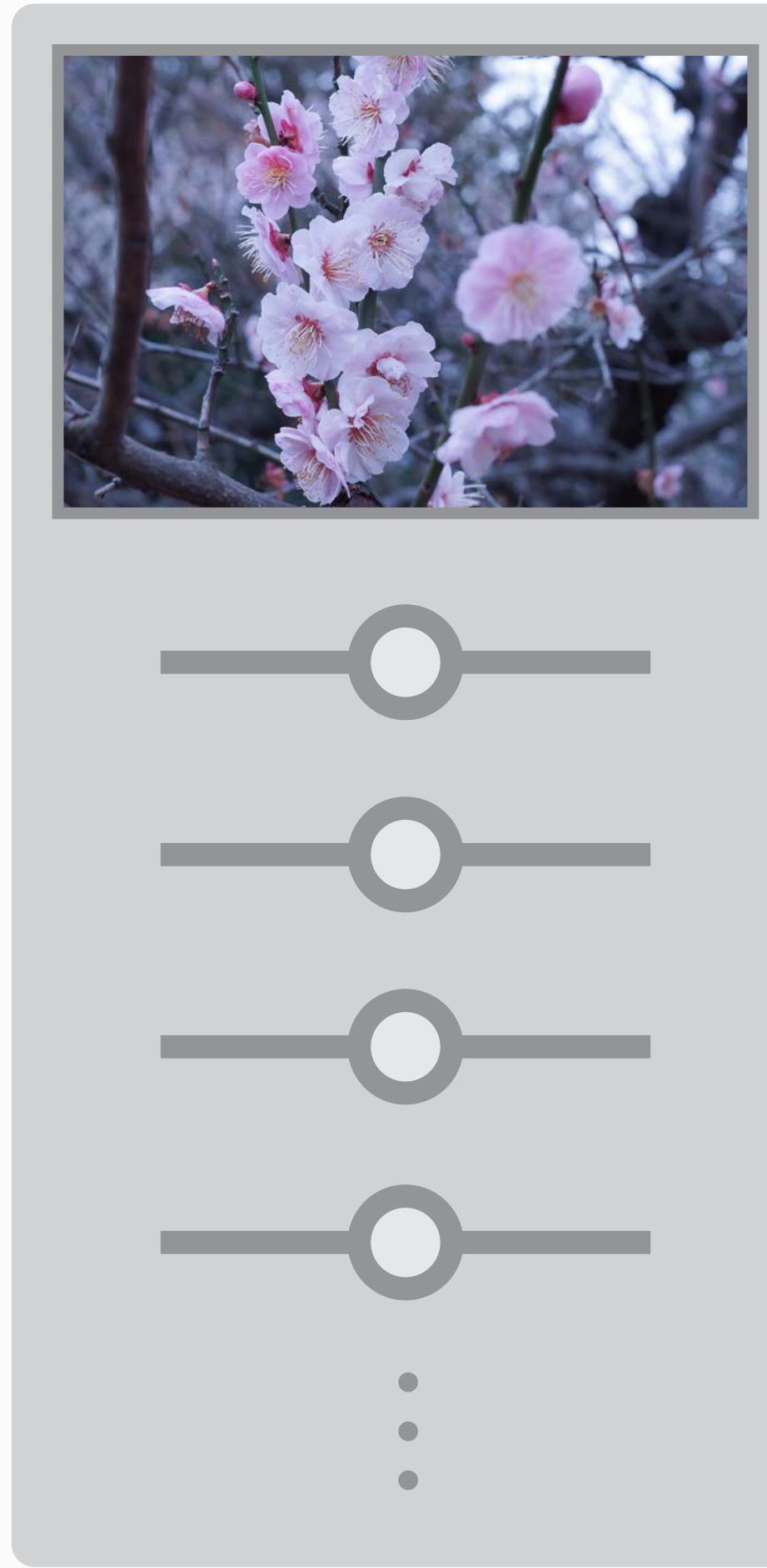


2D search subtask #4

Output:
An optimal
parameter set



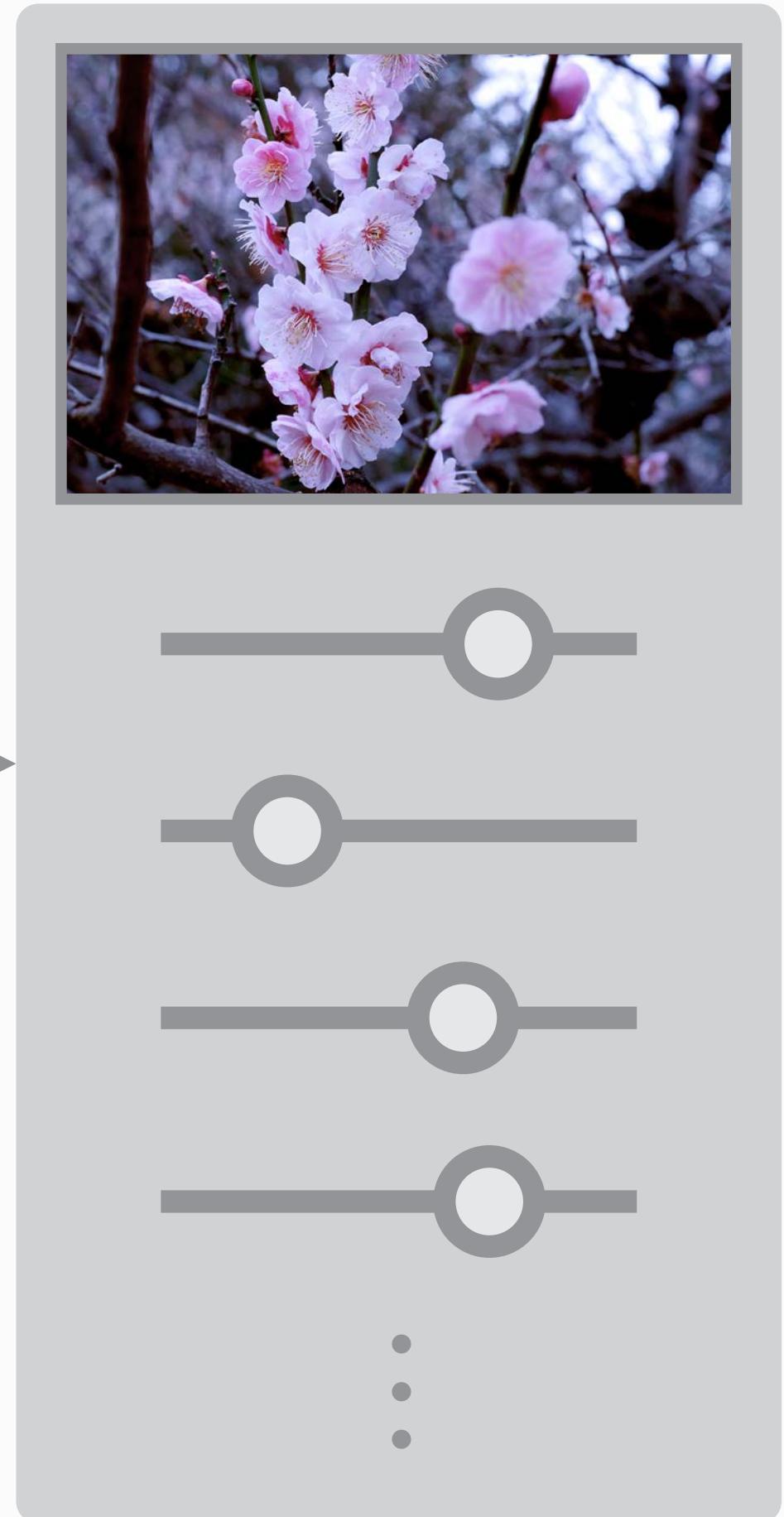
Target:
 n design parameters
(e.g., photo enhance)

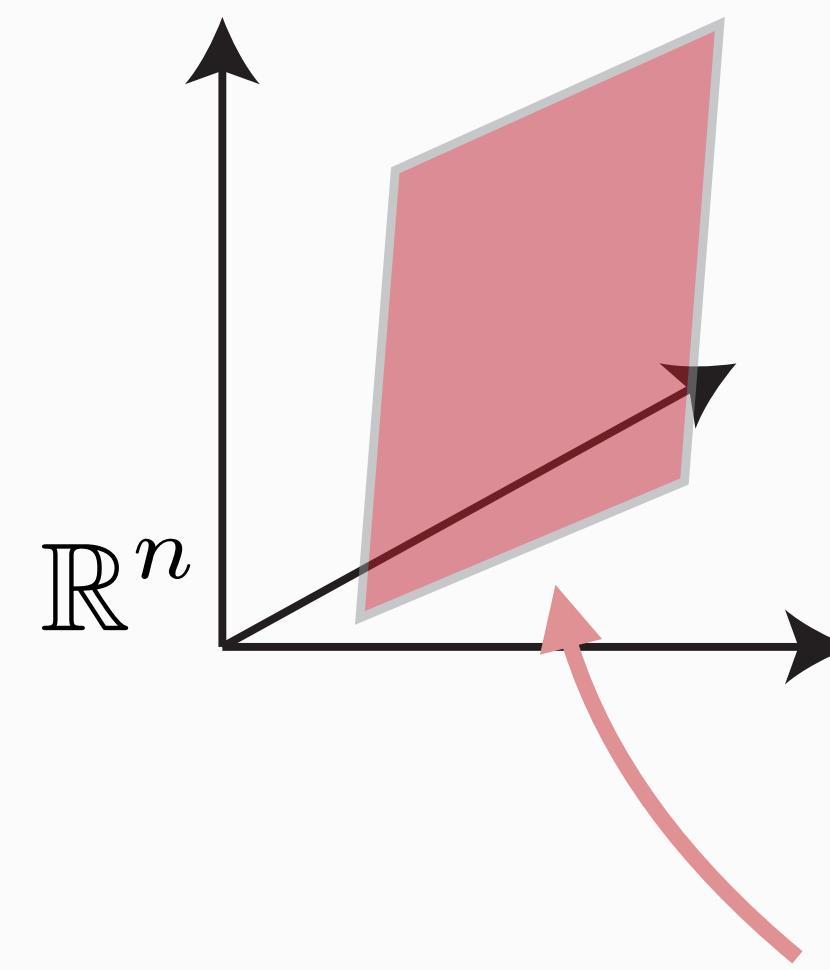


Sequential Gallery:
An interactive optimization framework
where the user sequentially performs
2D search subtasks via a grid interface

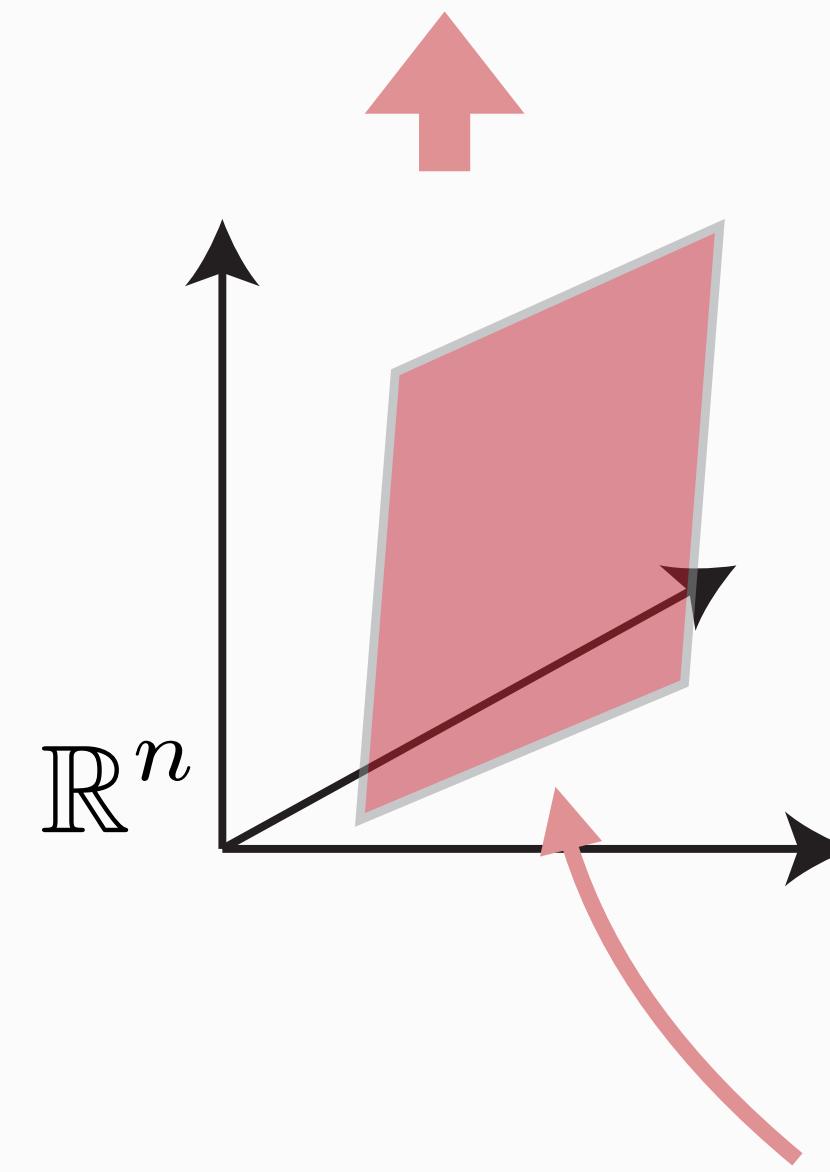


Output:
An optimal
parameter set





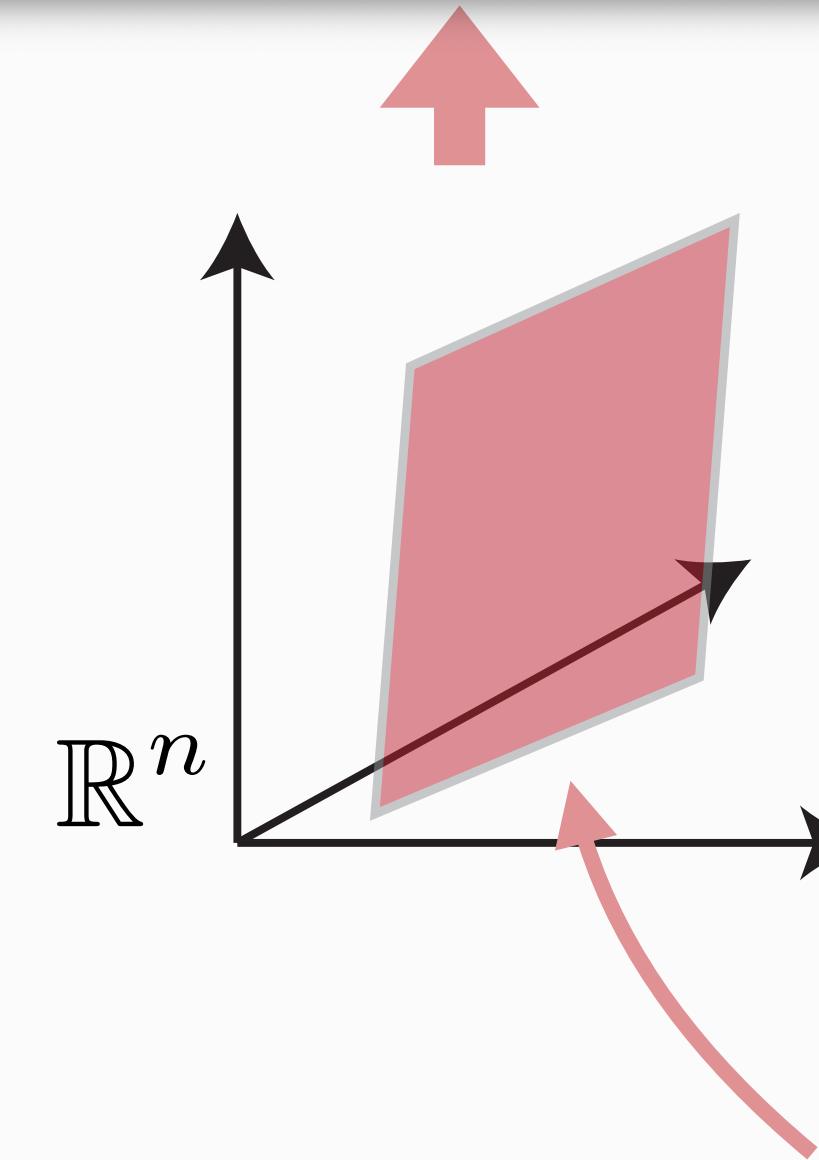
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)



2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

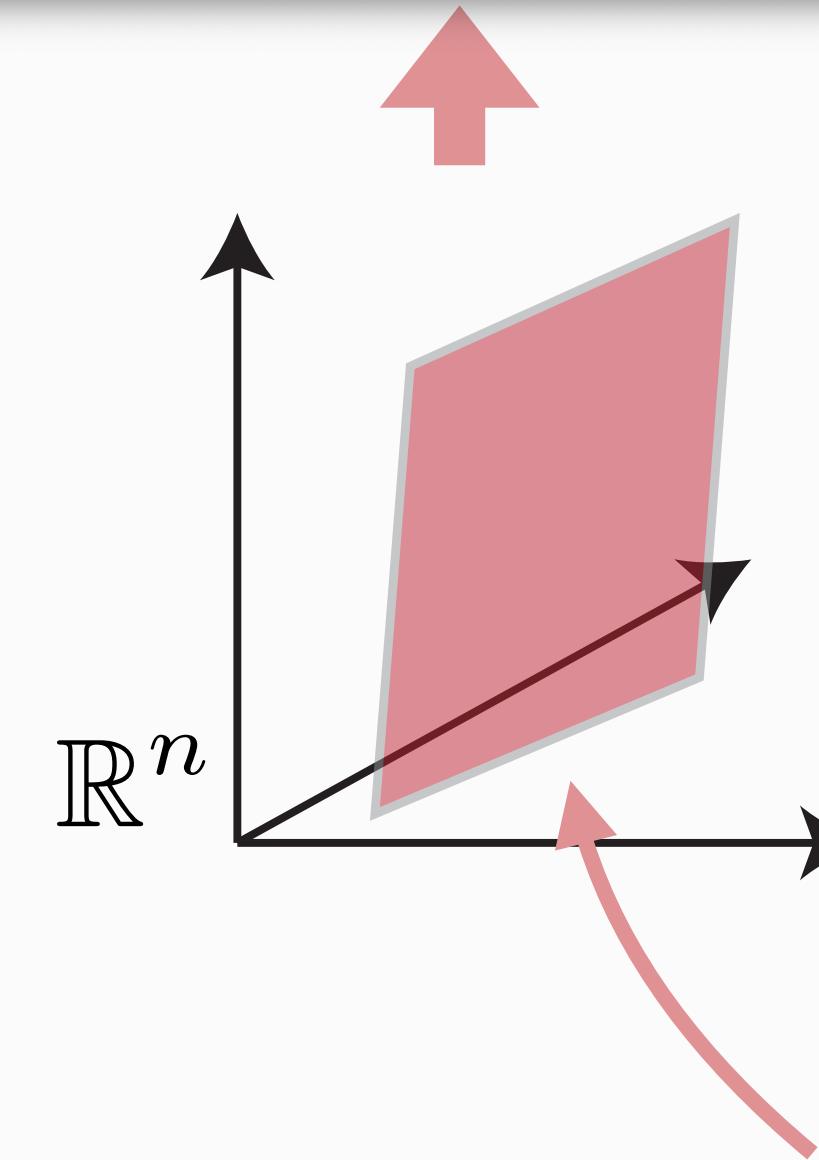
2D search subtask



2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

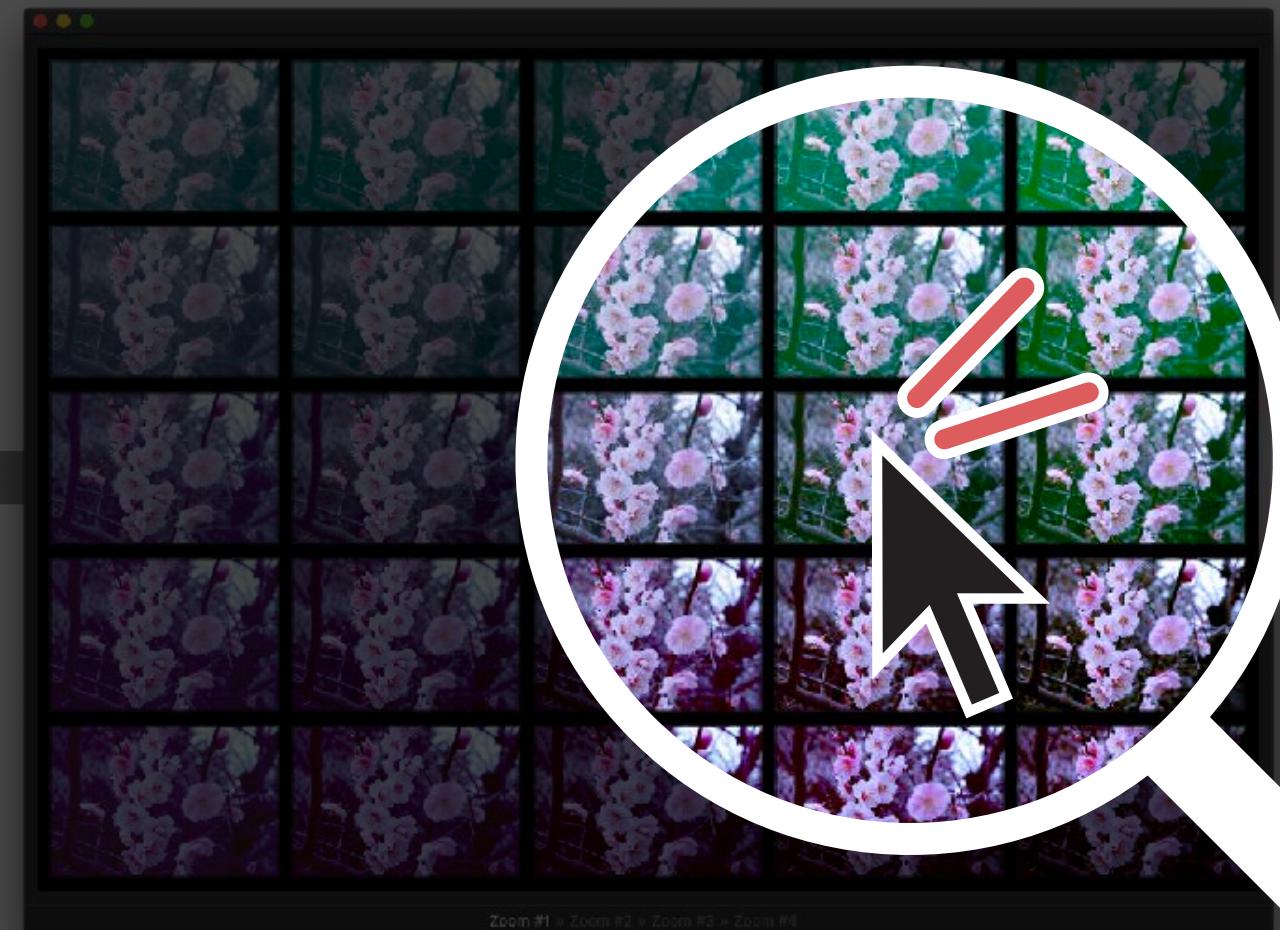
2D search subtask



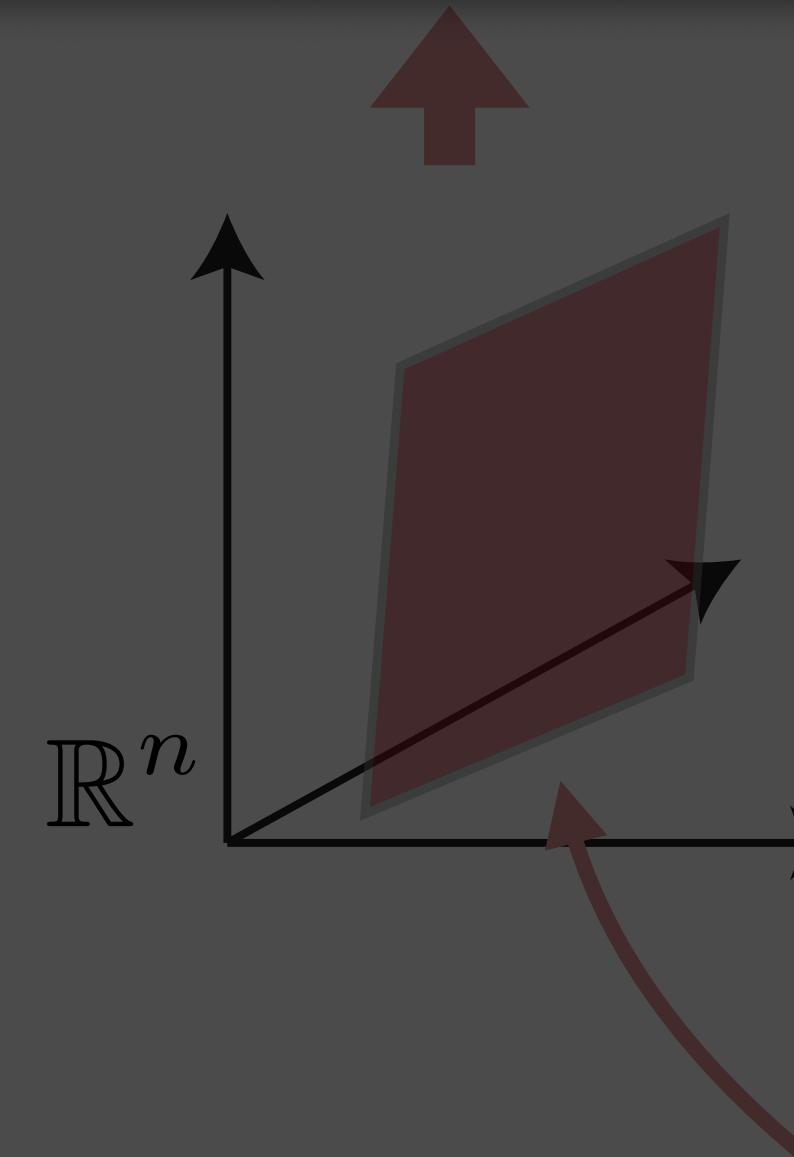
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

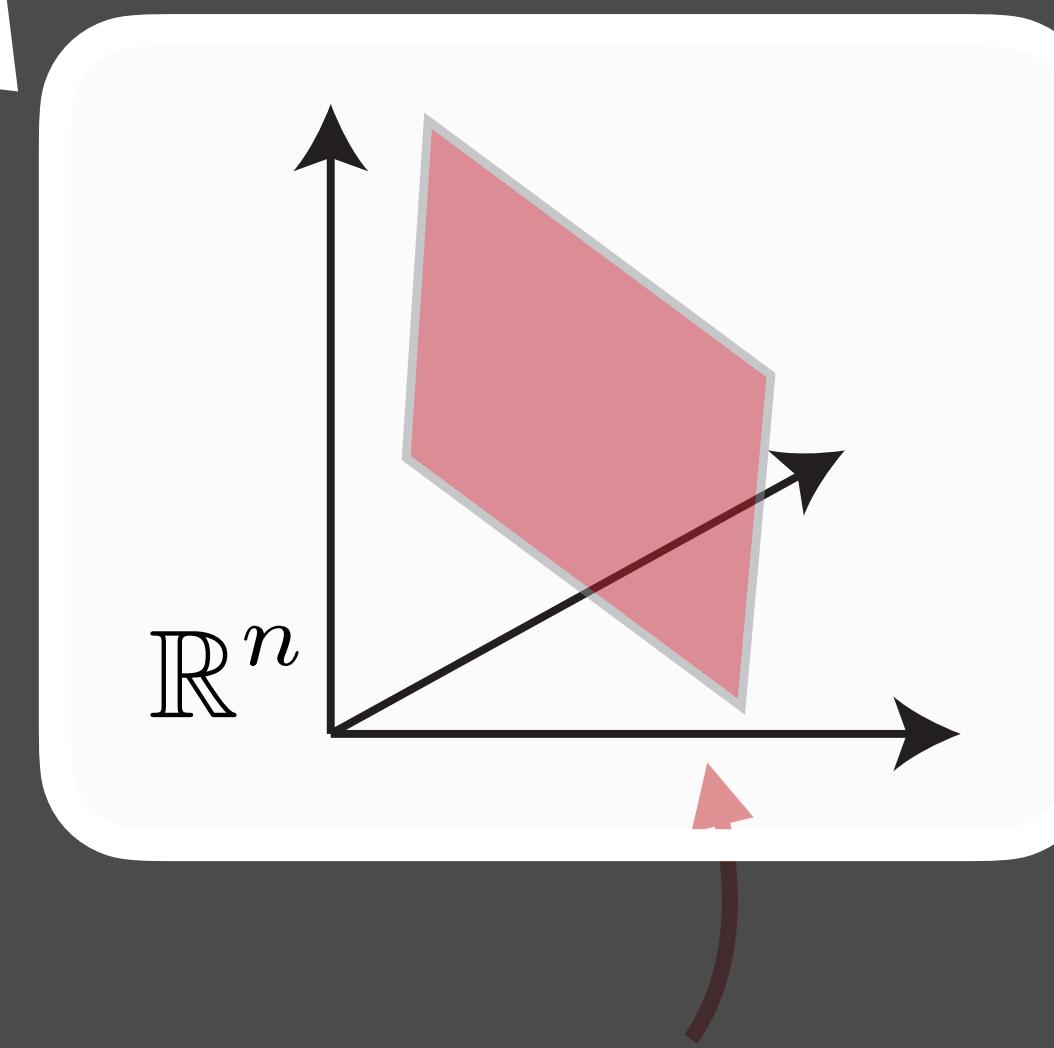
2D search subtask



User's feedback



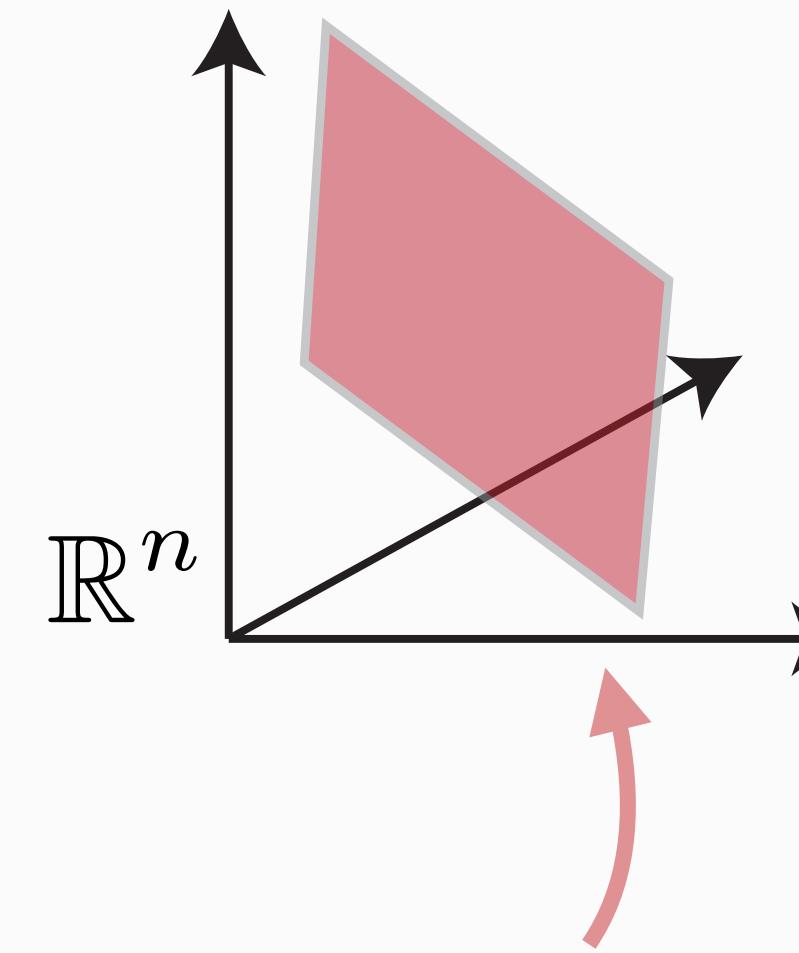
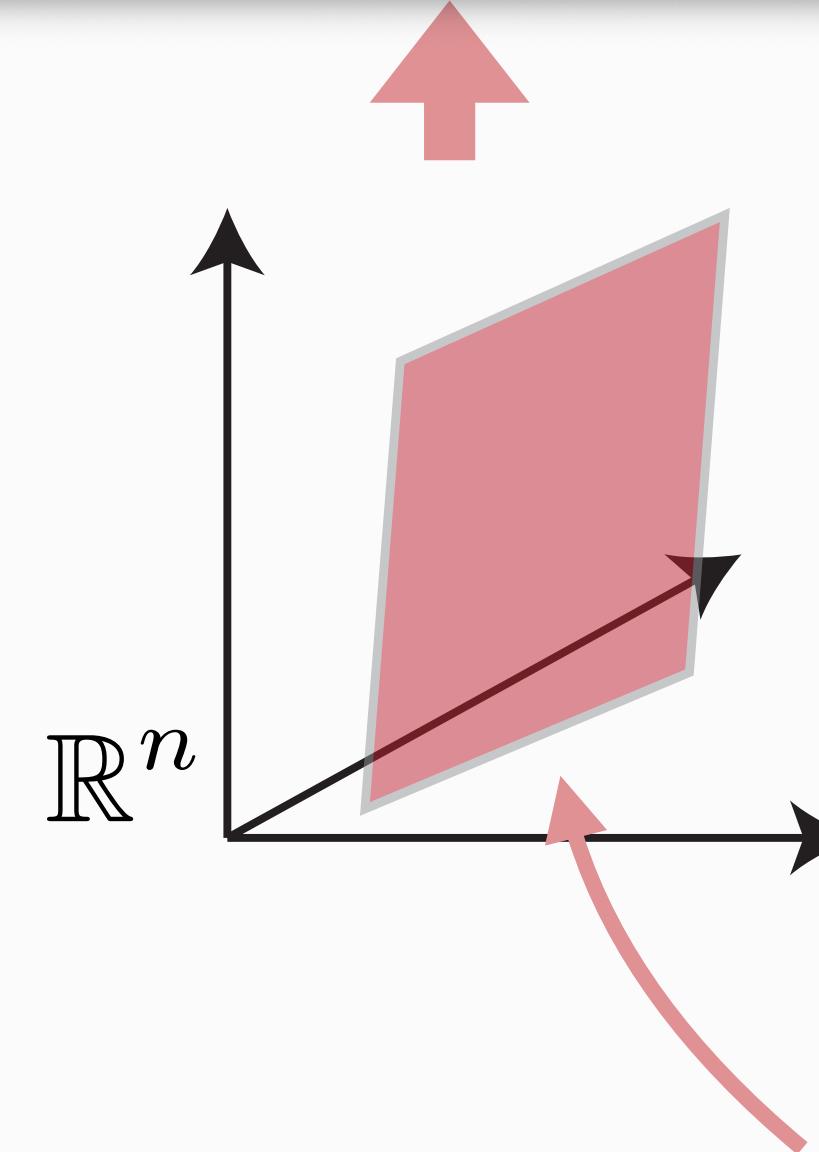
Next search plane



2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

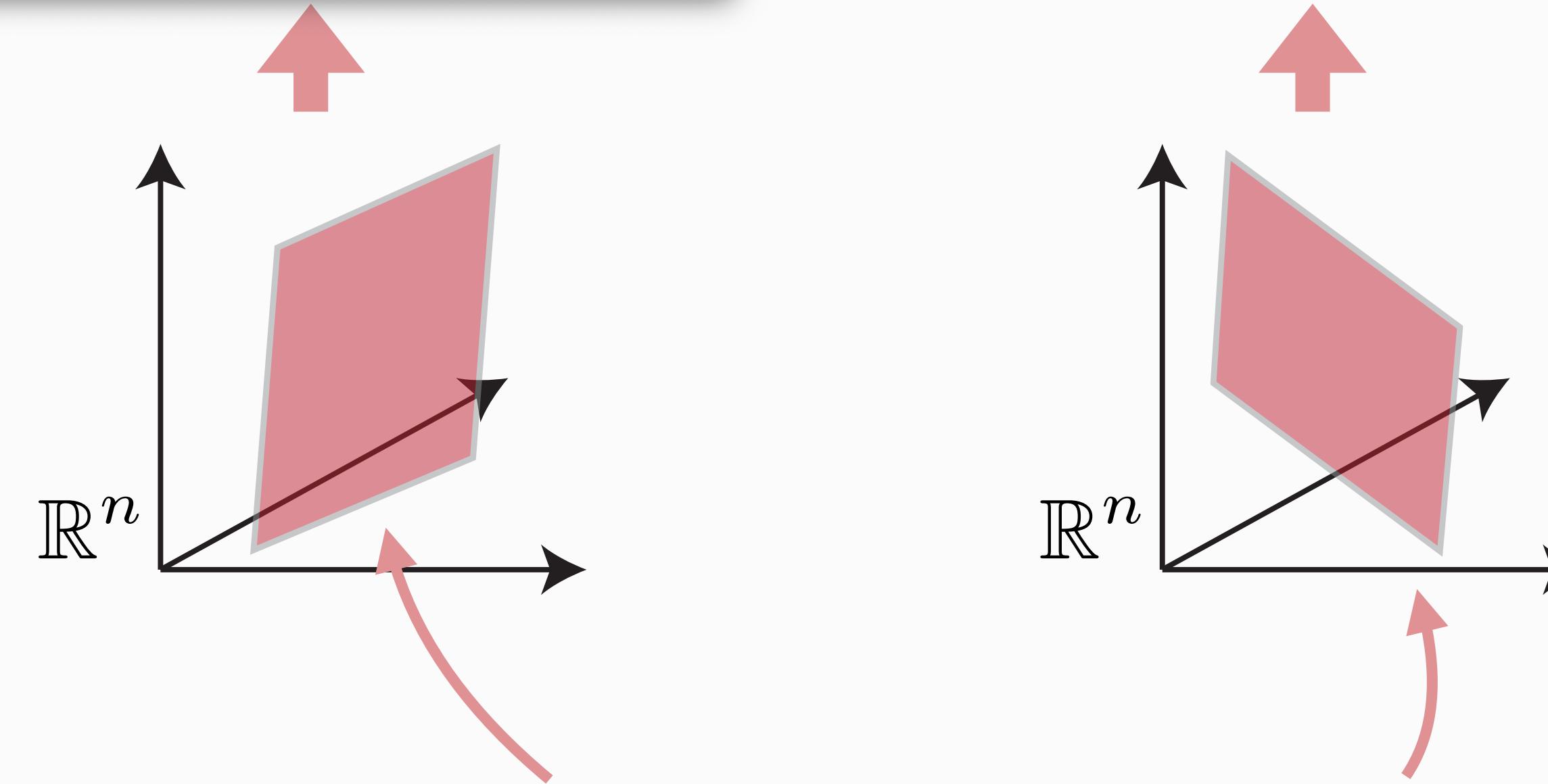
2D search subtask



2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization (PBO)**

...

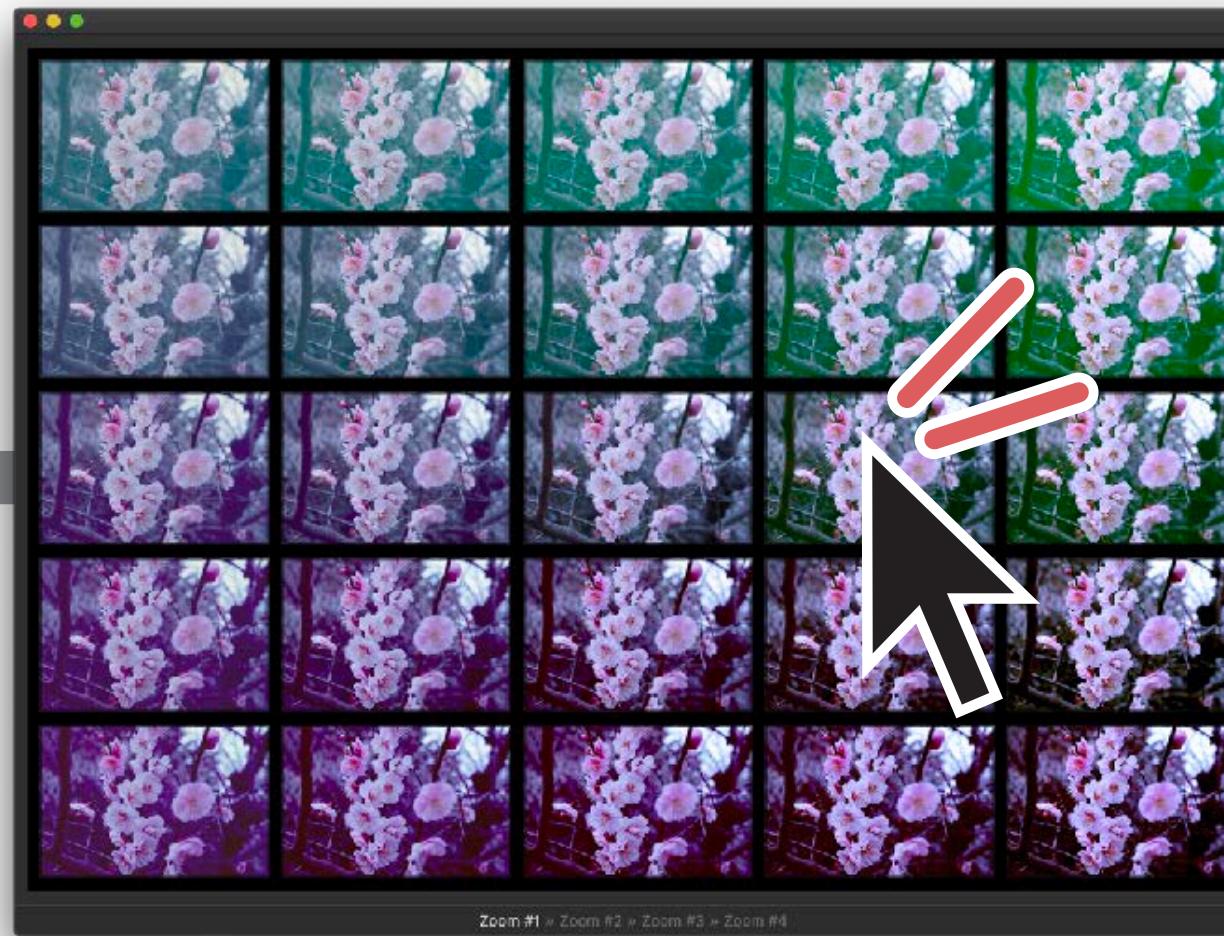
2D search subtask



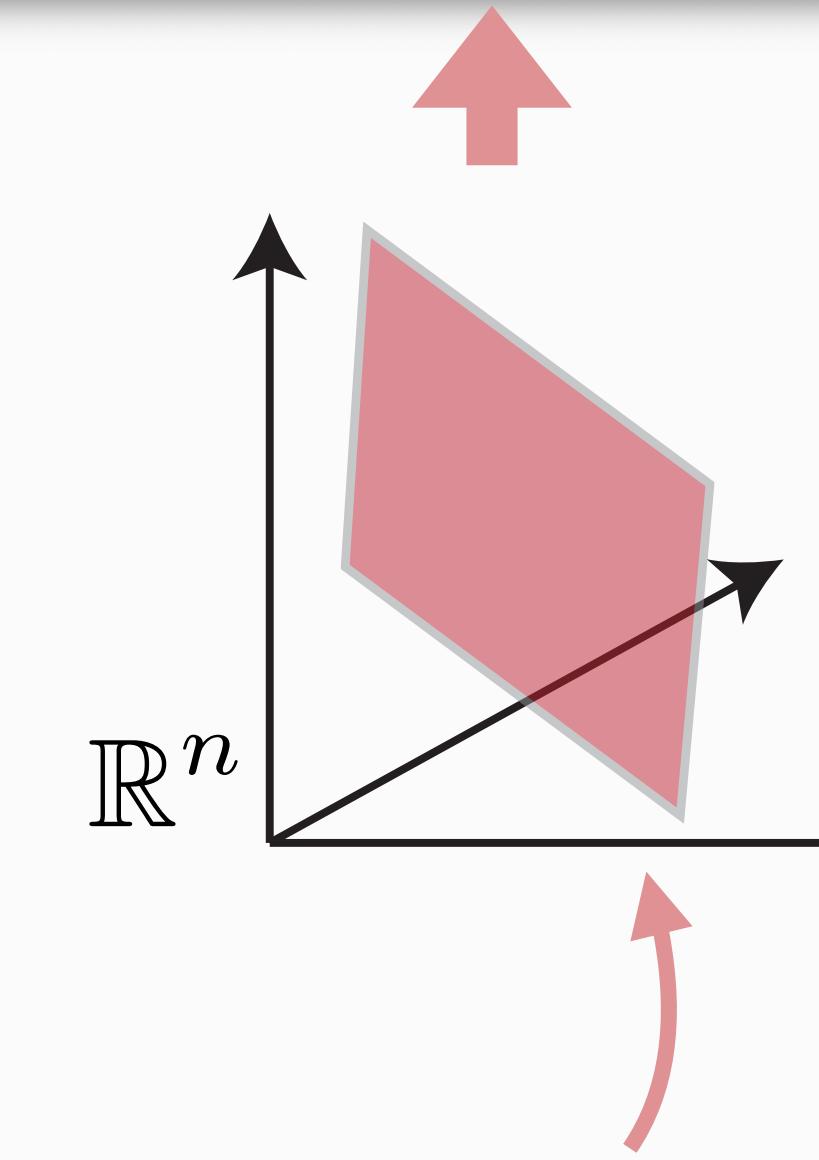
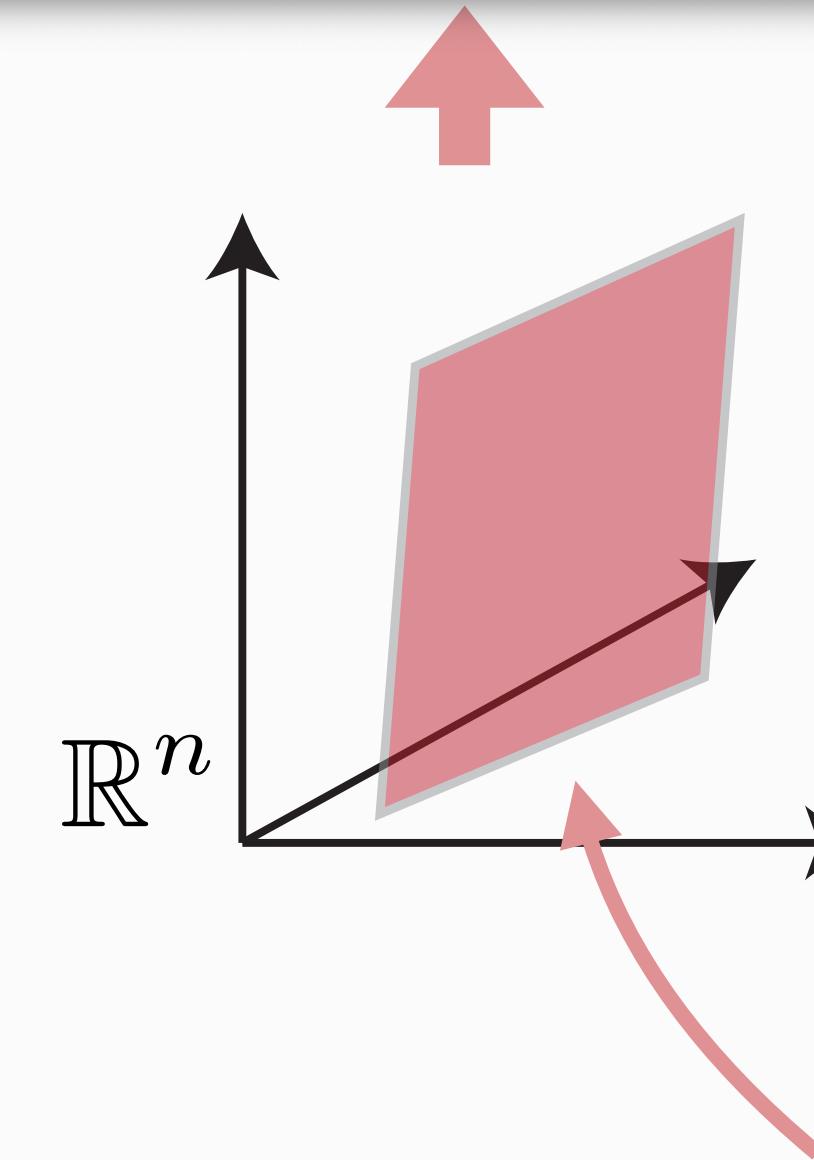
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

2D search subtask



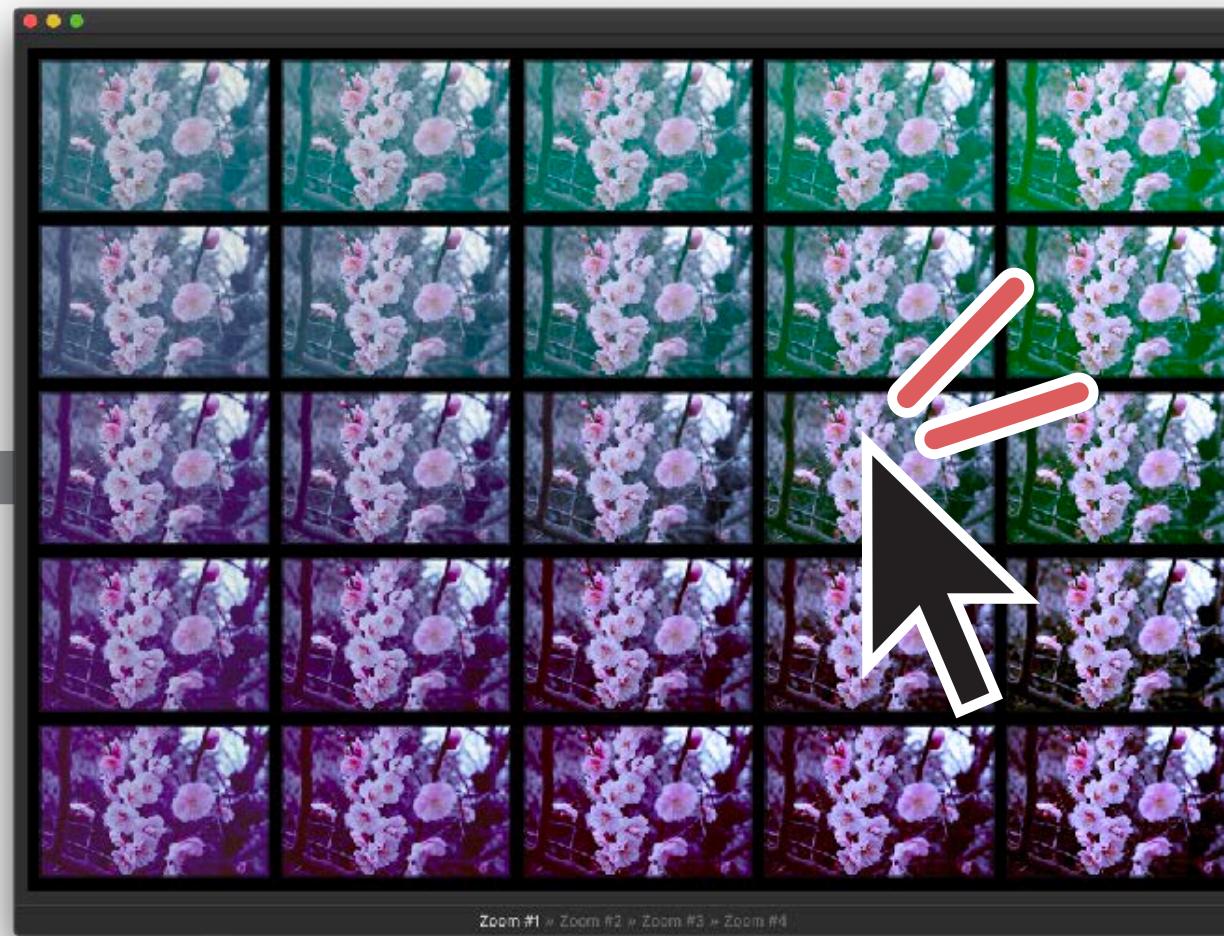
2D search subtask



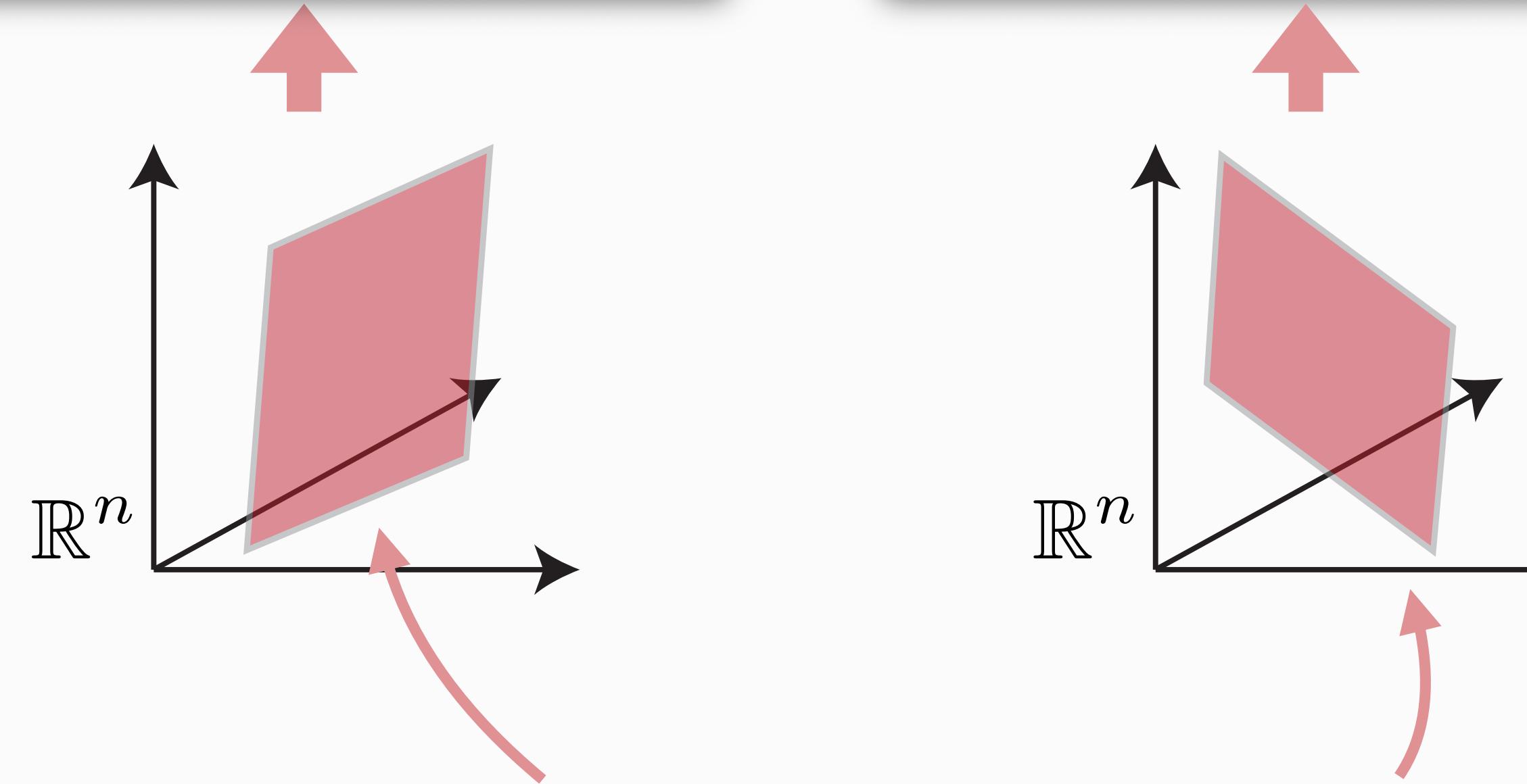
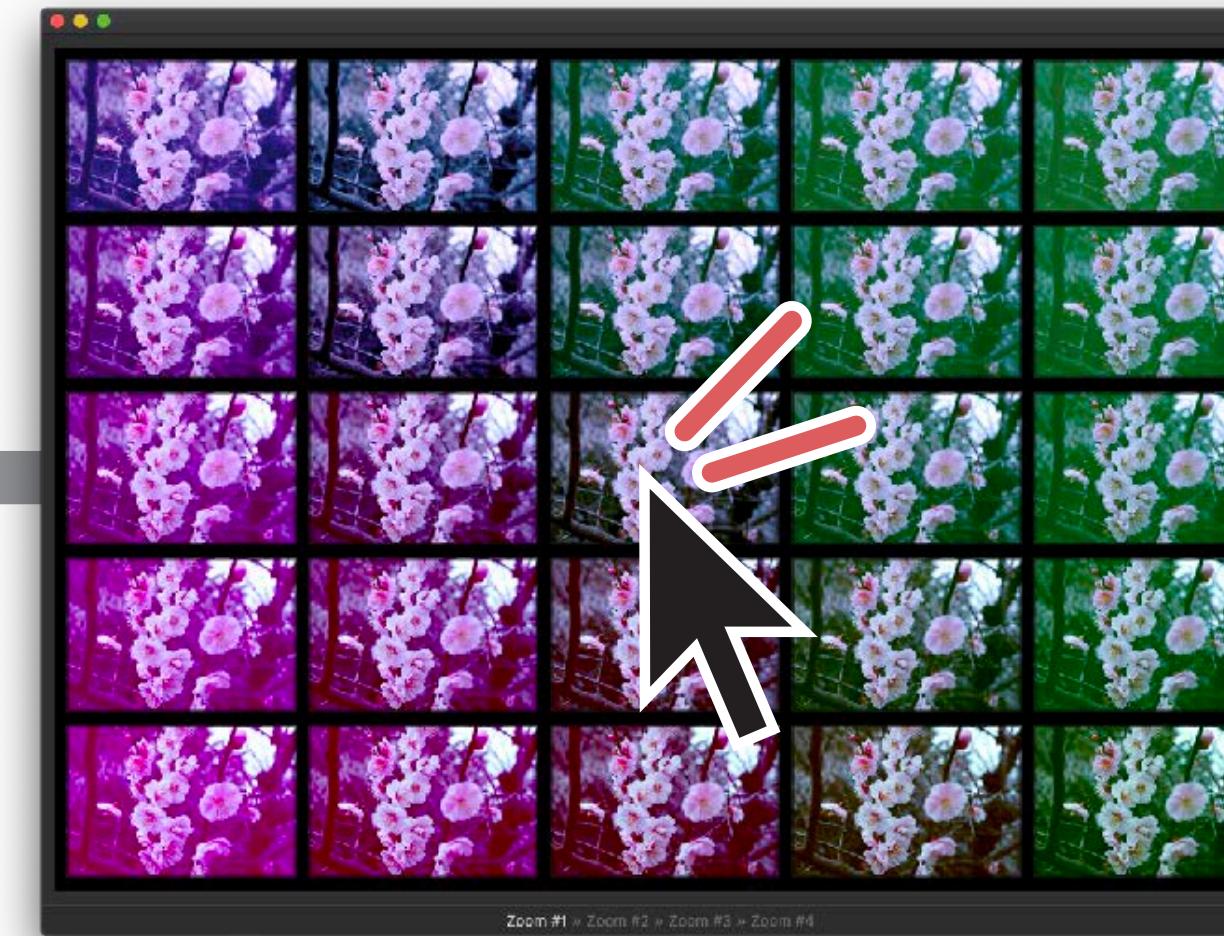
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization (PBO)**

...

2D search subtask



2D search subtask



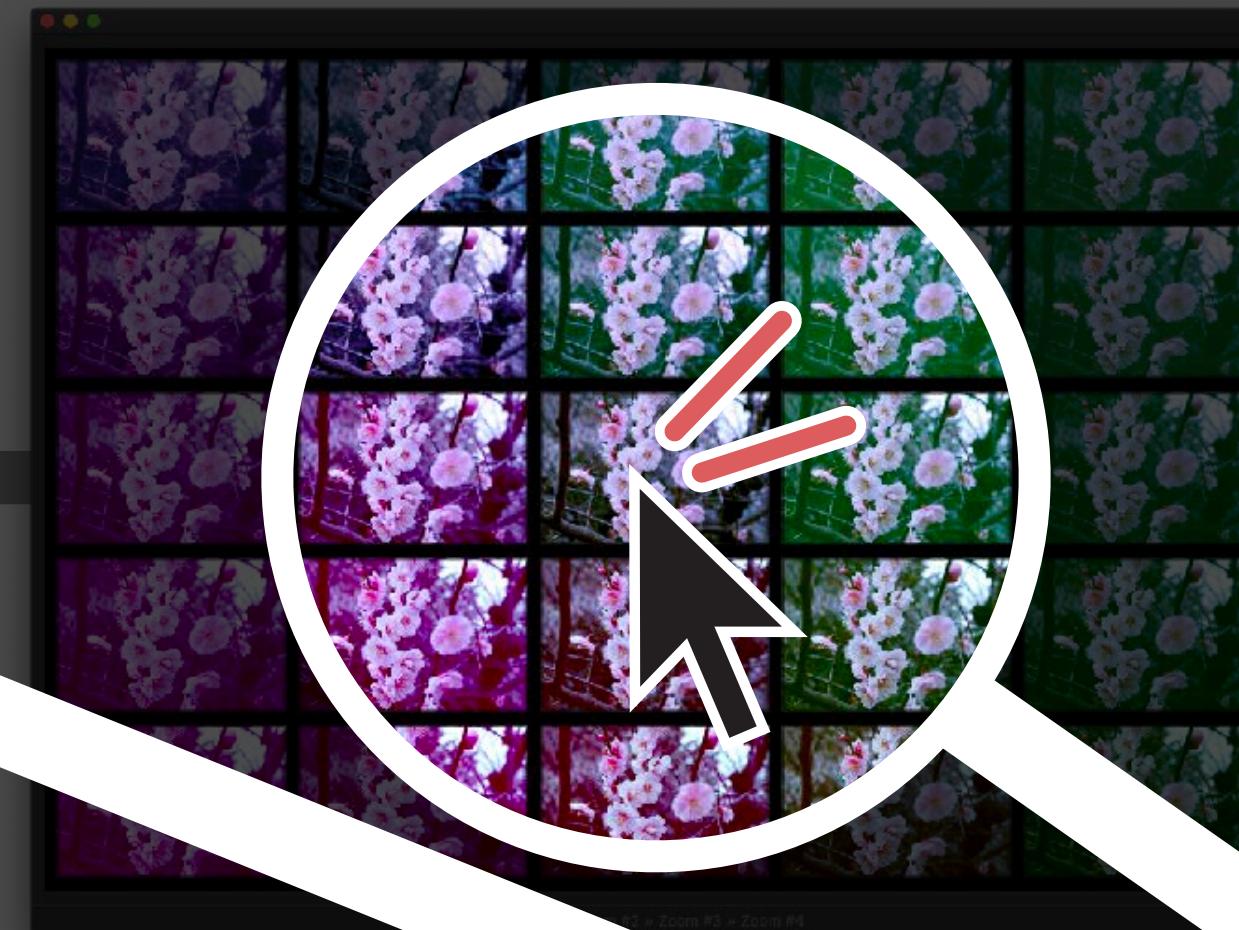
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

2D search subtask

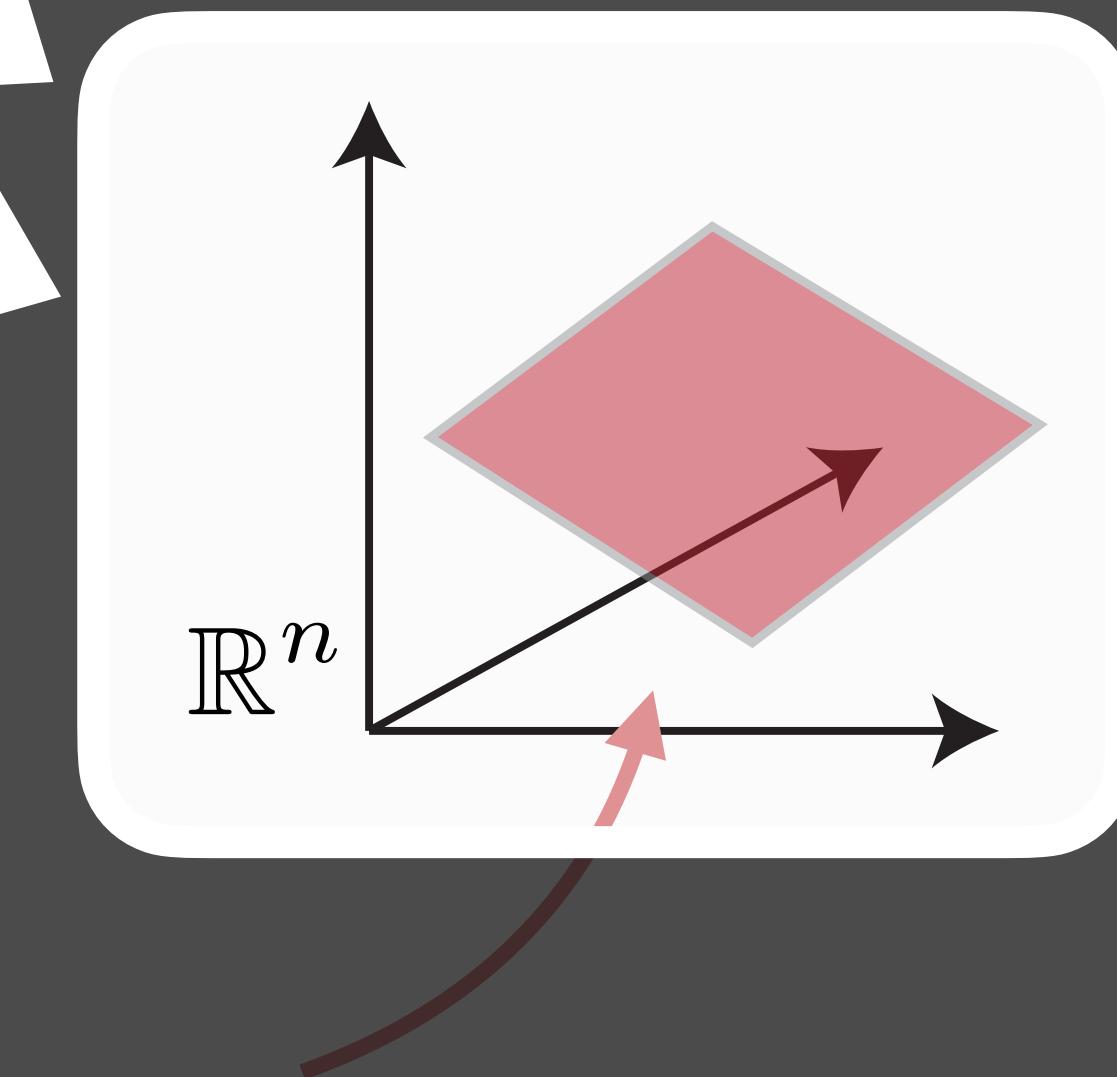
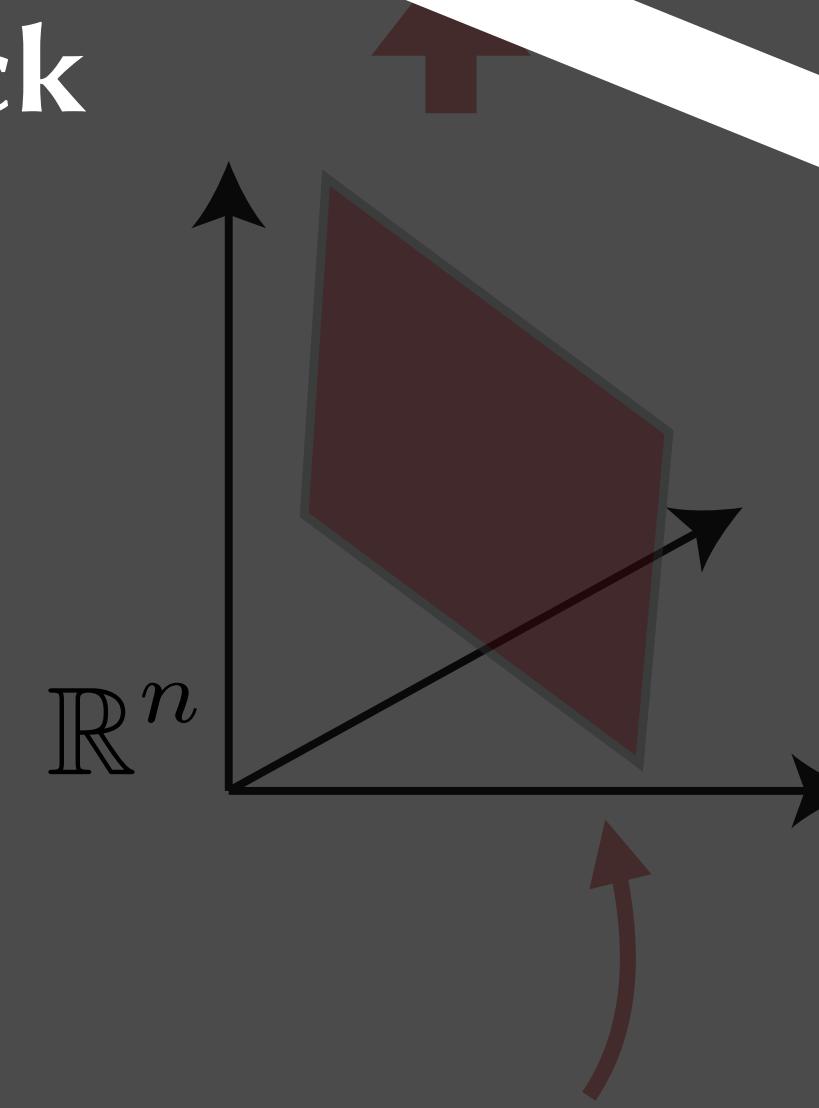
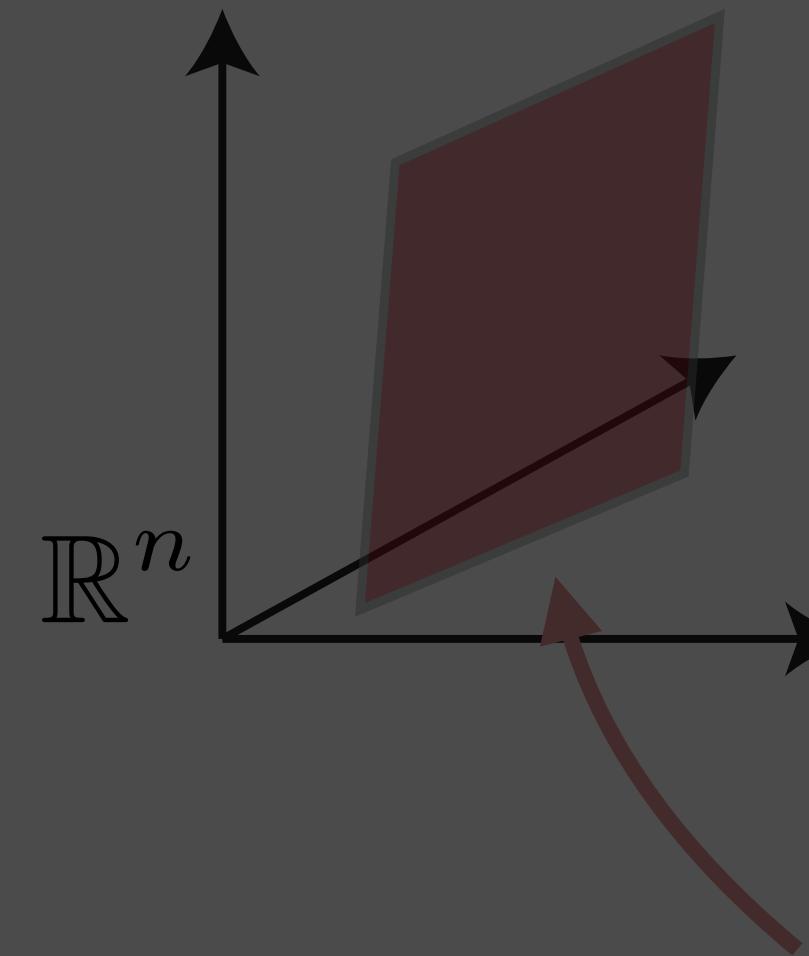


2D search subtask



Next search plane

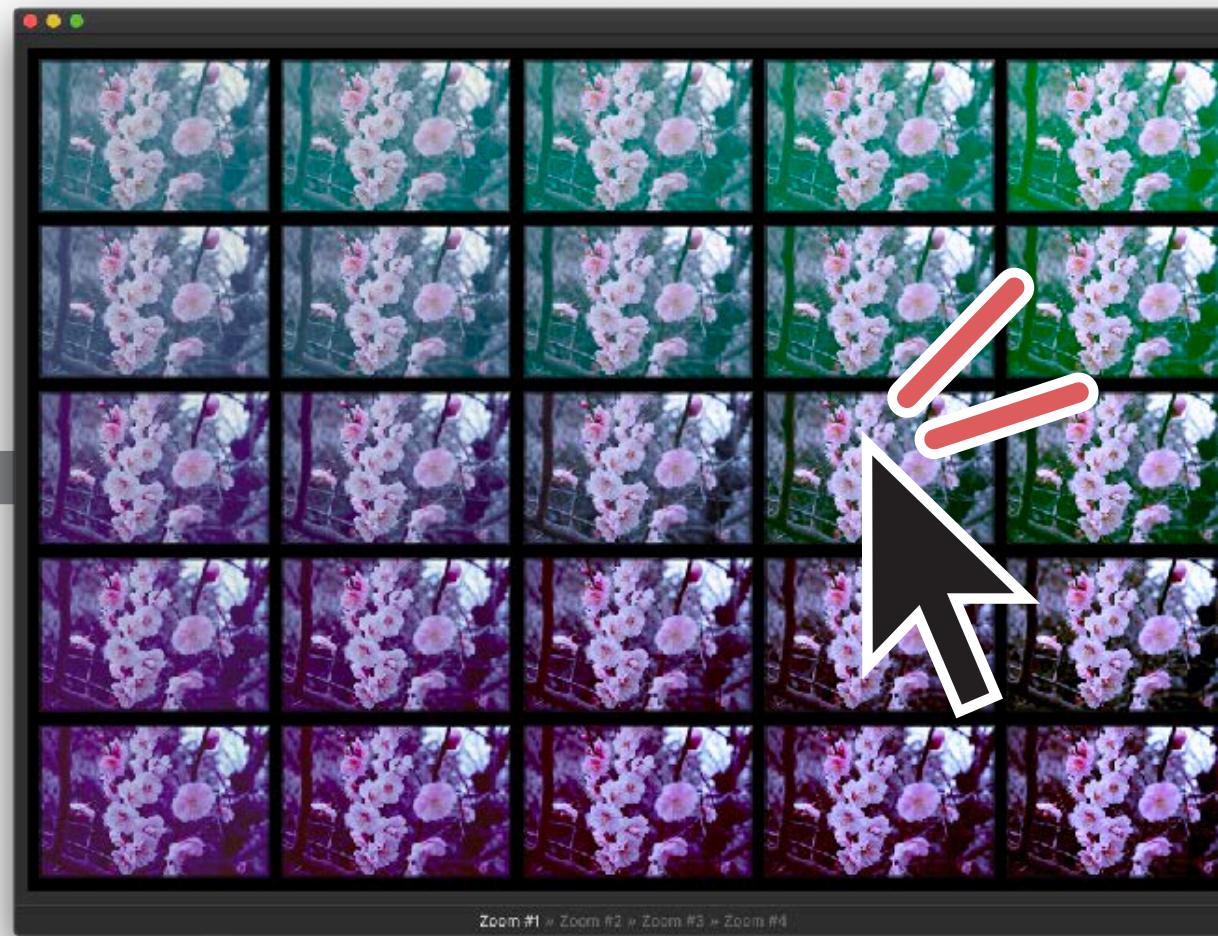
User's feedback



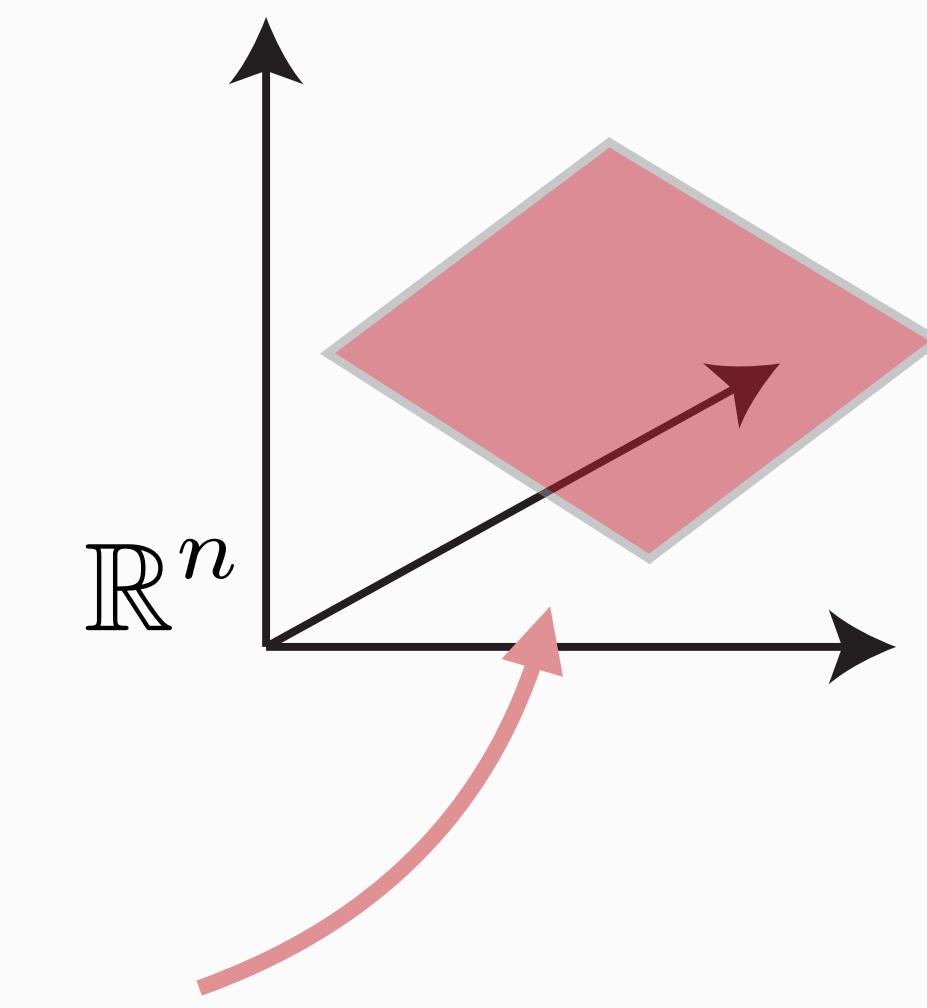
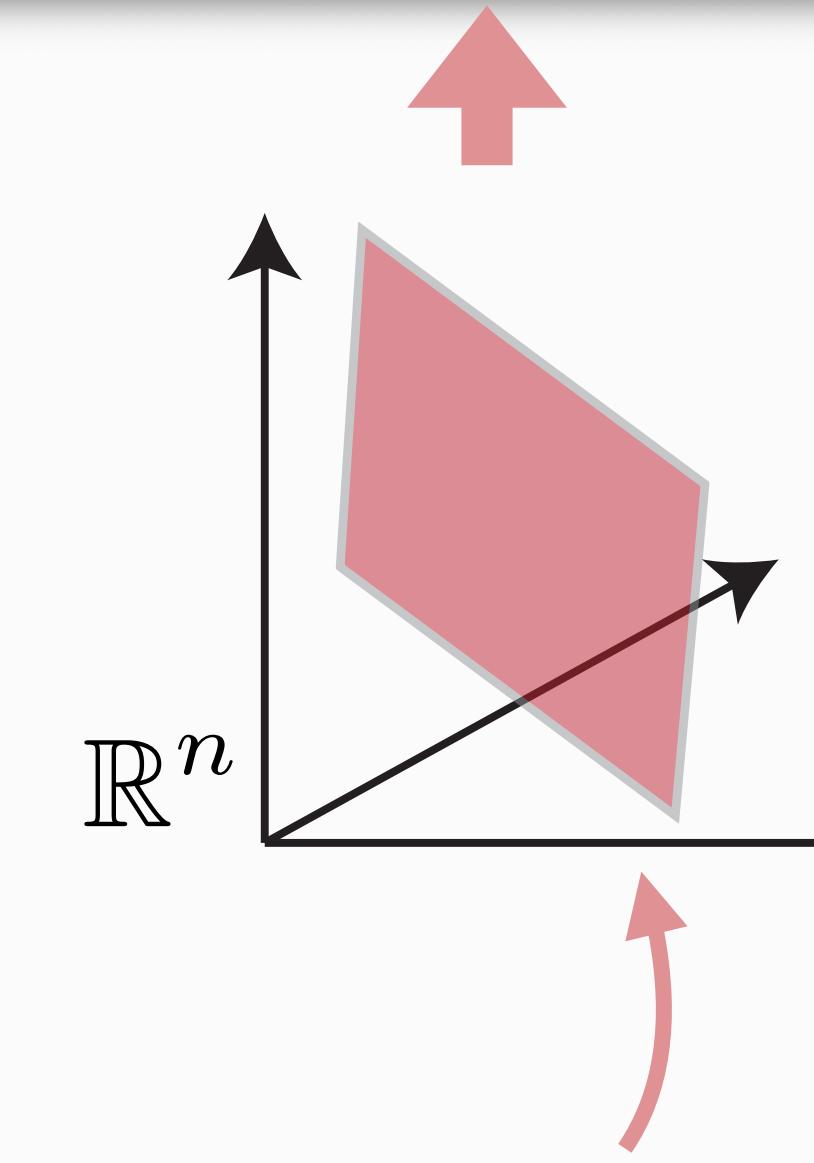
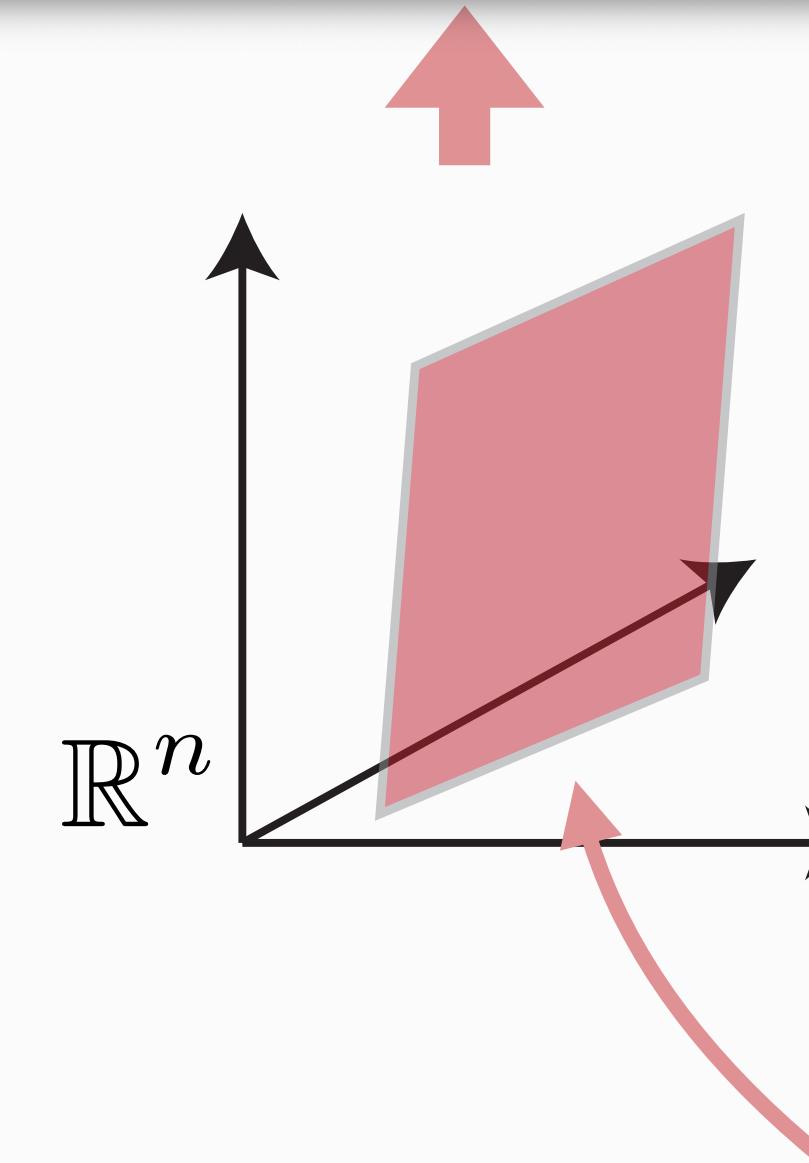
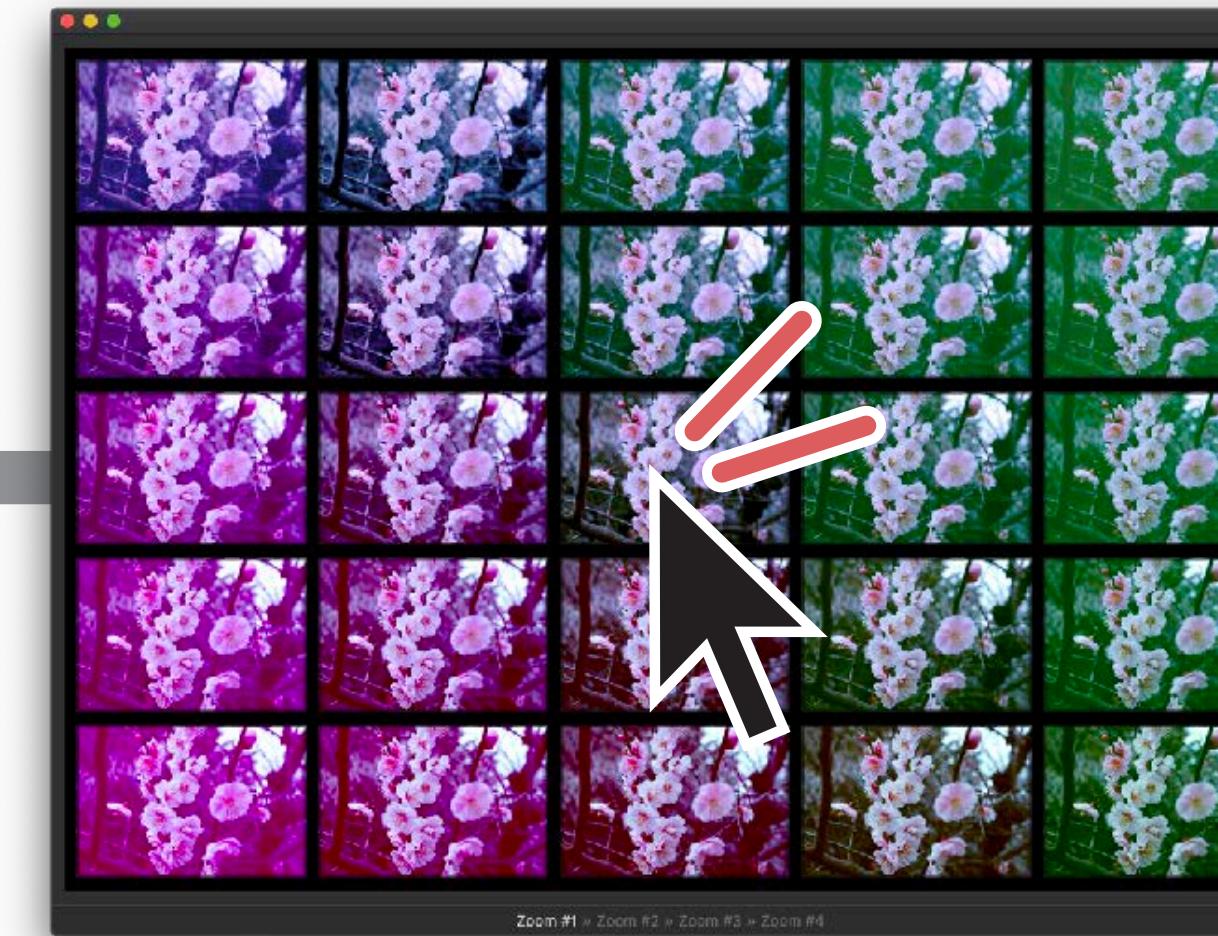
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization (PBO)**

...

2D search subtask



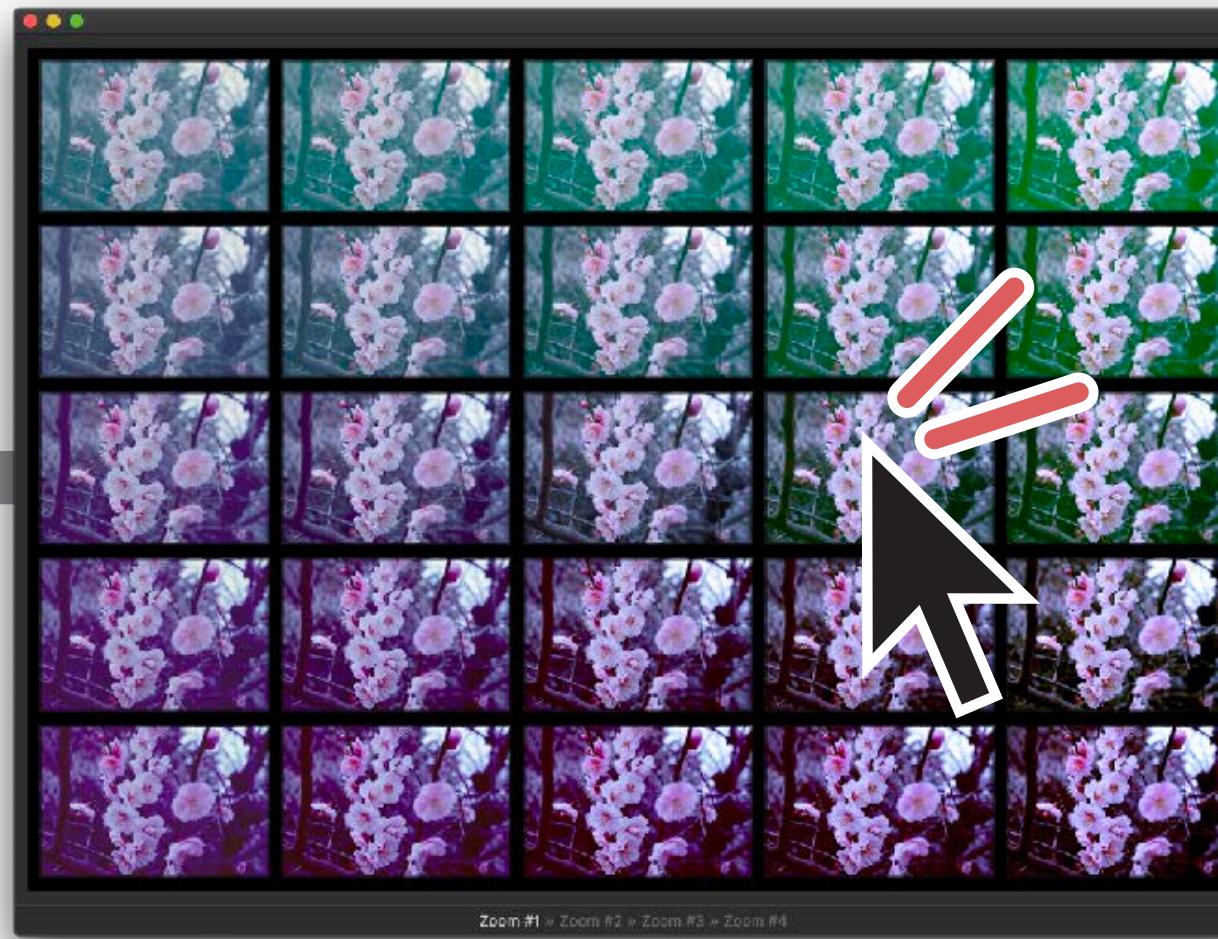
2D search subtask



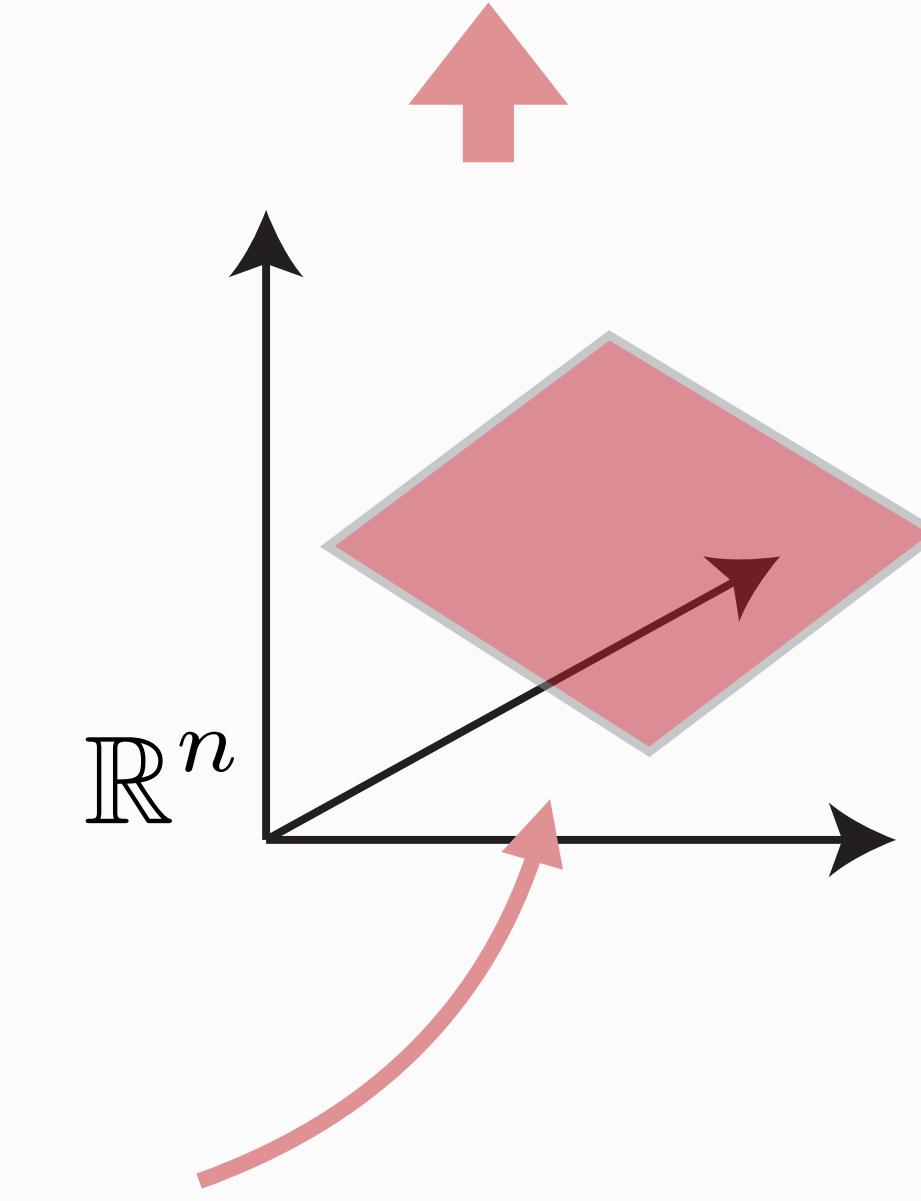
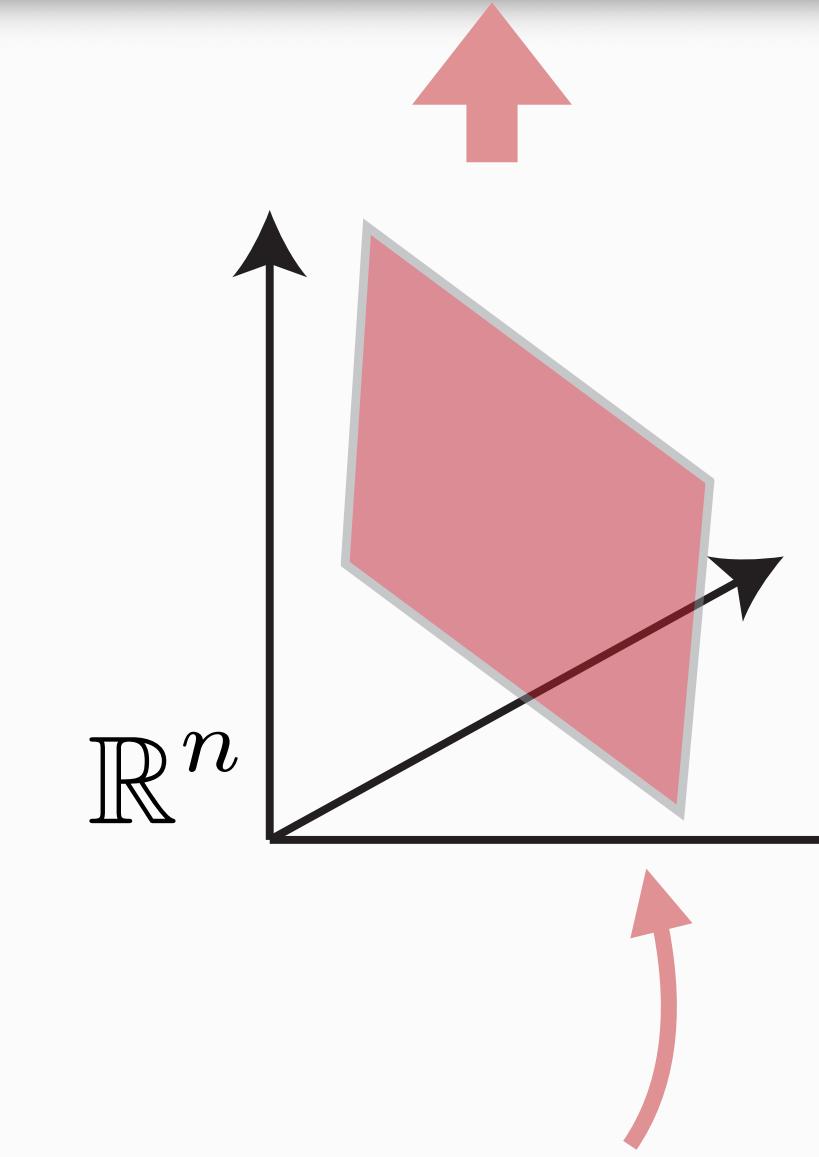
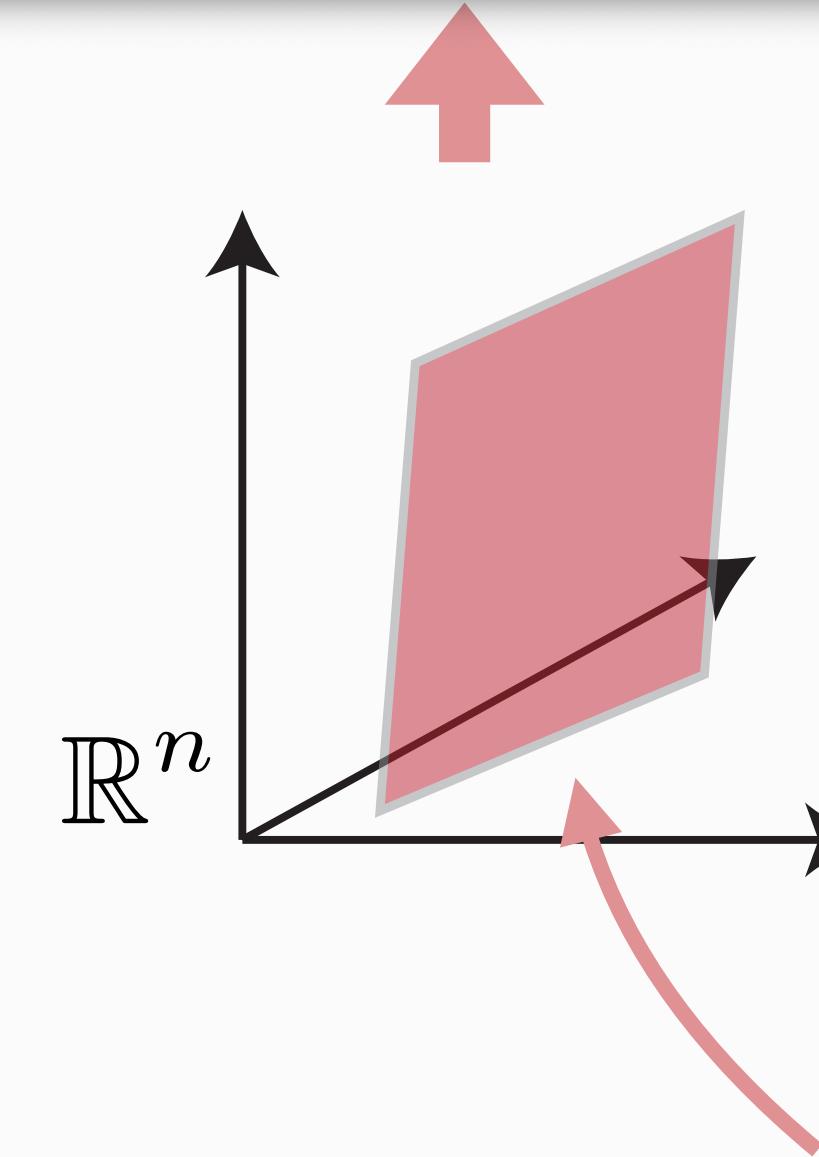
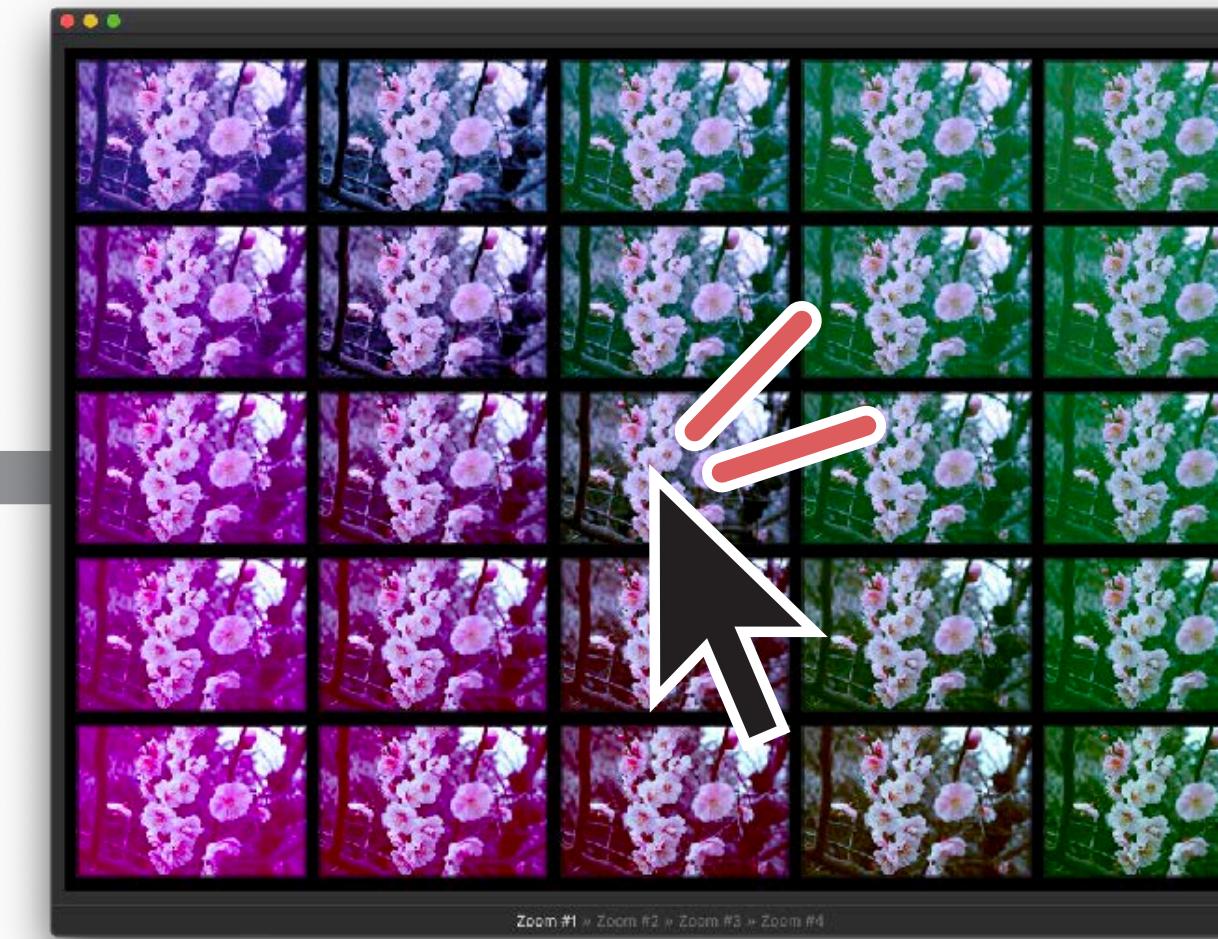
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

2D search subtask



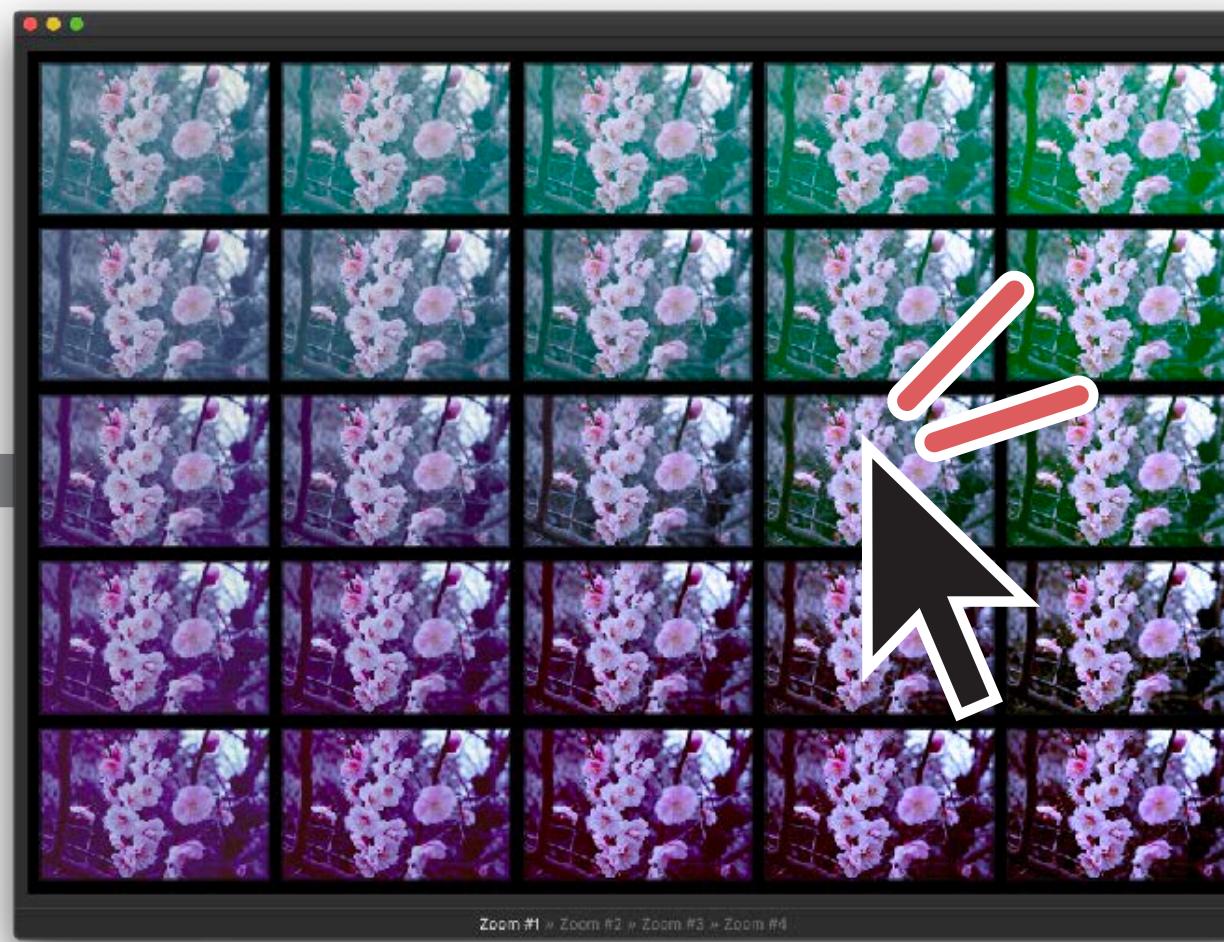
2D search subtask



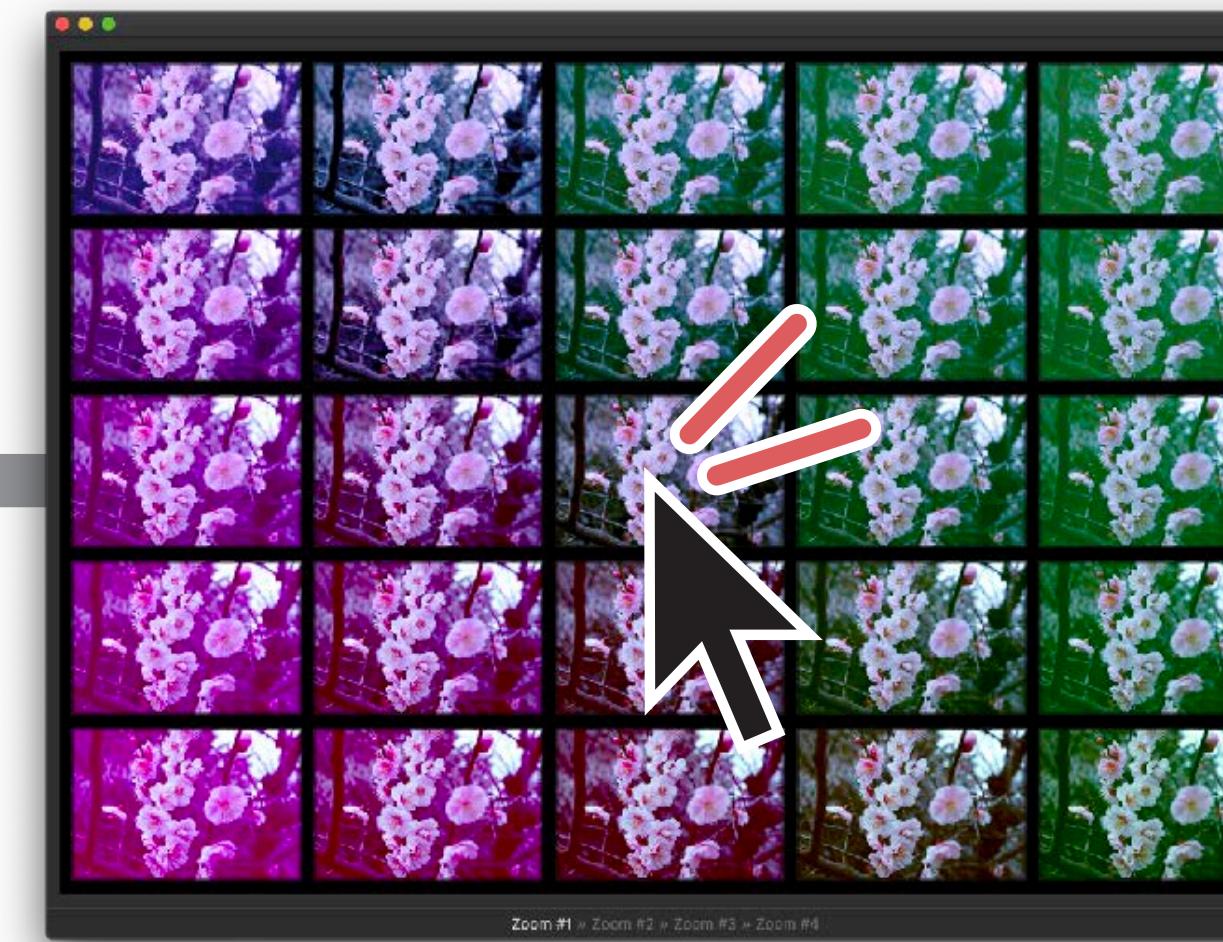
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

2D search subtask



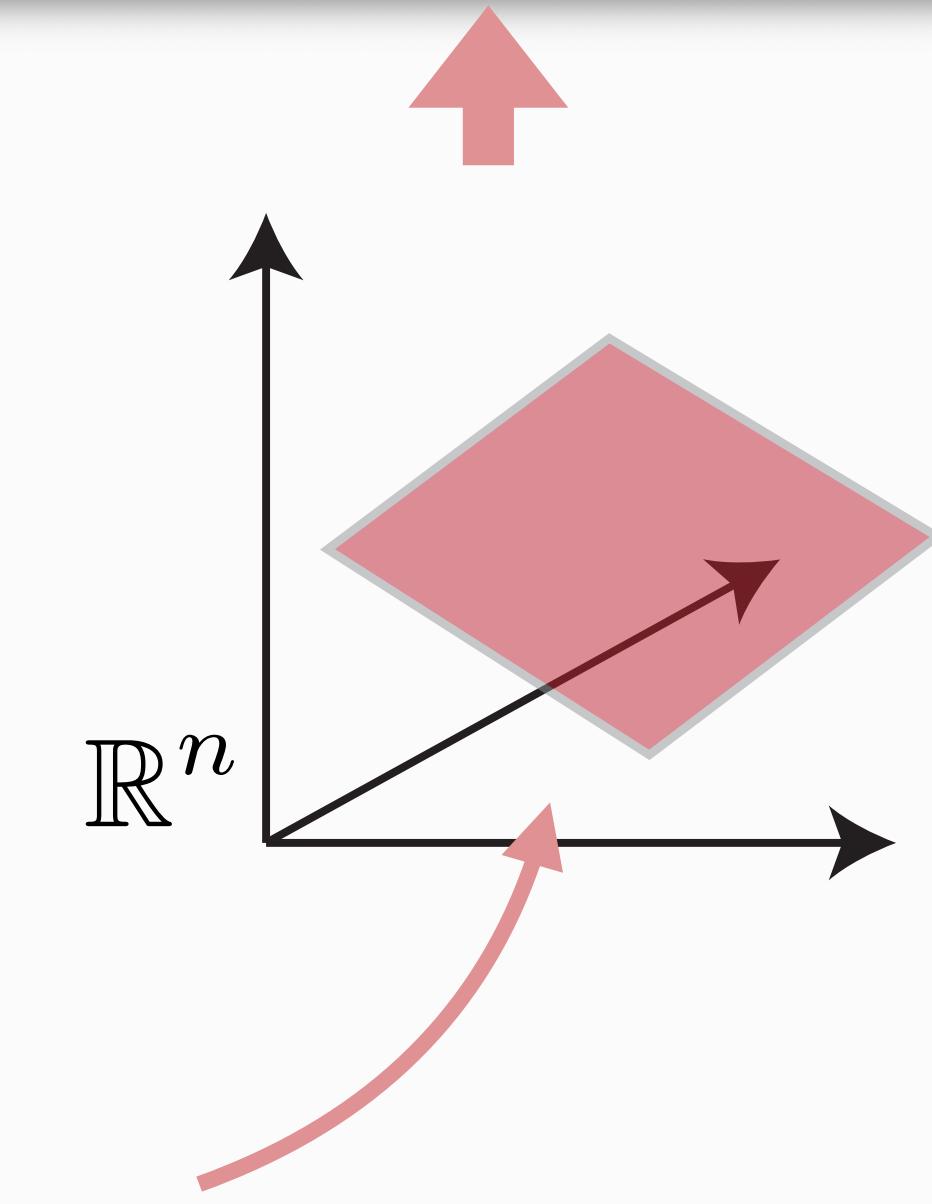
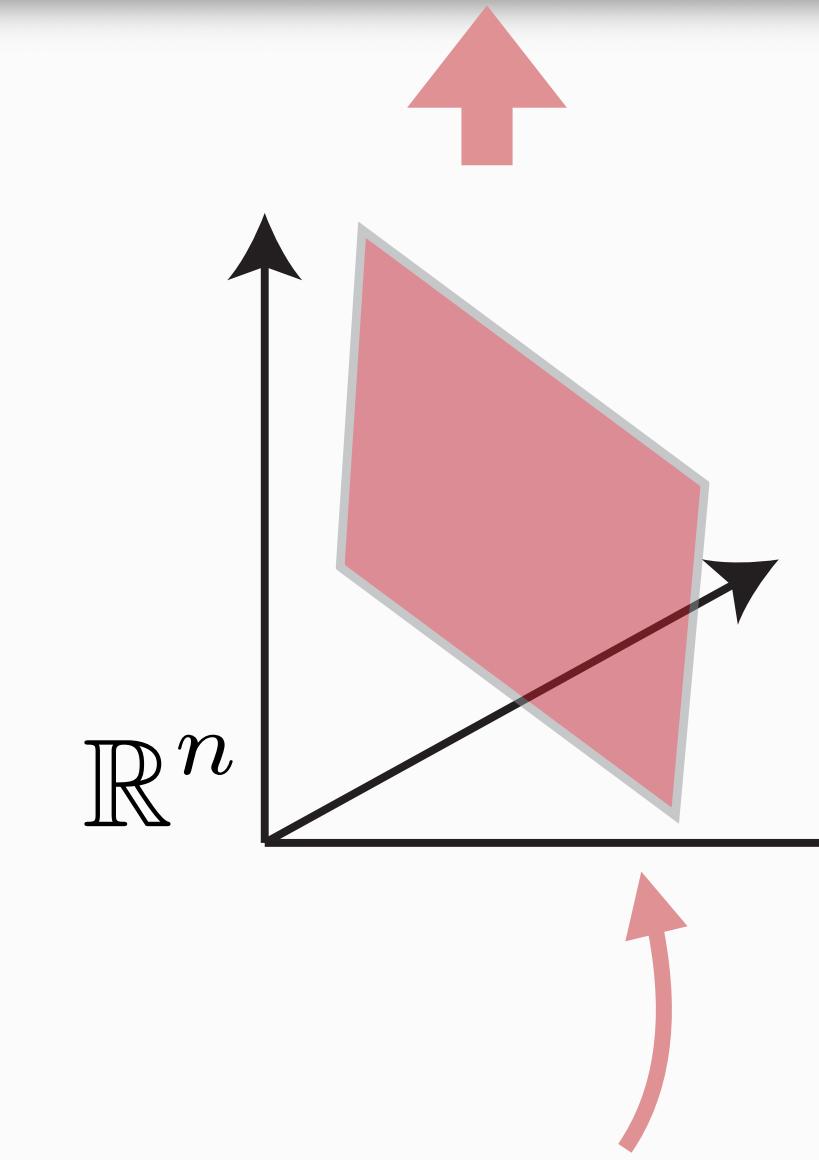
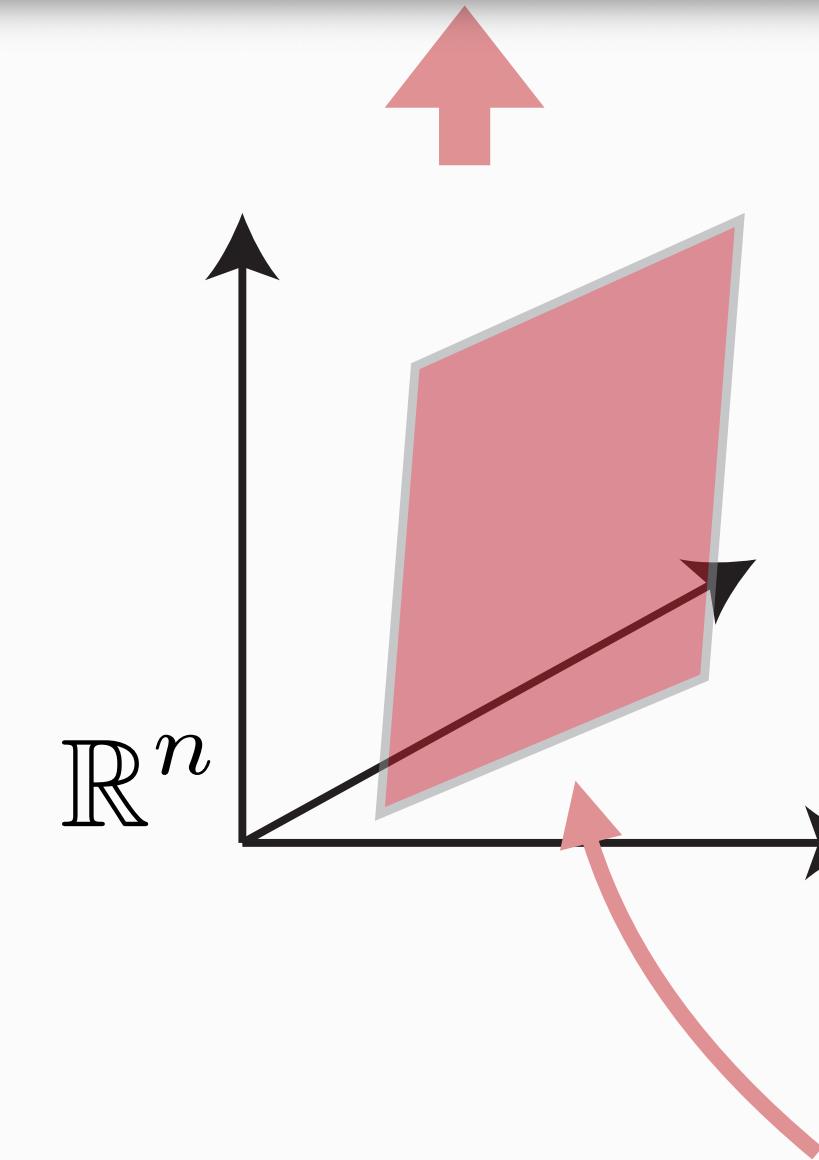
2D search subtask



2D search subtask



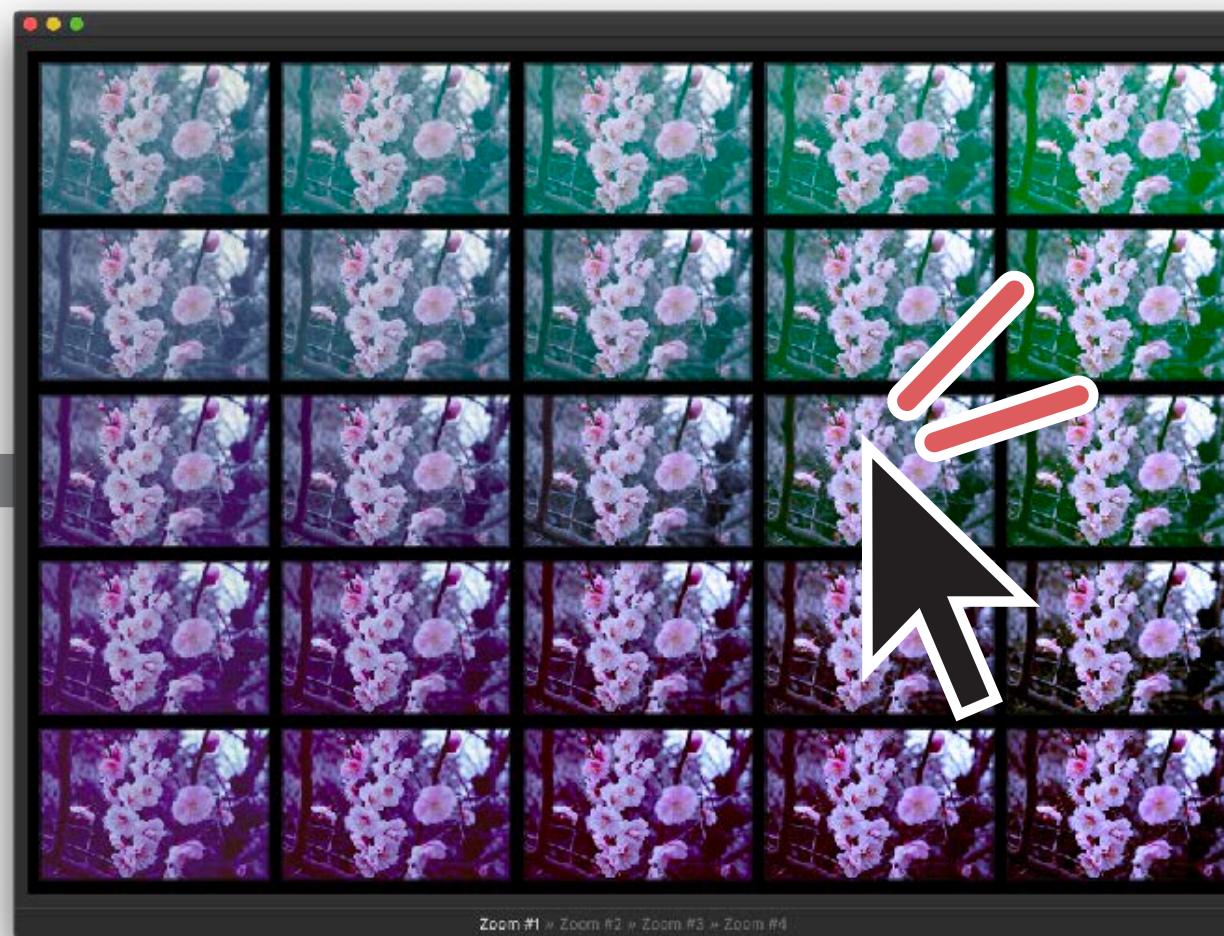
...



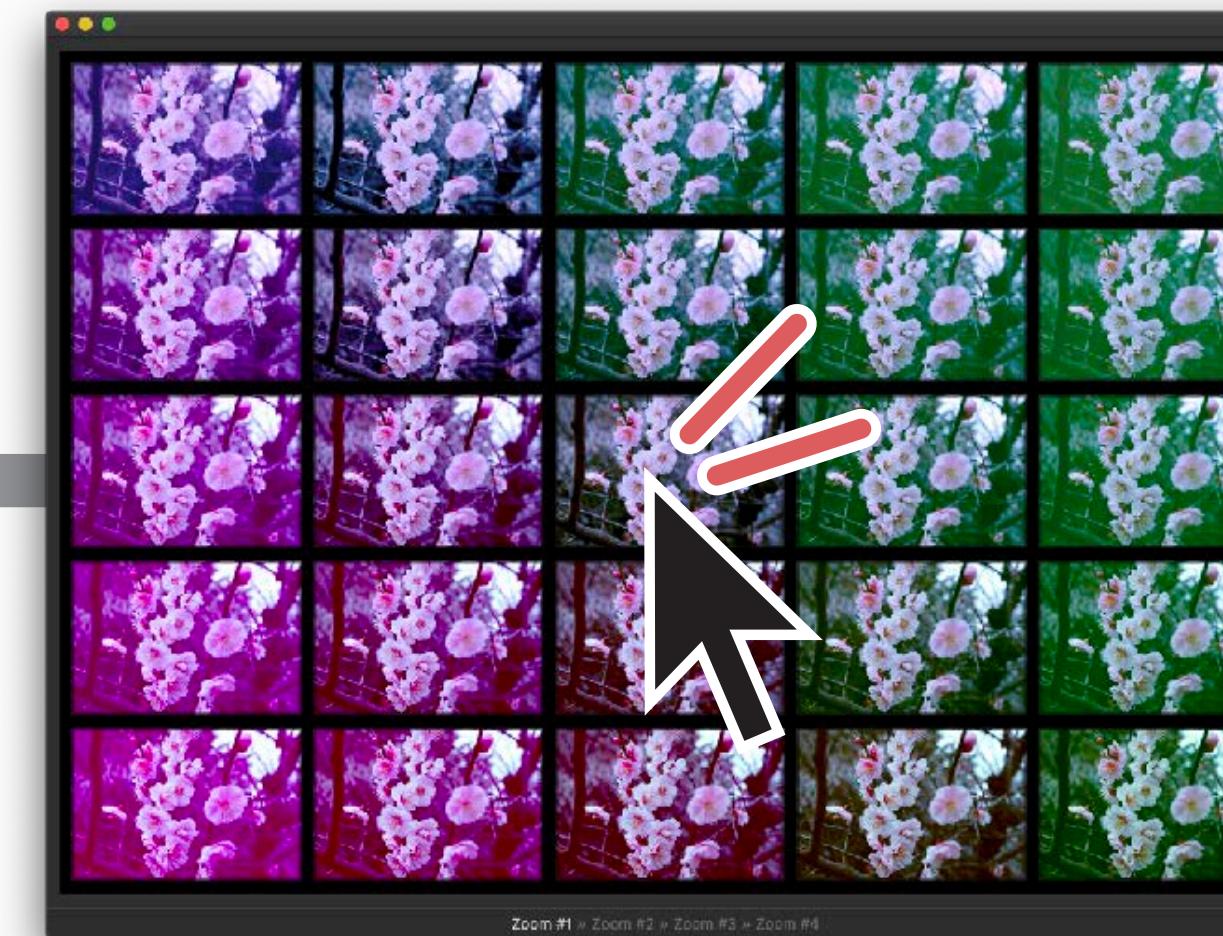
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

...

2D search subtask



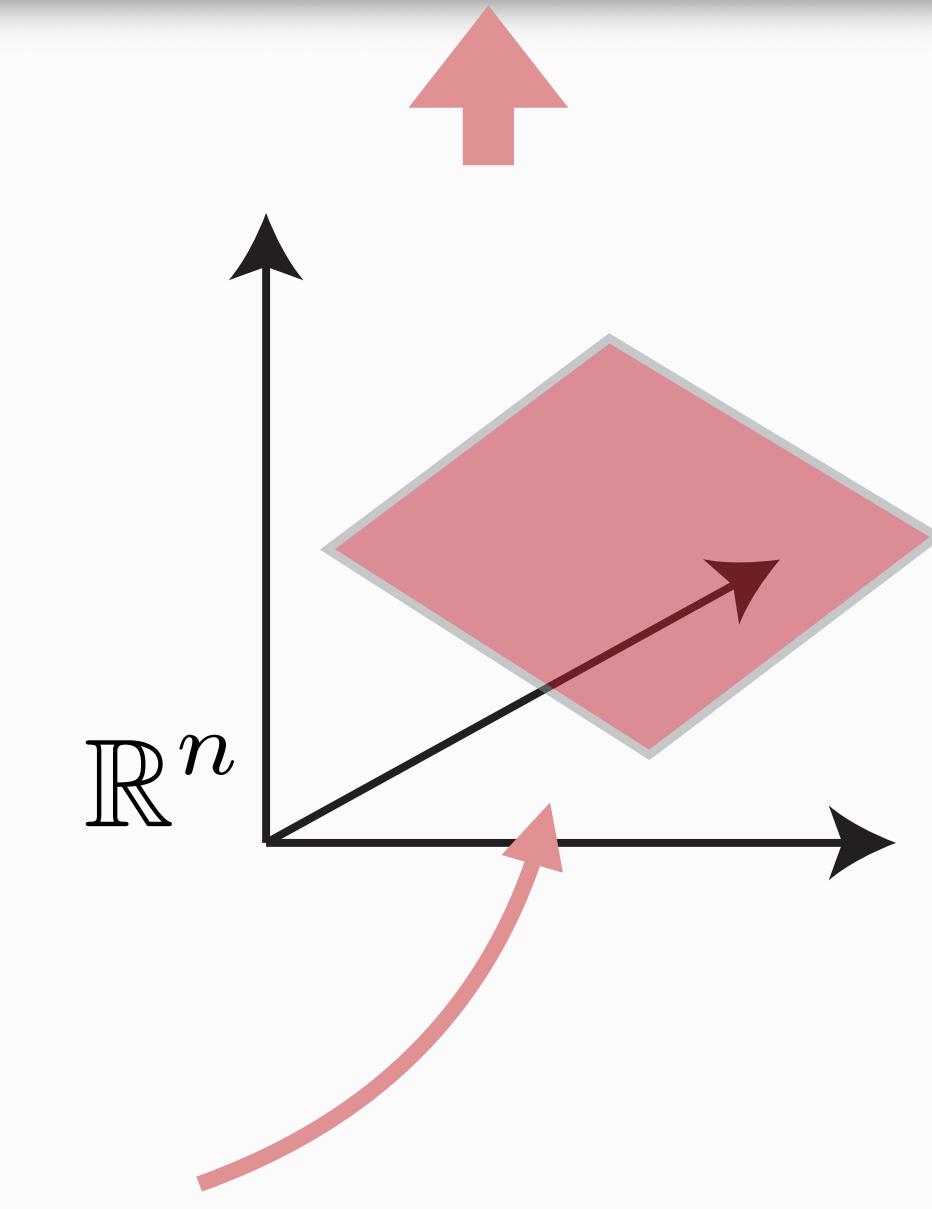
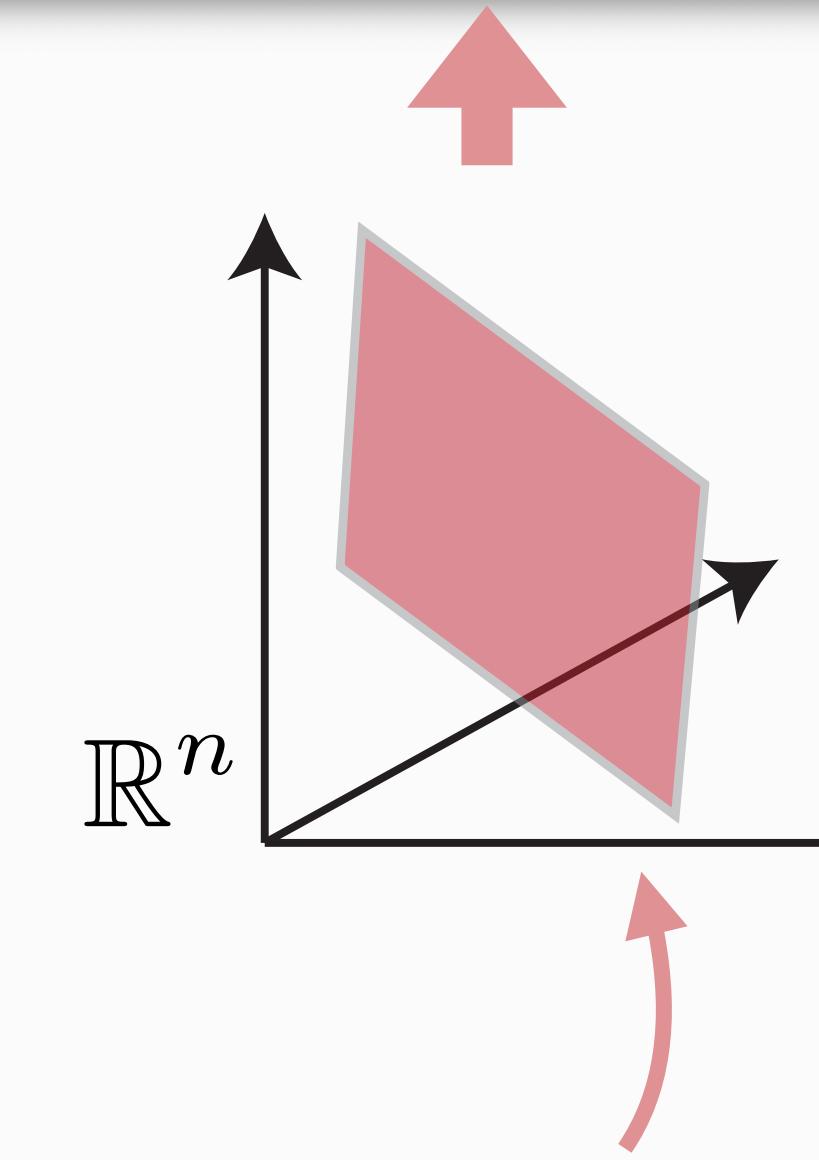
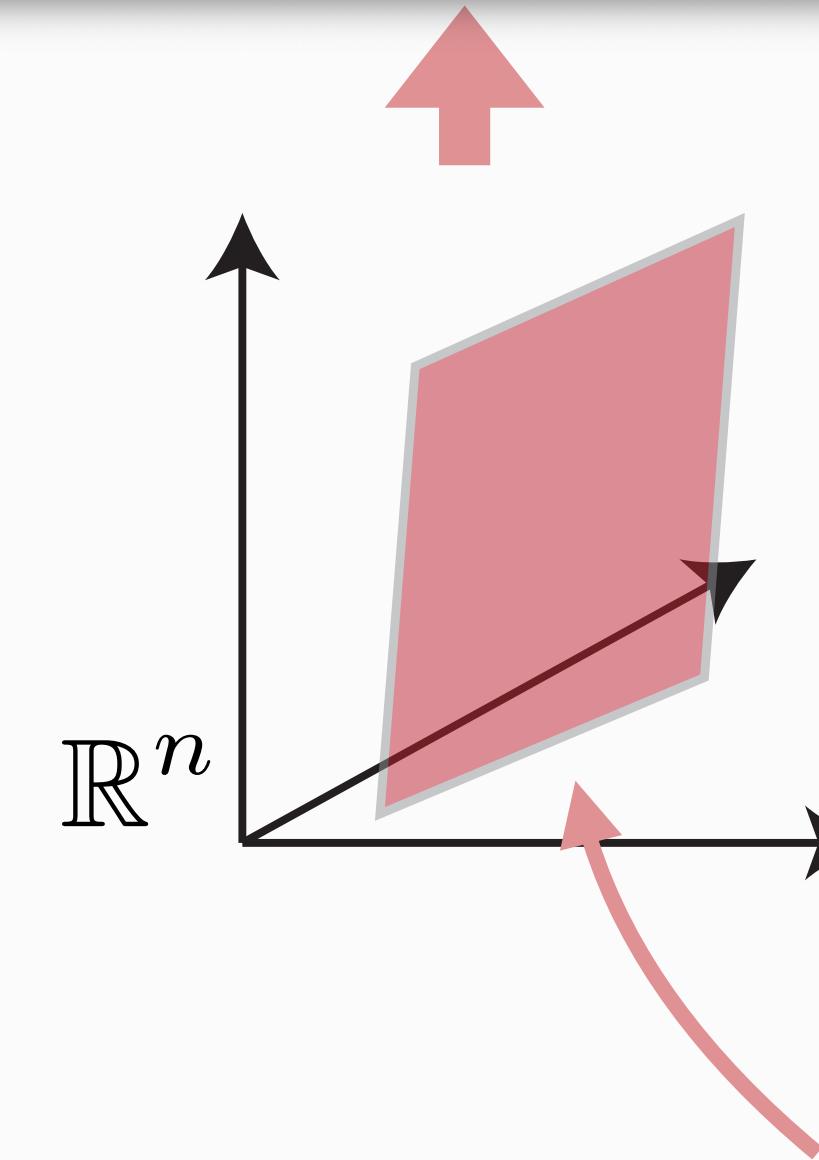
2D search subtask



2D search subtask



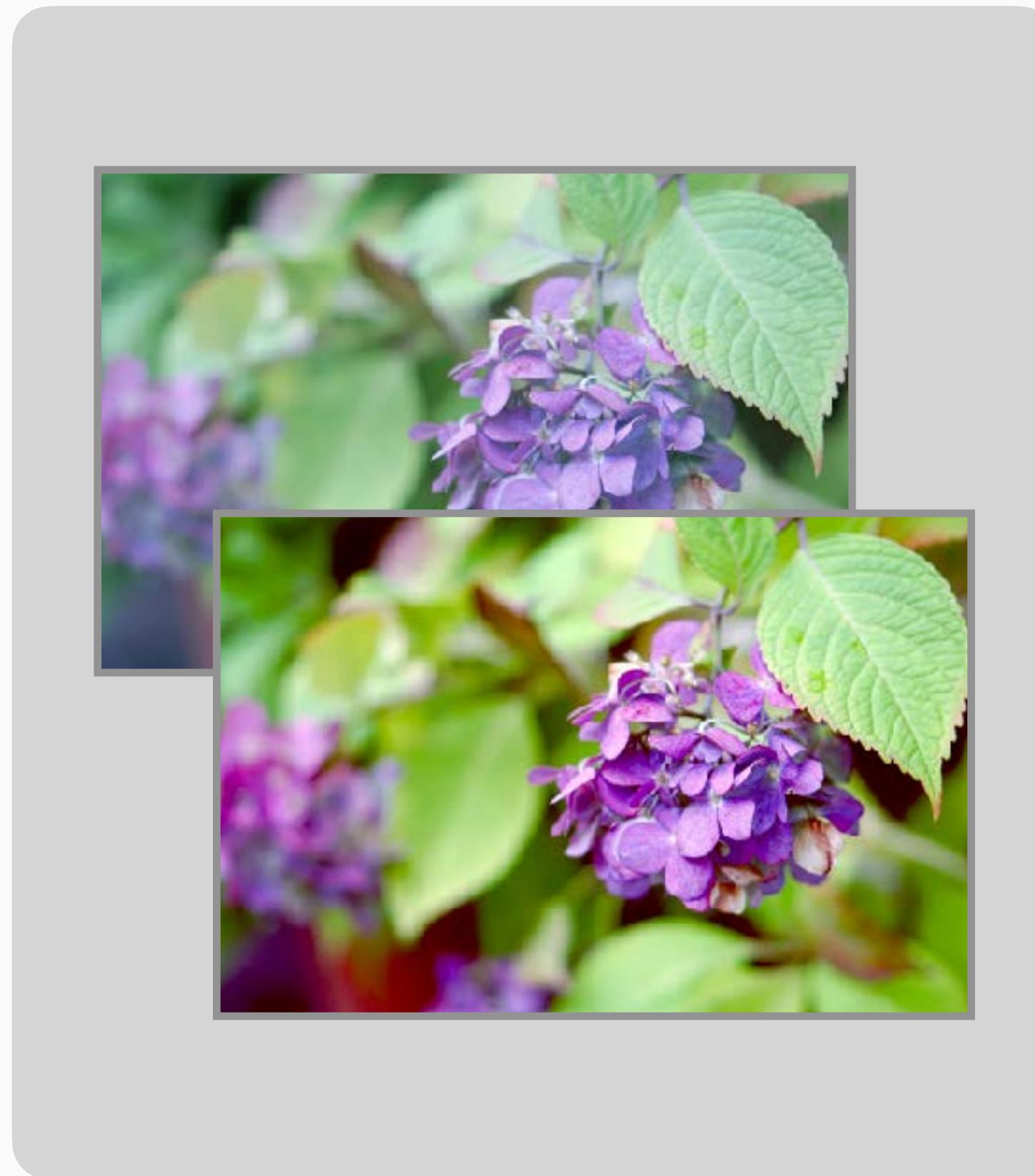
...



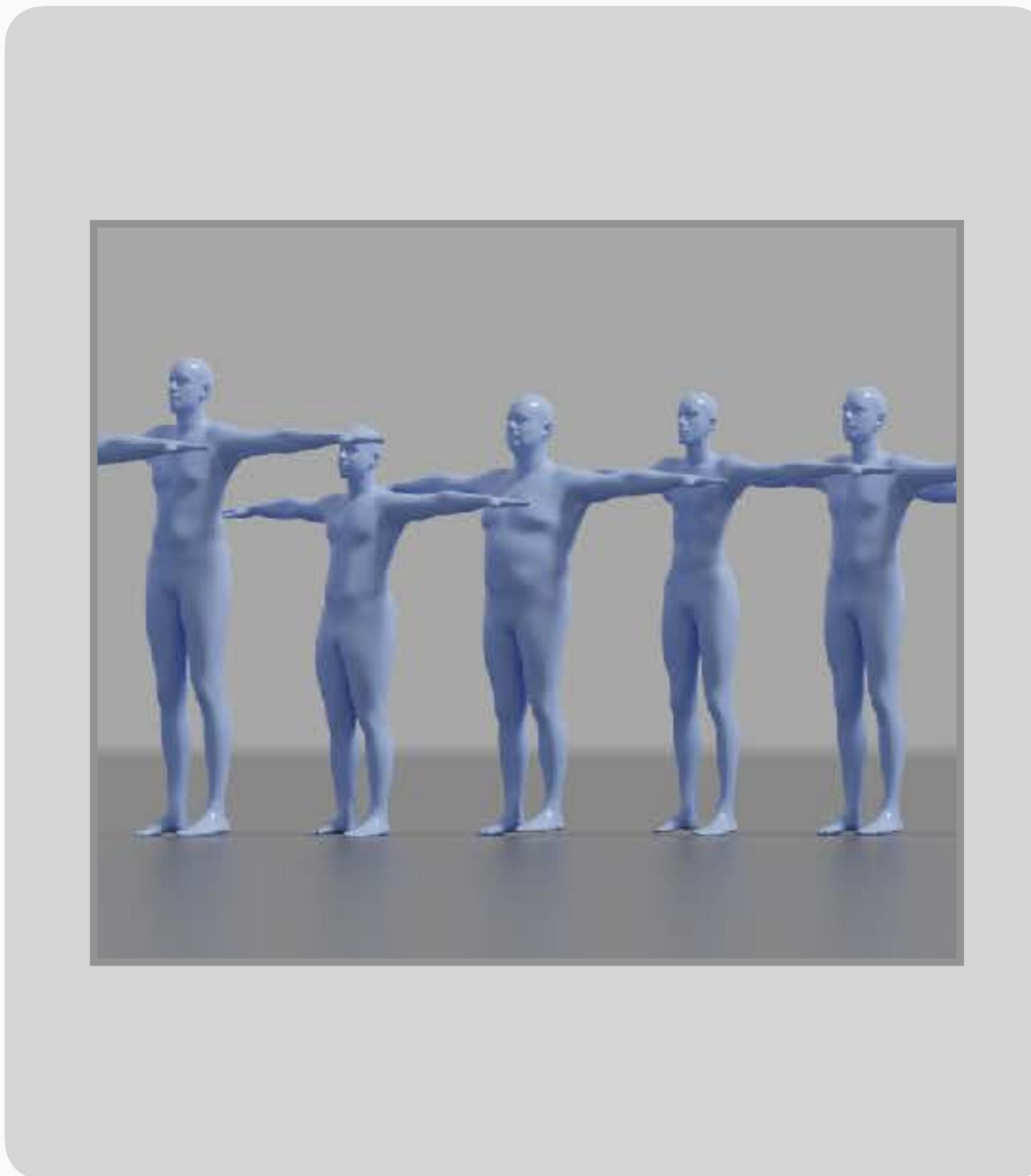
2-dimensional search subspaces (= **search planes**)
determined by **preferential Bayesian optimization** (PBO)

Potential Applications

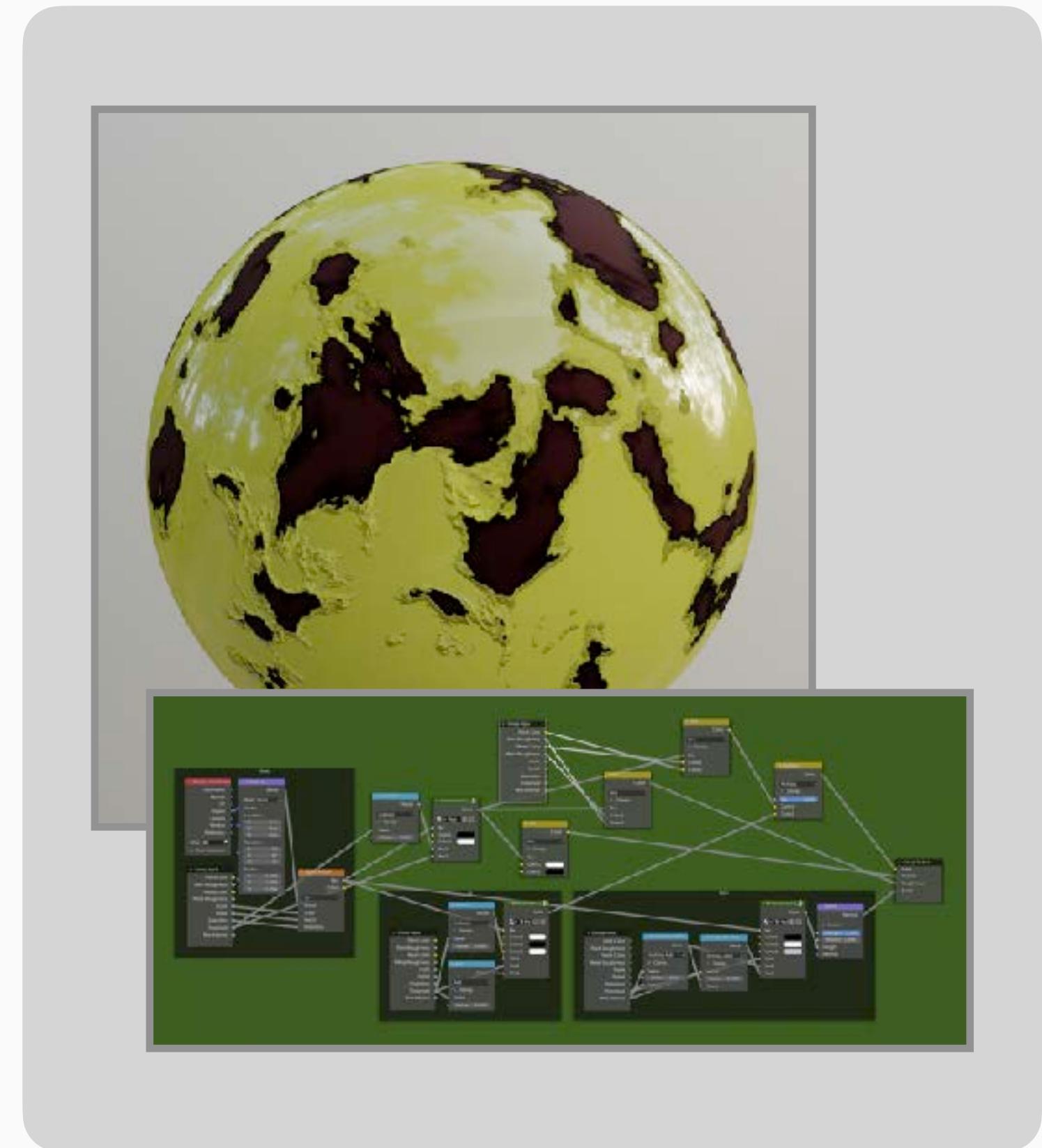
Photo color enhancement



Generative modeling



Procedural texturing

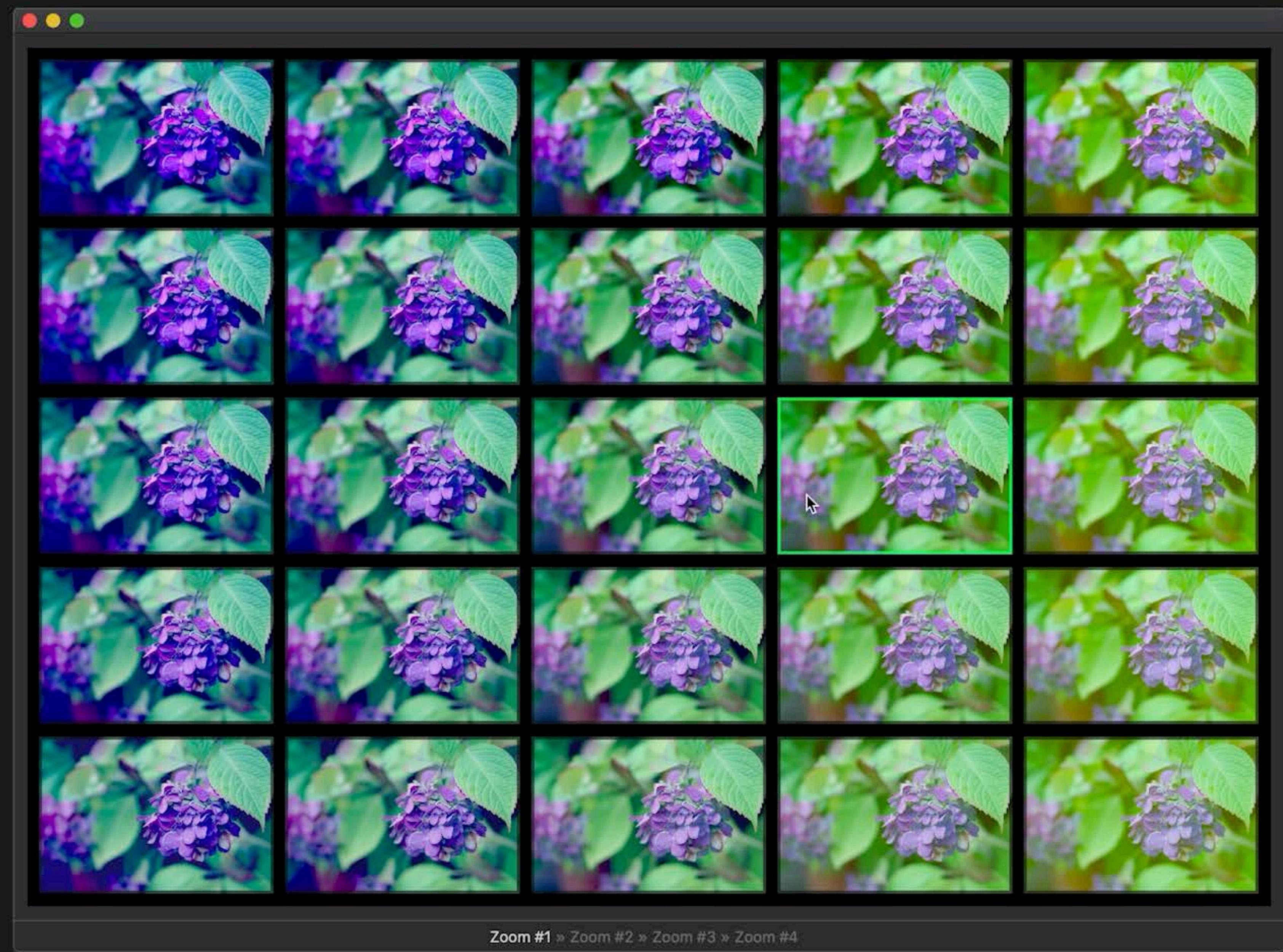


... and many other parametric design scenarios

Photo Color Enhancement (12D)

Brightness, contrast, saturation, shadows (RGB), midtones (RGB), and highlights (RGB)





x1.5 speed



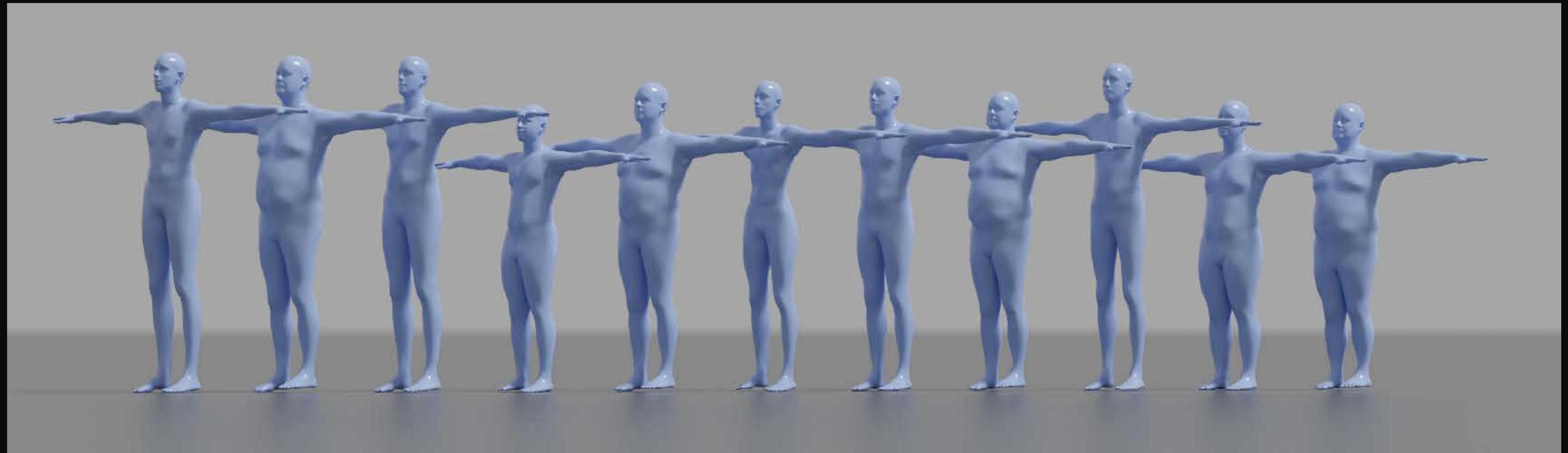
Original photograph

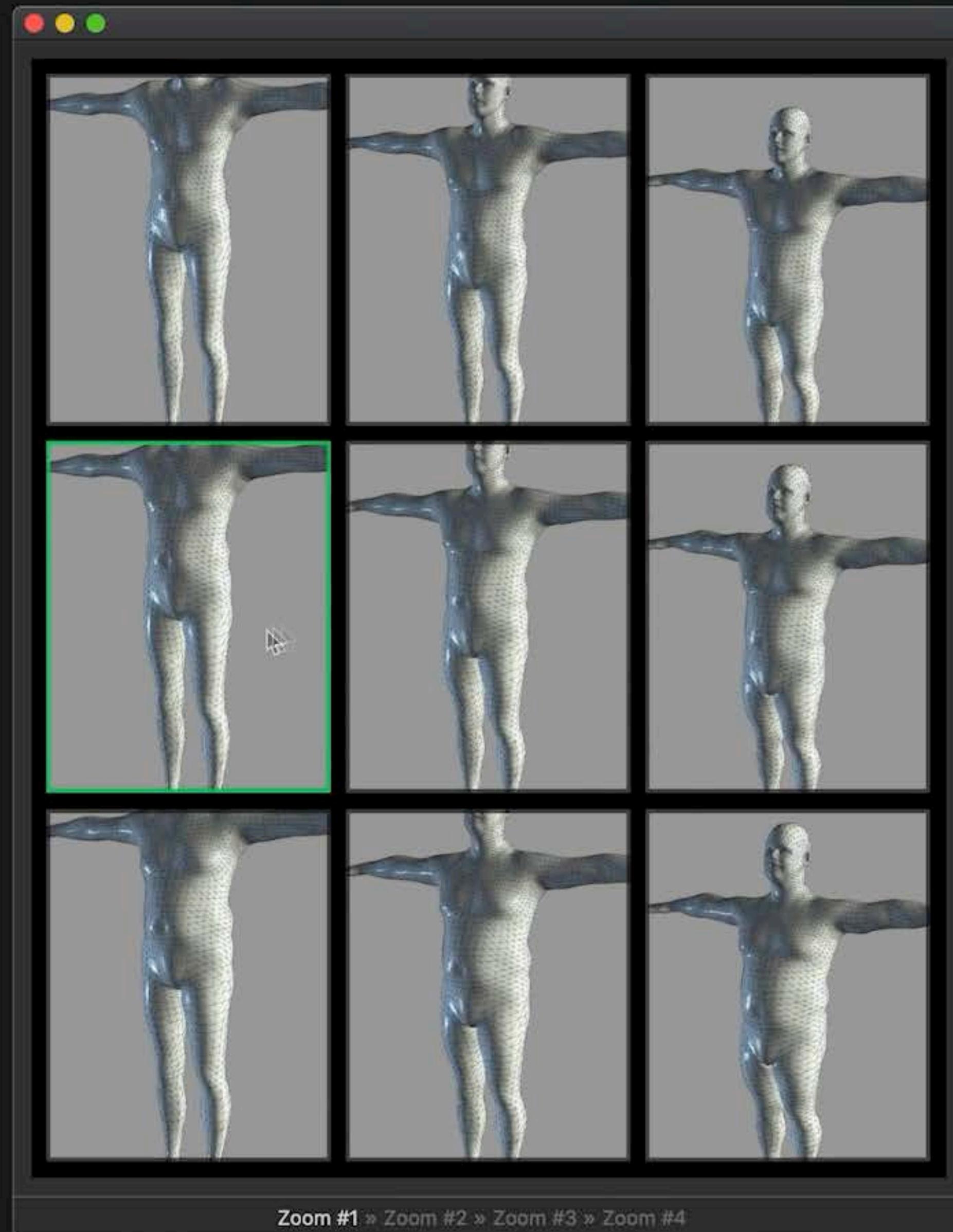


Enhanced photograph
(after 4 iterations)

Body Shaping (10D)

Using the SMPL model [Loper+15] (the first 10 principal components)





Goal: Body shaping from a character description

“He was of medium height, solidly built, wide in the shoulders, thick in the neck, with a jovial heavy-jawed red face [...]”

Dashiell Hammett. 1930. *The Maltese Falcon.*

Zoom #1 » Zoom #2 » Zoom #3 » Zoom #4

x1.5 speed

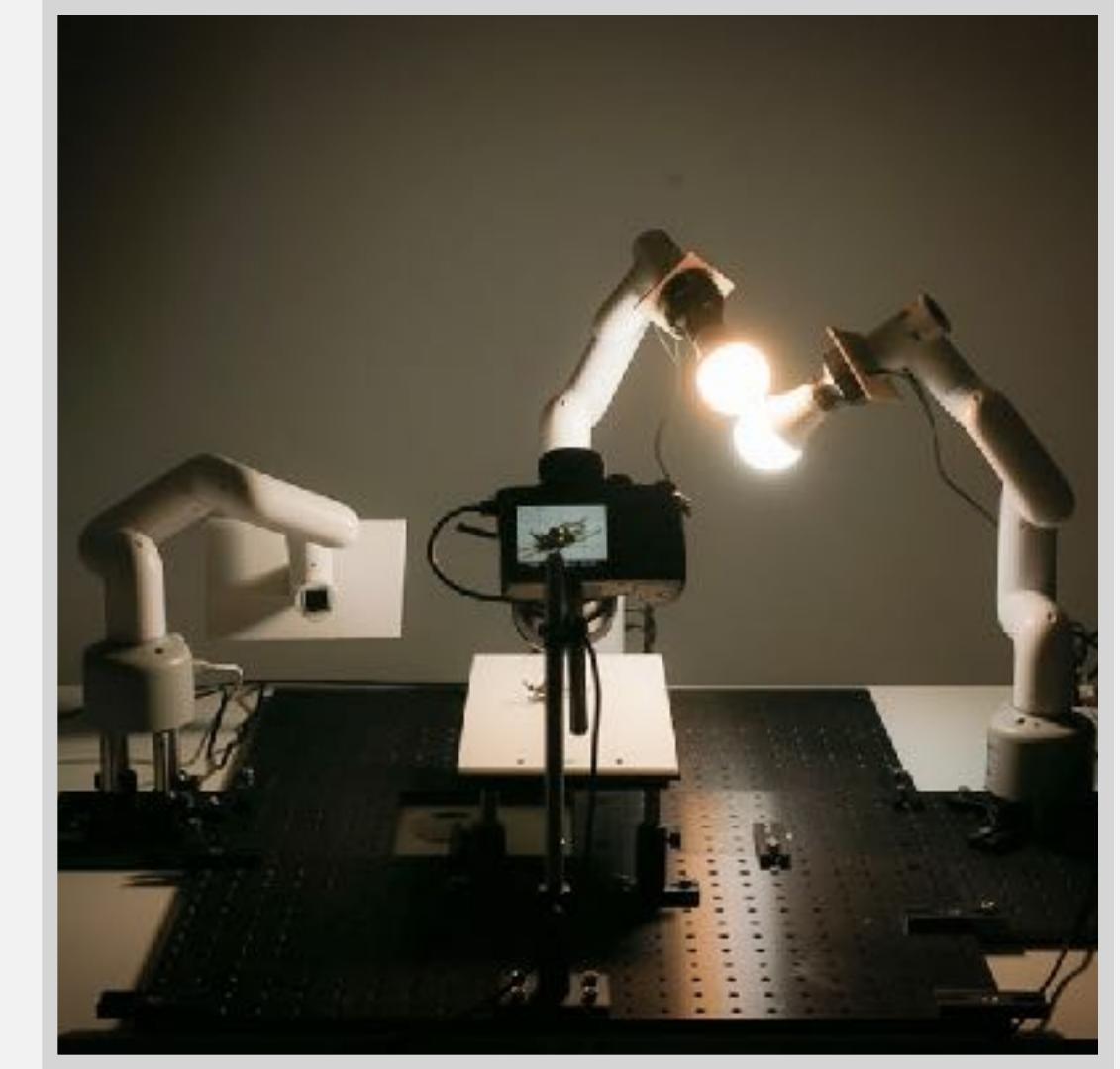
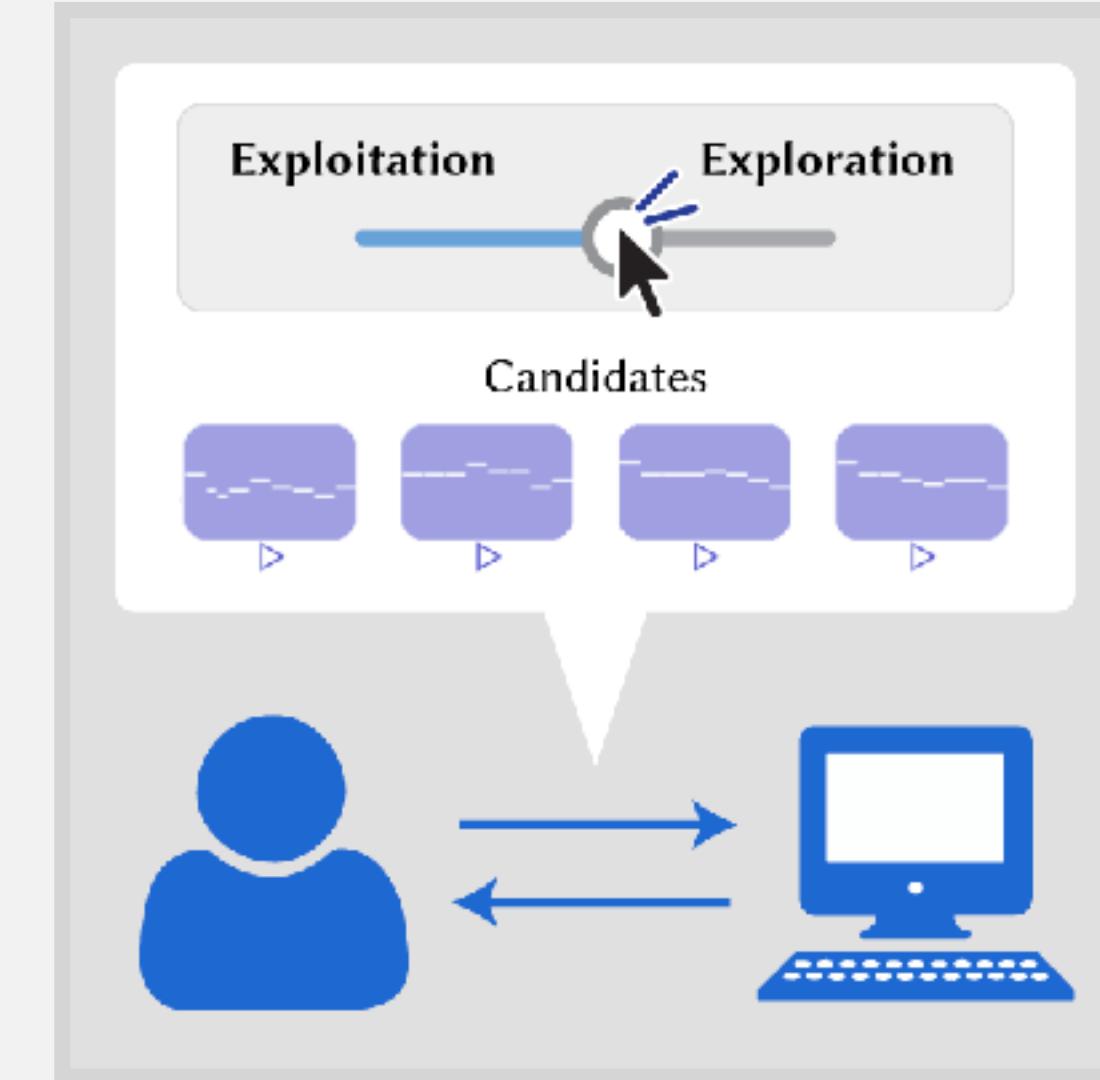
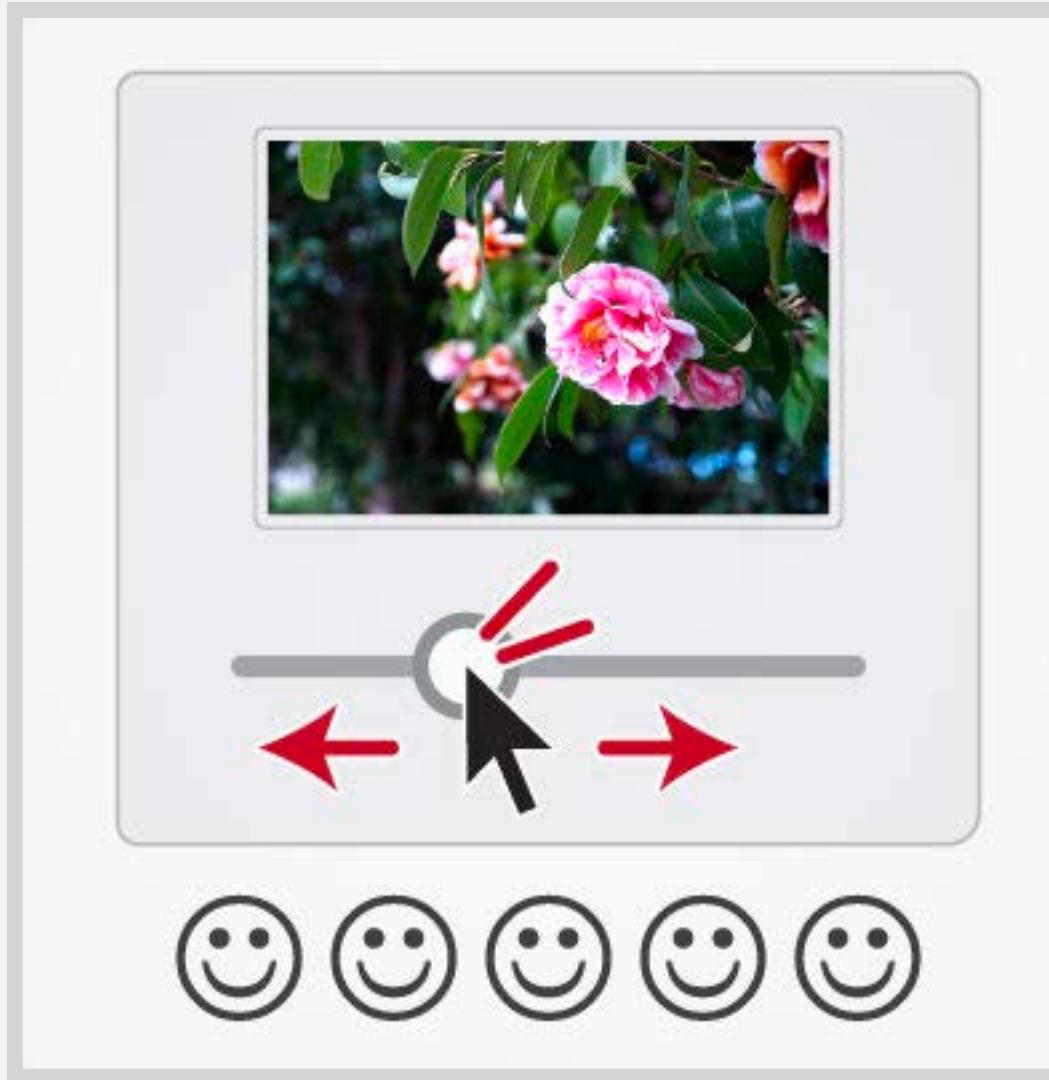
*“He was of medium height, solidly built,
wide in the shoulders, thick in the neck,
with a jovial heavy-jawed red face [...]”*

Dashiell Hammett. 1930. *The Maltese Falcon.*



- User-in-the-Loop最適化を実現
- グリッド状に選択肢を提示するインターフェースを採用することで必要な反復回数を削減
- そのために選好ベイズ最適化 (PBO) を拡張

Human-in-the-Loop選好ベイズ最適化



写真の色調編集や3Dグラフィクス

Koyama+
SIGGRAPH 2017

Koyama+
SIGGRAPH 2020

メロディー生成

Zhou+
IUI 2020

写真撮影時の照明

Yamamoto+
UIST 2022

- 様々なデザインシナリオでその可能性を摸索してきた
- 一方でHuman-in-the-Loopベイズ最適化には課題もある

研究事例 3

BO as Assistant [UIST 2022]



"どちらが好き？"

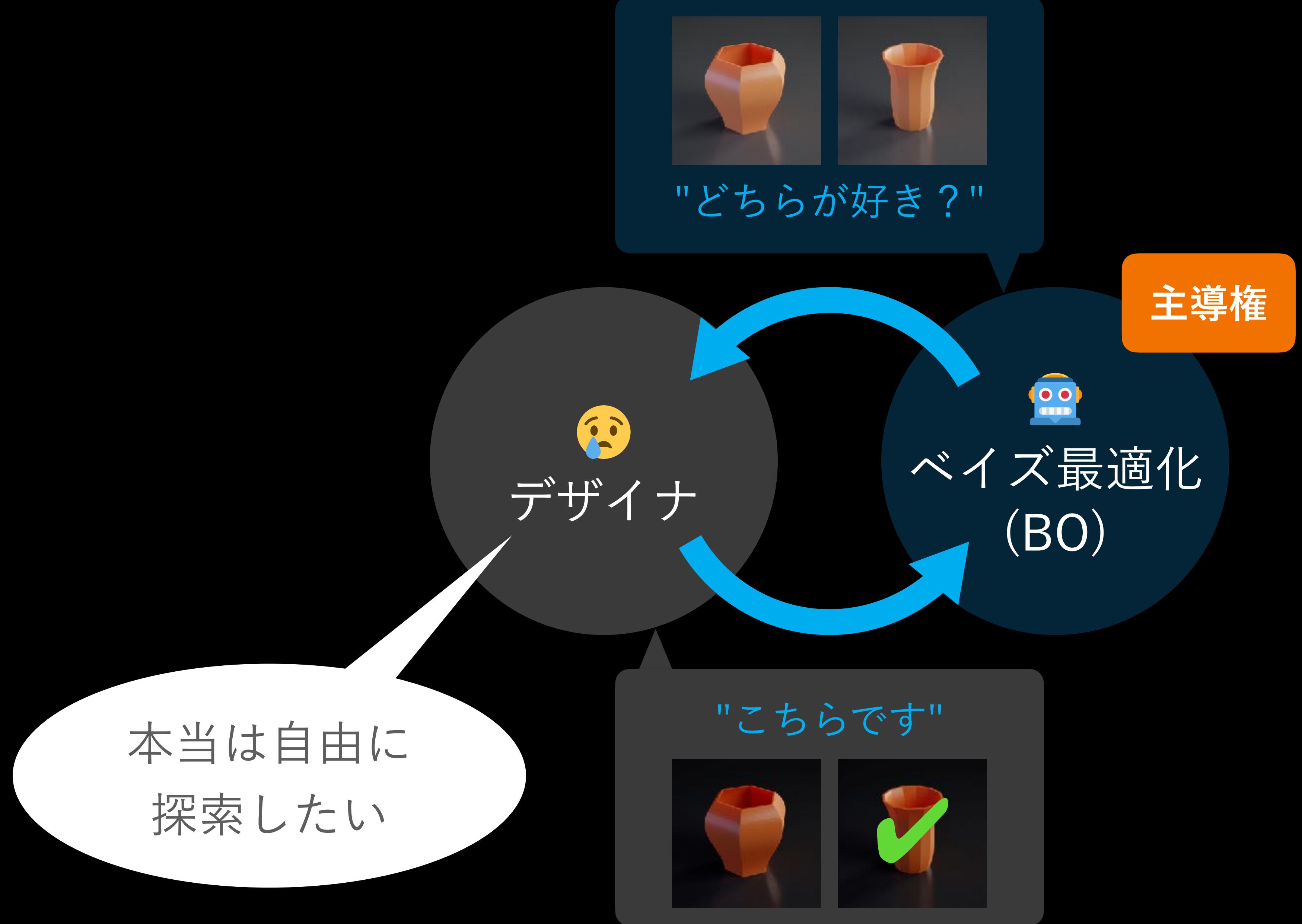
主導権

デザイナ

ベイズ最適化
(BO)

"こちらです"





問題：

デザイナが自由に探索できず、
行為主体感 (agency) や創造性 (creativity) の
低下を招く懸念がある [Chan+, CHI 2022]

本当は自由に
探索したい

[Chan+, CHI 2022] L. Chan et al. 2022.

Investigating Positive and Negative Qualities of
Human-in-the-Loop Optimization for Designing
Interaction Techniques. In Proc. CHI 2022.

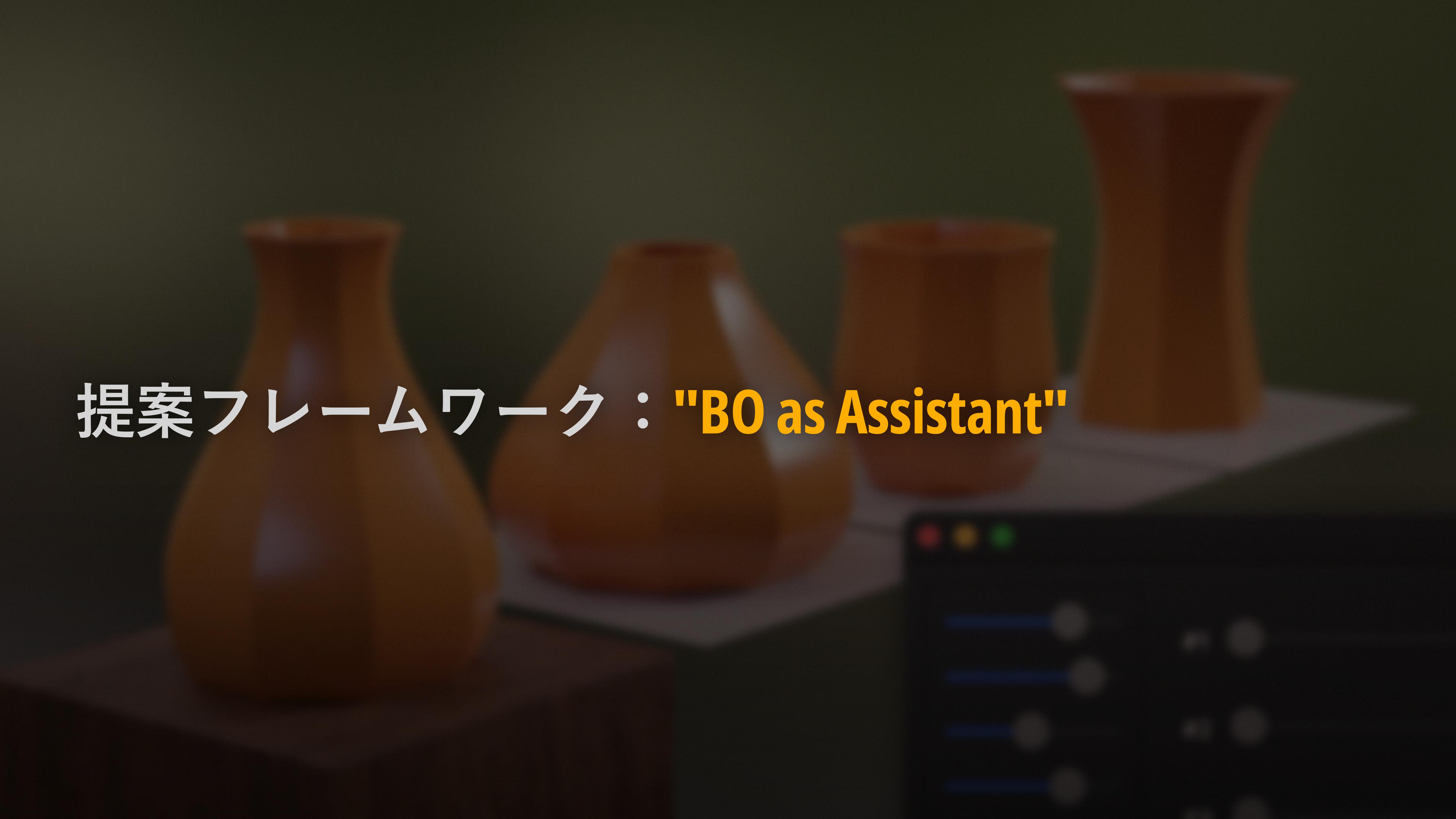


着想：

ベイズ最適化 (BO) のサンプリング戦略の賢さの恩恵を受けつつ、
デザイナが自由にデザイン探索できるようにしたい

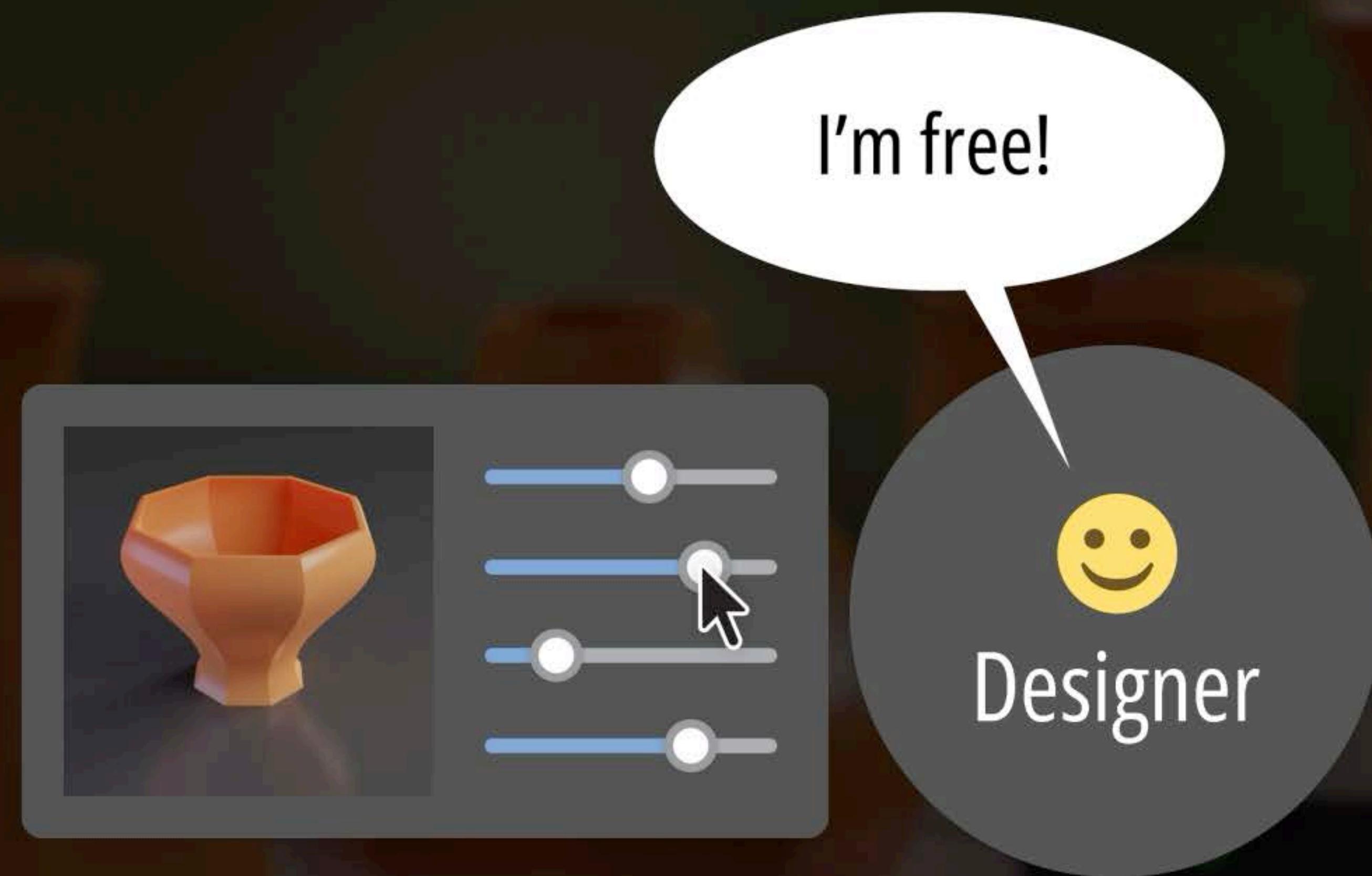


- ベイズ最適化 (BO) を (human-in-the-loopの仕組みとしてでなく)
デザイナの "助手" (assistant) として活用するフレームワークを提案

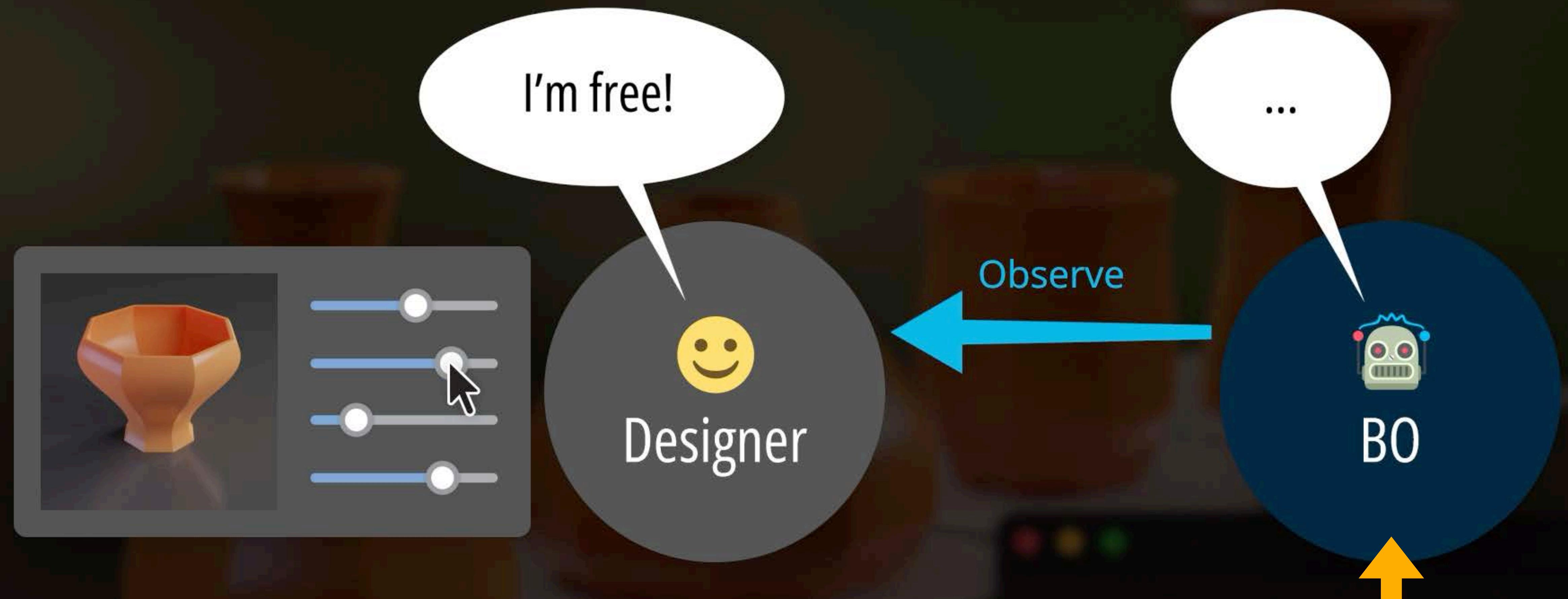


提案フレームワーク："BO as Assistant"

BO as Assistantの場合：

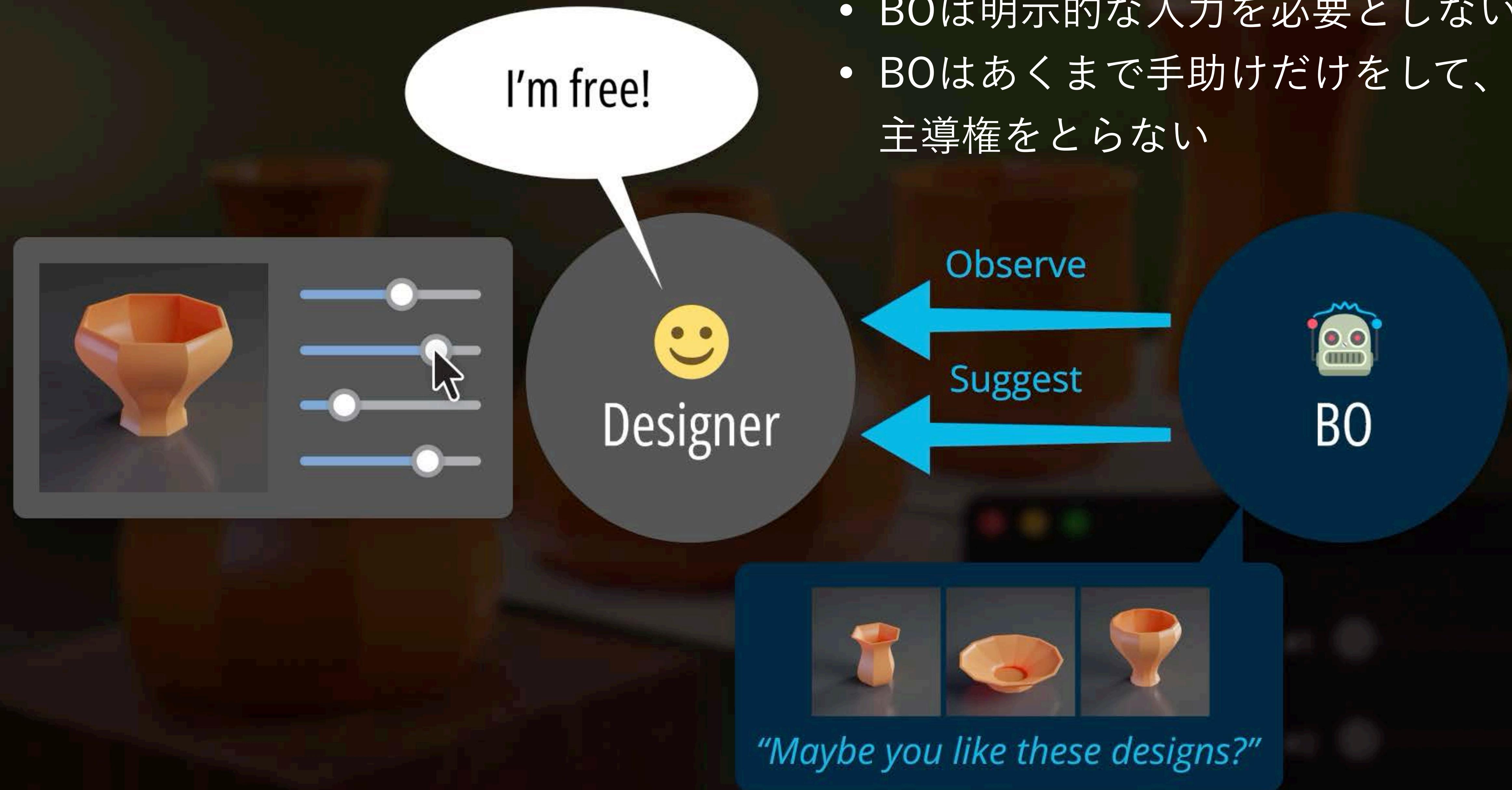


BO as Assistantの場合：

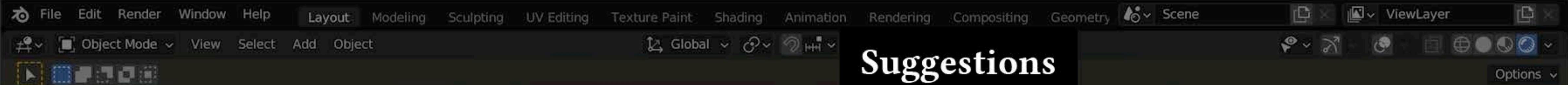


デザイナの好みや意図を（勝手に）学習

BO as Assistantの場合：



procedural-modeling.blend



Parameters:

- Num Sides
- Height
- Bottom Radius
- Bottom Tangent
- Top Radius
- Top Tangent

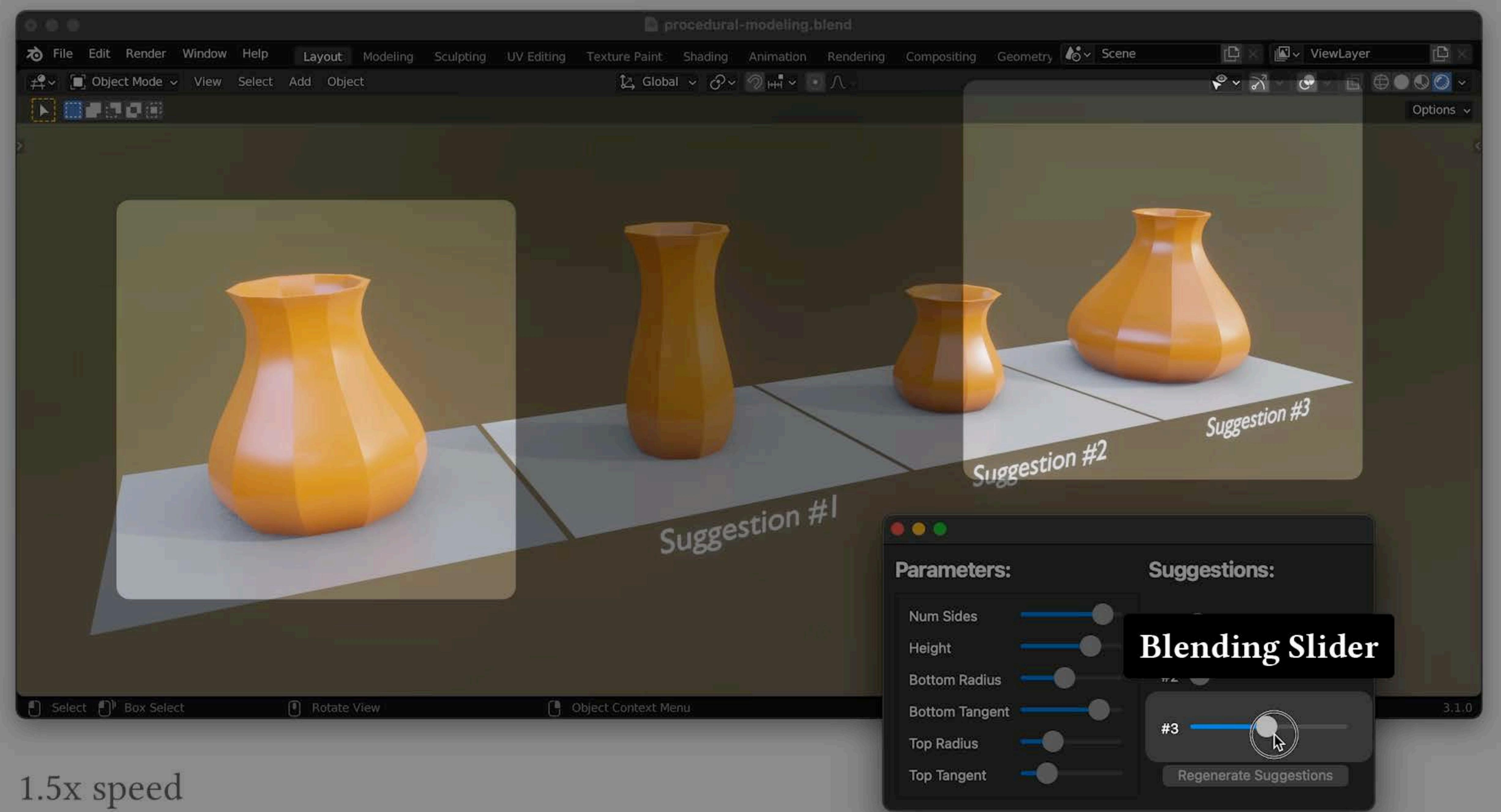
Suggestions:

- #1
- #2
- #3

Regenerate Suggestions

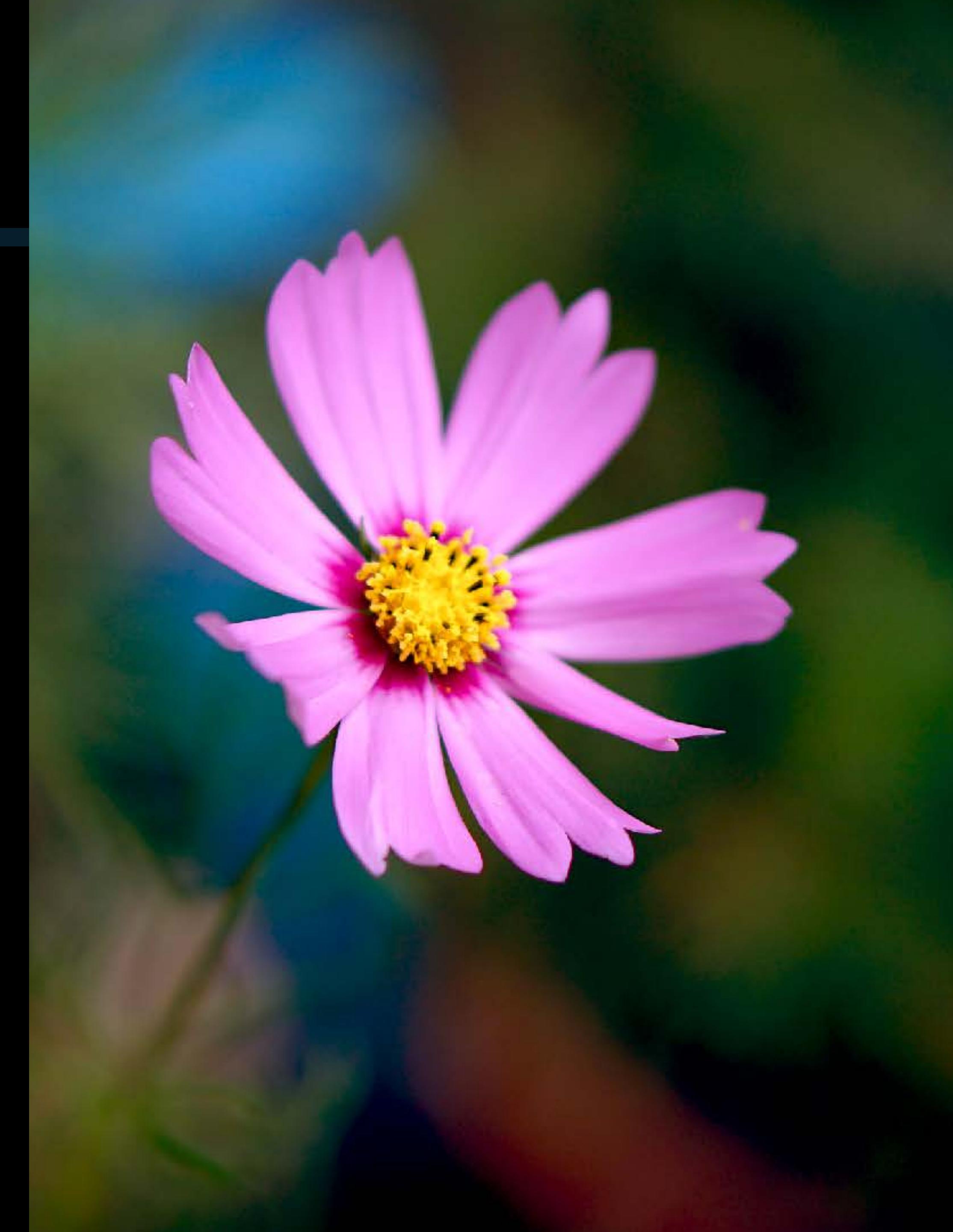
1.5x speed

3.1.0



写真の色調編集

- パラメタ数：12
 - Brightness
 - Contrast
 - Saturation
 - Lift (RGB)
 - Gamma (RGB)
 - Gain (RGB)
- デザイン目標：
写真の見栄えが良くなるようにする



x5

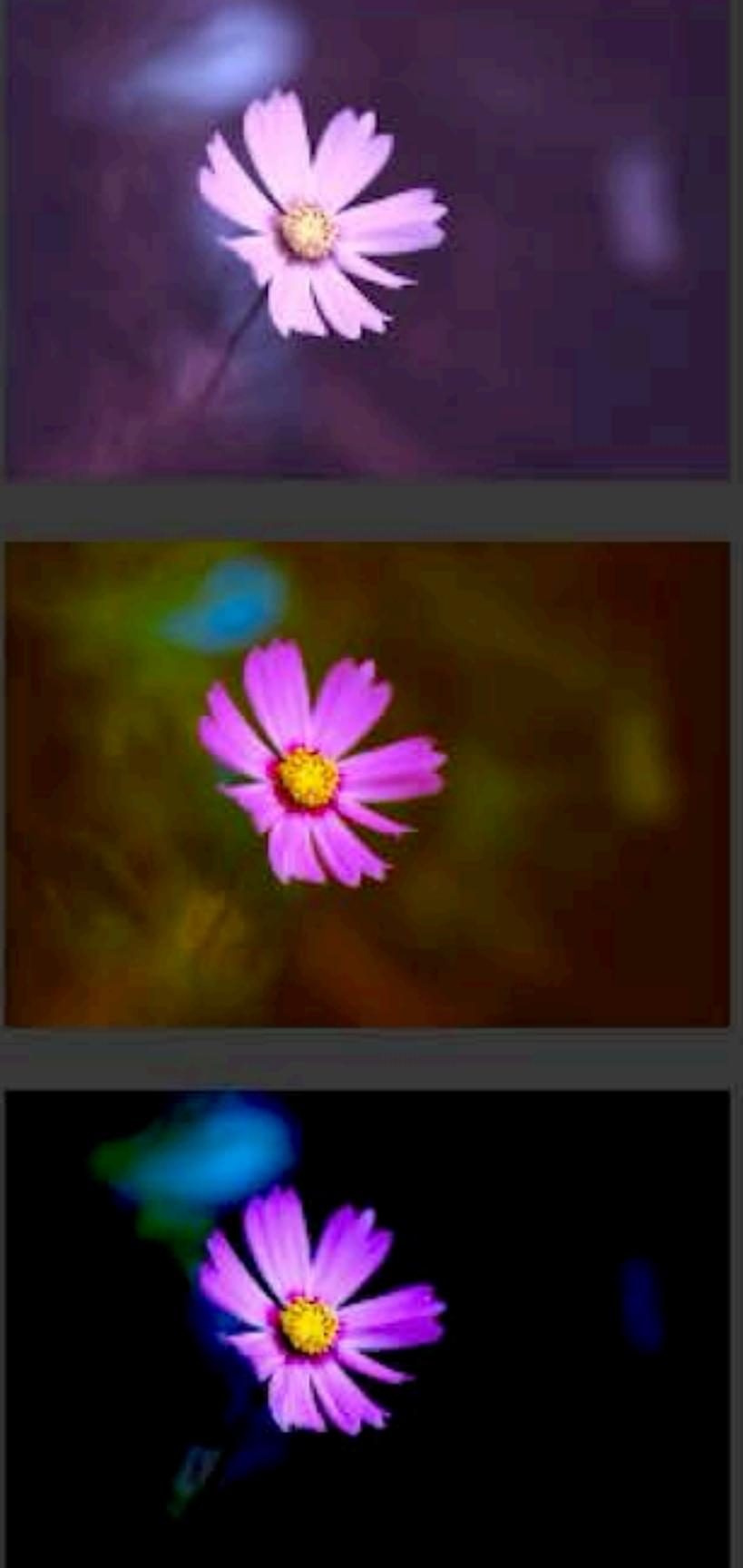
Parameters:

- Brightness
- Contrast
- Saturation
- Lift (R)
- Lift (G)
- Lift (B)
- Gamma (R)
- Gamma (G)
- Gamma (B)
- Gain (R)
- Gain (G)
- Gain (B)

Preview:



Suggestions:



Regenerate Suggestions

プロシージャルマテリアル生成

- パラメタ数：8
 - Threshold
 - Noise Scale
 - Noise Detail
 - Noise Roughness
 - Noise Distortion
 - Ambient Occlusion
 - Bump Strength
 - Peel Boundary Strength
- デザイン目標：
ペイントが剥げている錆びた金属



The 3D model is provided by Bastien Genbrugge under CC BY 4.0 at <https://skfb.ly/6pNQ6>

x5

Suggestion #1 Suggestion #2 Suggestion #3



Parameters:

- Threshold
- Noise Scale
- Noise Detail
- Noise Roughness
- Noise Distortion
- Ambient Occlusion
- Bump Strength
- Peel Boundary Strength

Suggestions:

- #1
- #2
- #3

Regenerate Suggestions

デザイナ

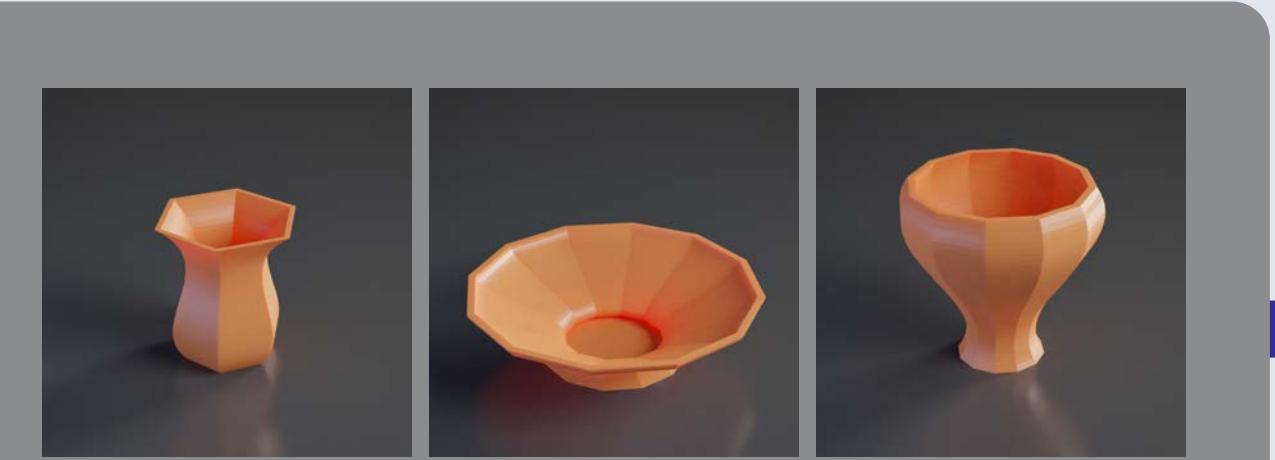
普段通り自由にスライダ操作でデザイン探索を行う



デザイナはデザイン案を採用しても無視しても良い

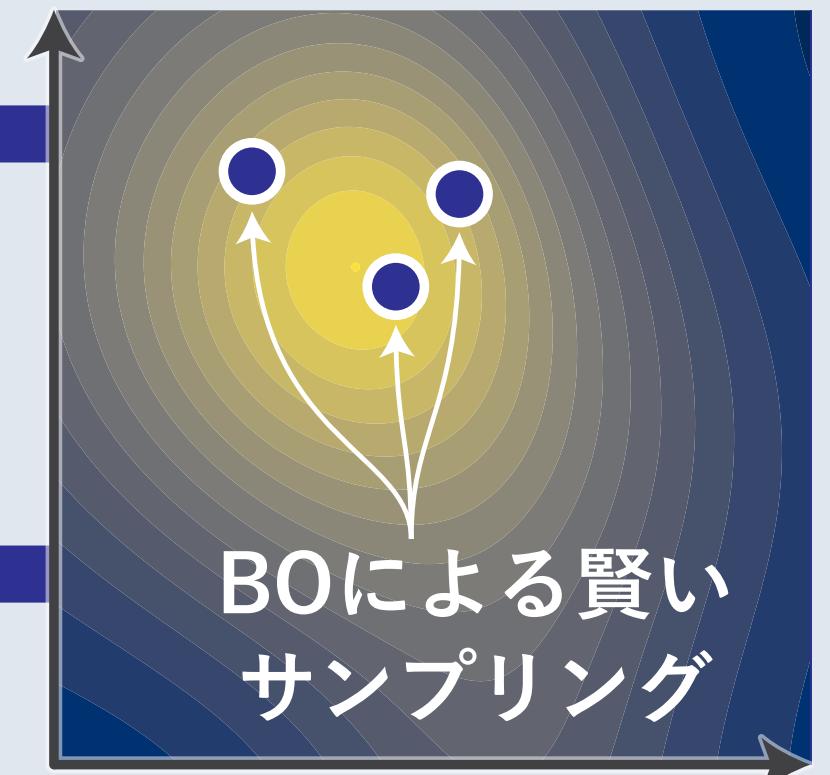
"助手" としてのベイズ最適化 (BO)

(1) スライダ操作を観測



BOが生成したデザイン案

(2) デザイン目標を推定



(3) デザイン案を提示

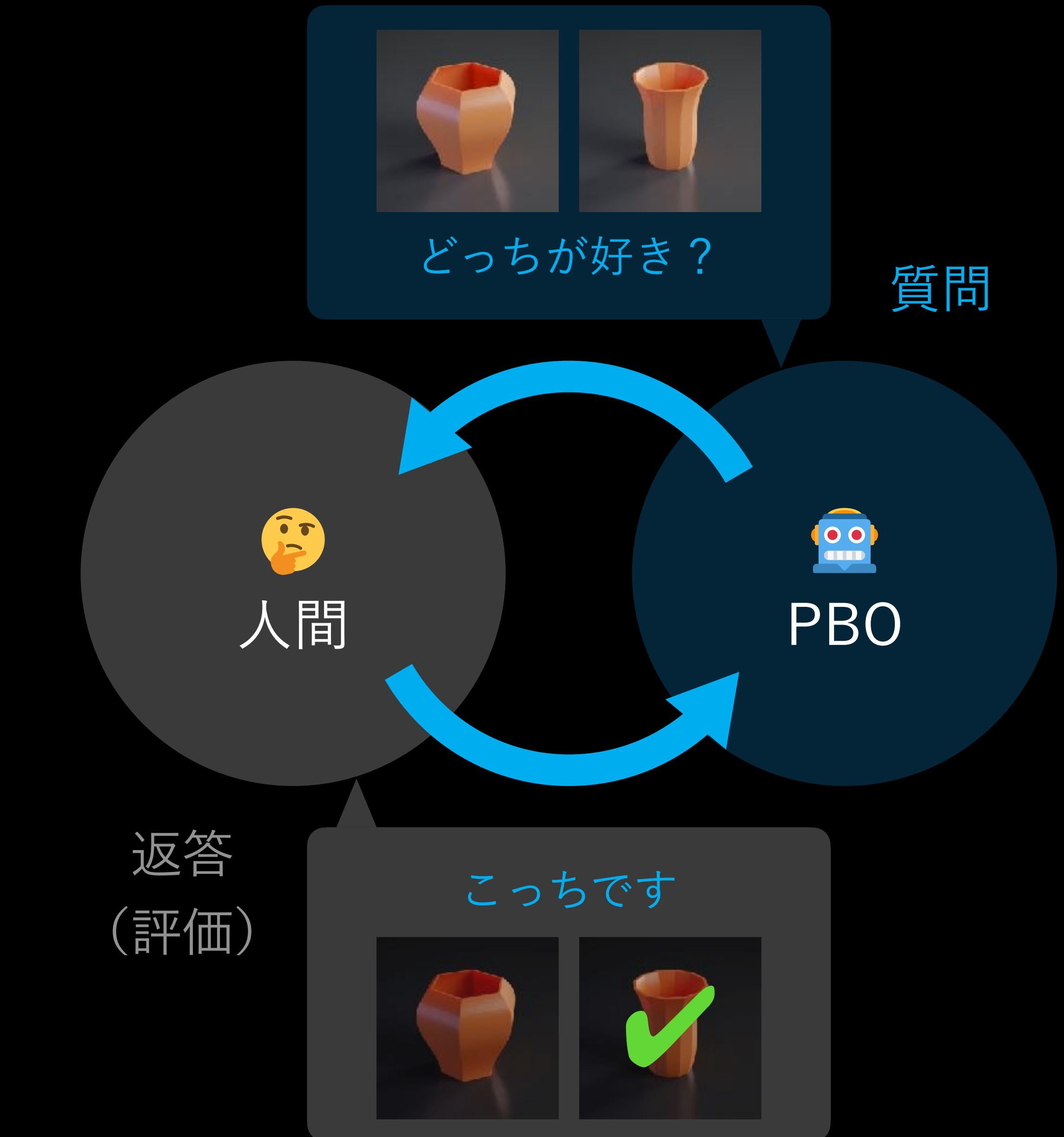
- ベイズ最適化 (BO) を (human-in-the-loopでなく)
デザイナの "助手" (assistant) として活用するインタラクションを提案
- スライダ操作を観測することで好みを学習し、賢くデザイン案を生成する技術
を提案



終わりに まとめと議論

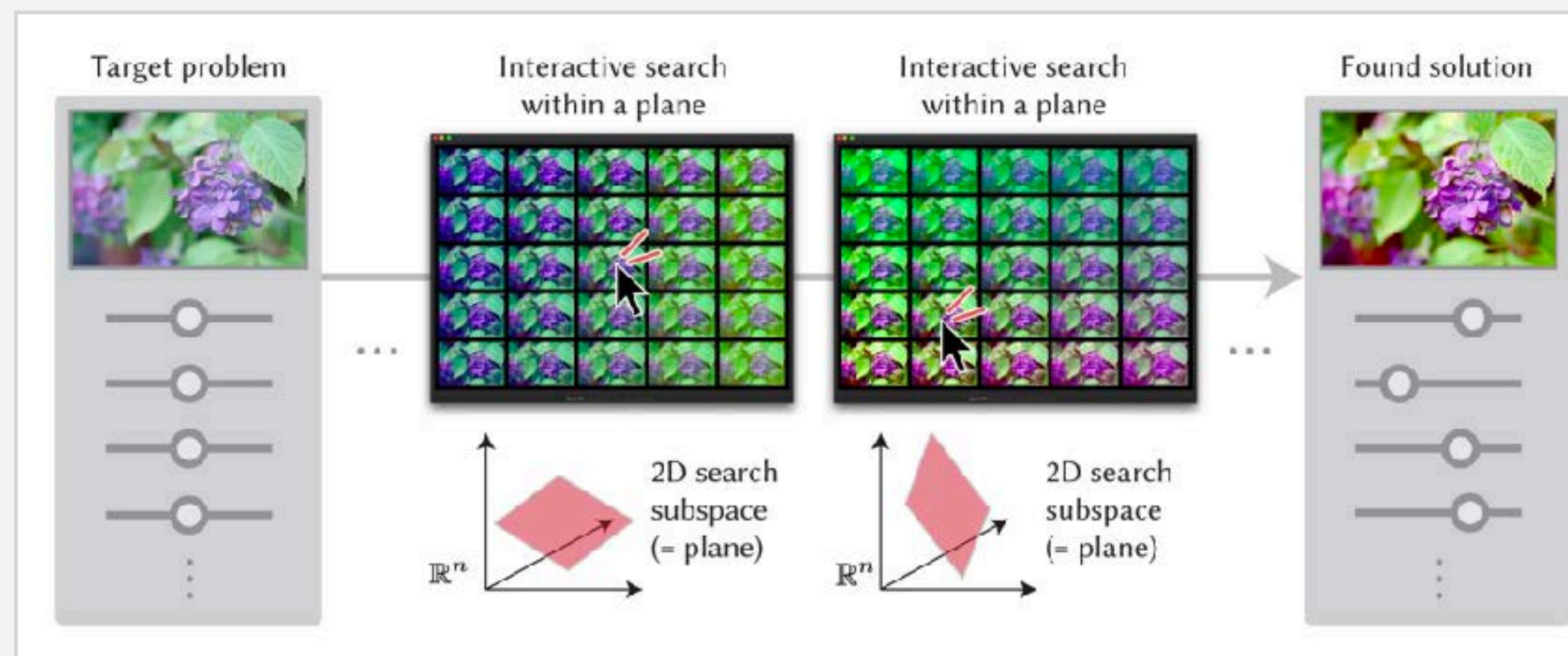
まとめ [1/2]

- **Human-in-the-Loop最適化**
 - 人間の評価が必要な目的関数（好みなど）を対象とする最適化問題を解く上で有効なアプローチ
- **選好ベイズ最適化** Preferential Bayesian Optimization (PBO) が役立つ
 - 相対比較データから好みを推定して最適化を実行
 - 少ない反復回数で解を見つける性質

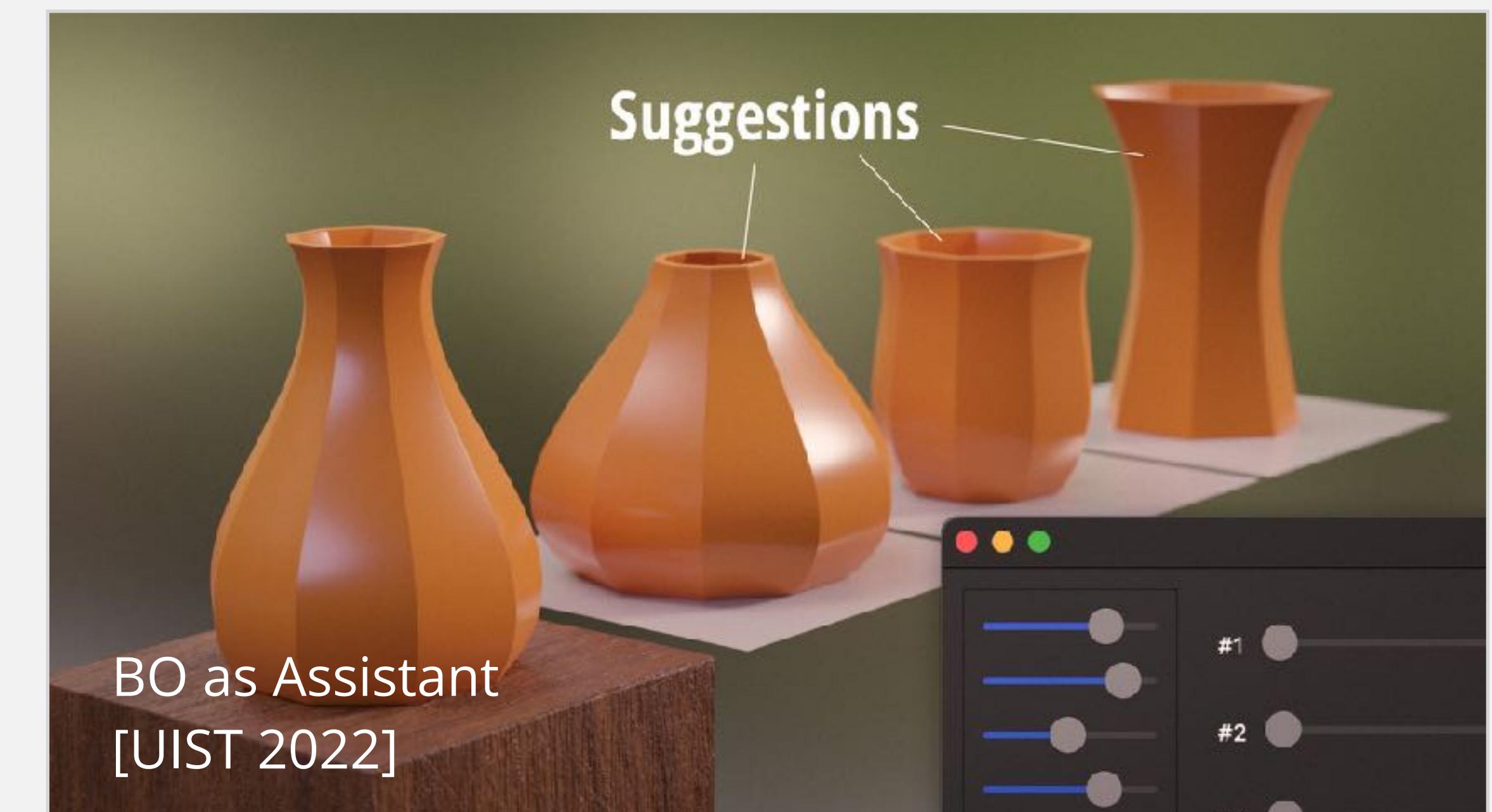


まとめ [2/2]

- アルゴリズムとインタフェース両側面から工夫することが、効率的な Human-in-the-Loop最適化を実現する上で重要 [SIGGRAPH 2017; 2020]
- Human-in-the-Loop最適化でないインタラクション設計として、デザインを提案してくれる "助手" としてベイズ最適化技術を活用可能 [UIST 2022]



Sequential Gallery
[SIGGRAPH 2020]

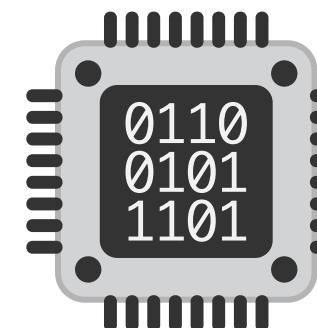


議論：Human-AI Collaborationの観点



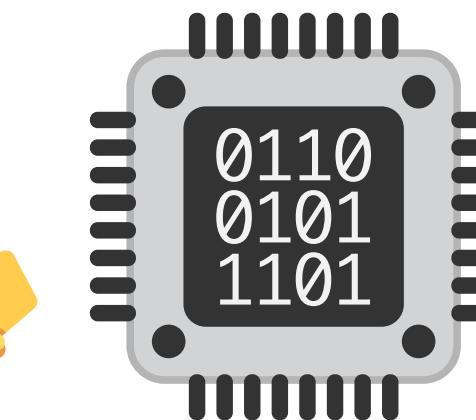
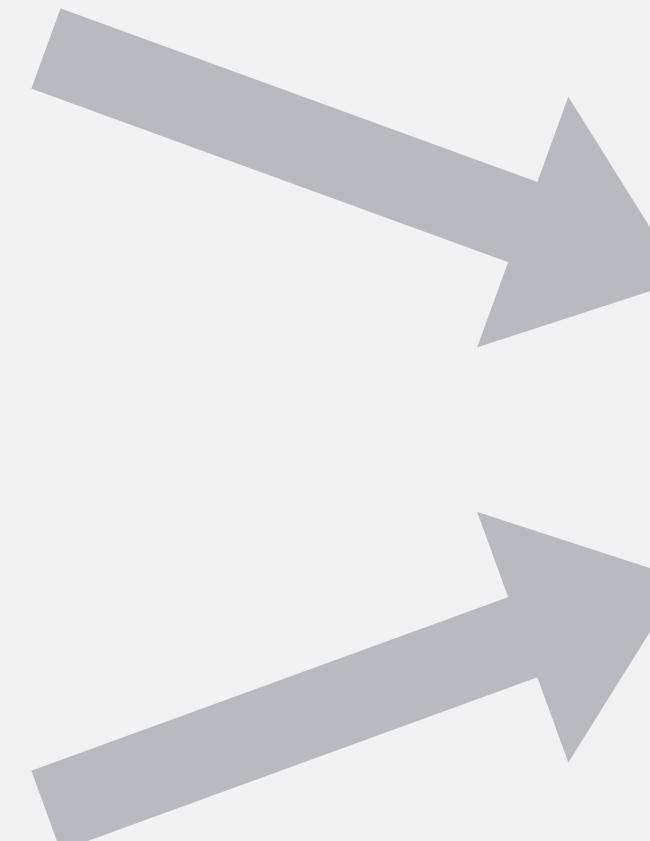
Human Only

経験と勘による属人的な戦略と思考に依存し、計算効率も悪い



AI Only

事前に定義された問題を扱い、人間の柔軟な判断を取り込めない



Human-AI Collaboration

数理技術の持つ合理性・効率性を活かしながら、人間とAIとが協調して柔軟な問題解決・意思決定を行う

- 人工知能技術を実問題に対し効果的に適用するために必要な観点であり、学術的注目も高まっている
- 選好ベイズ最適化によるインタラクションは設計変数を効率的に決定するhuman-AI collaborationの汎用手法の一つとみなせる

Co-Authors



Daisuke
Sakamoto



Issei
Sato



Takeo
Igarashi



Masataka
Goto