



# Artificial Intelligence & Digital Reality

## Do we need a "CERN for AI"

**Prof. Dr.-Ing. Philipp Slusallek**

German Research Center for Artificial Intelligence (DFKI)

Research Area: Agents and Simulated Reality

Excellence Cluster Multimodal Computing and Interaction (MMCI)

Intel Visual Computing Institute (IVCI)

Saarland University

# Overview



- Background on DFKI
- Digital Reality
- Digital Reality for Autonomous Driving
- AI Research Environment in Germany and EU
- Conclusions

# German Research Center for Artificial Intelligence (DFKI)



- **Motto**

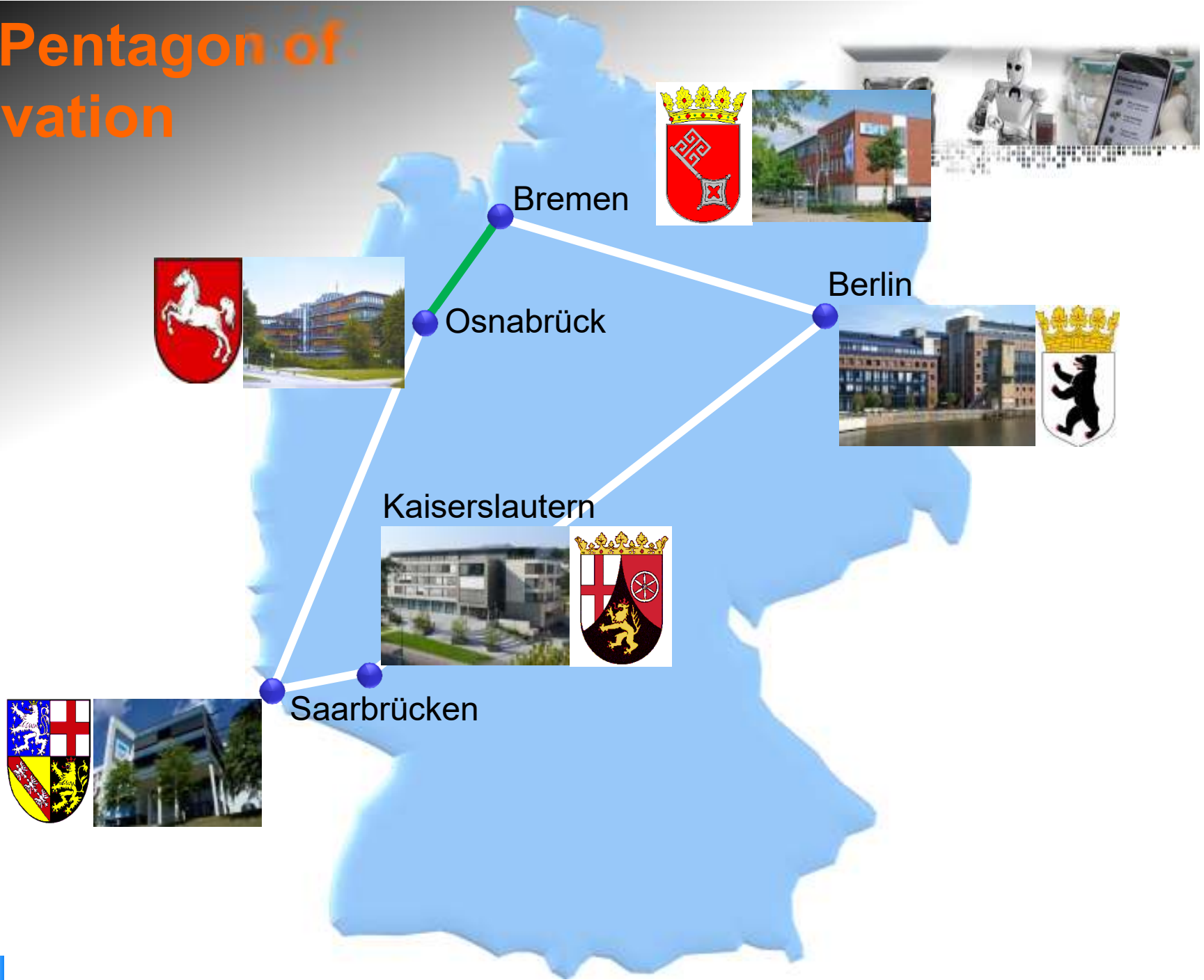
- „Computer with Eyes, Ears, and Common Sense“

- **Overview**

- Largest AI research center worldwide (founded in 1988)
  - Germany’s leading research center for innovative SW technologies
  - 5 sites in Germany
    - Saarbrücken, Bremen, Kaiserslautern; Berlin, Osnabrück
  - 18 research areas, 10 competence centers, 7 living labs
  - More than 510 employees (>900 with research assistants)
  - Budget of more than 44 M€ (2017)
  - More than 80 spin-offs



# The Pentagon of Innovation



# DFKI is a Joint Venture of:



Saarland

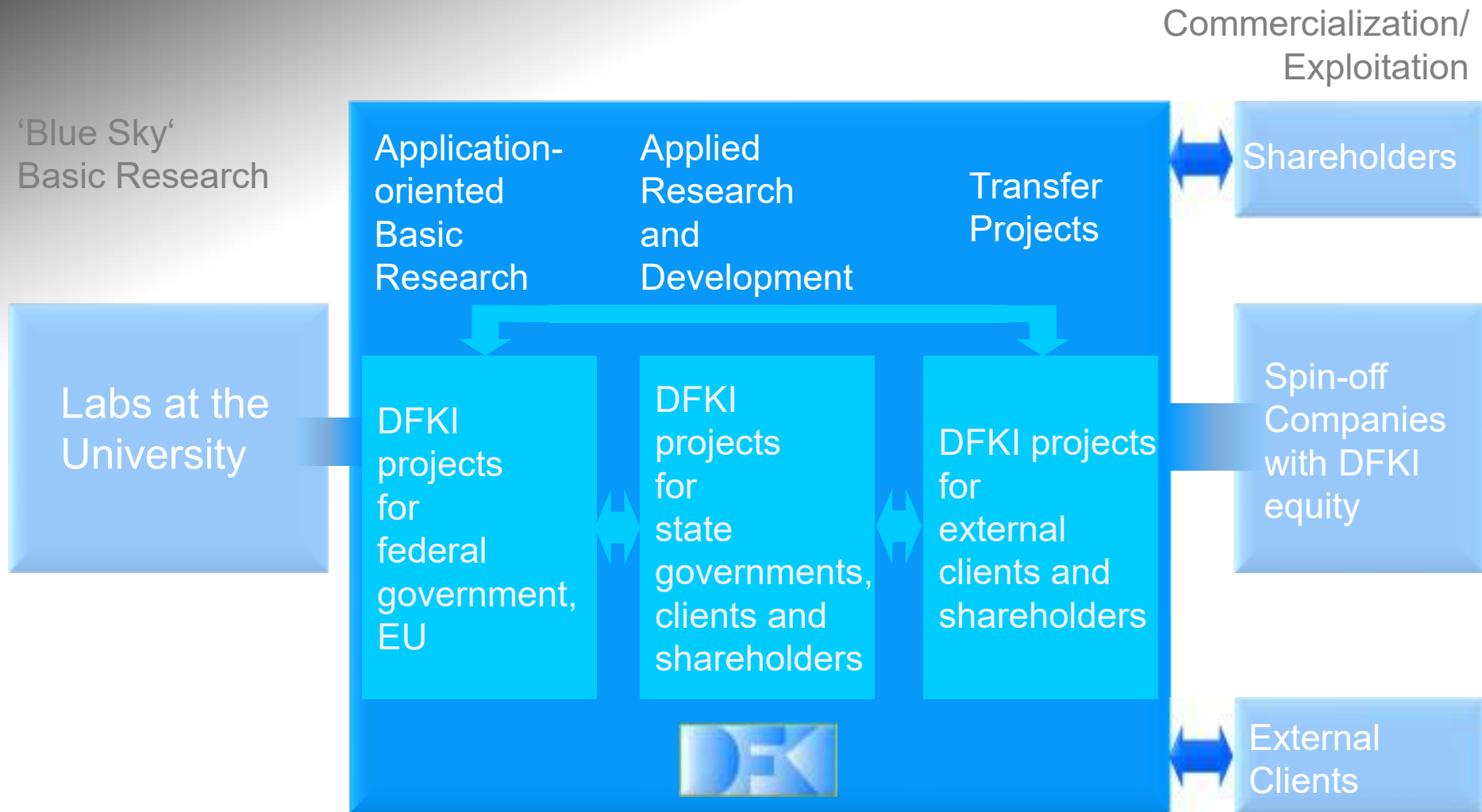


Rhineland-Palatinate

Bremen



# DFKI Covers the Complete Innovation Cycle



# Agents & Simulated Reality: AI & Graphics & HPC & Security



**Scientific Director**  
Philipp Slusallek





## Knowledge- and Technology Transfer

<b>VisCenter</b> Georg Demme	<b>Strategic Relations</b> Hilko Hoffmann	<b>SW-Engineering &amp; Organization</b> Georg Demme
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## Application Domains

<b>Autonomous Driving</b> Christian Müller	<b>Computational Sciences</b> Tim Dahmen	<b>Industrie 4.0</b> Ingo Zinnikus	<b>High-Performance Computing</b> Richard Membarth	<b>Smart Environments</b> Hilko Hoffmann
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## Research: Topics & Teams

<b>Multi-agent Systems</b> Klaus Fischer	<b>Intelligent Information Systems</b> Matthias Klusch	<b>Linked Data Representations</b> René Schubotz	<b>Autonomous Driving</b> Christian Müller
<b>Computational 3D Imaging</b> Tim Dahmen	<b>High-Performance Graphics &amp; Computing</b> Richard Membarth	<b>Smart System Security</b> Andreas Nonnengart	<b>Behavior, Interaction &amp; Visualization</b> Georg Demme
 <b>Survivable Systems and Services</b> Philipp Slusallek	 <b>Distributed Realistic Graphics</b> Philipp Slusallek	 <b>Large-Scale Virtual Environments</b> Philipp Slusallek	 <b>Visual Computing</b> Philipp Slusallek



Flexible Production Control  
Using Multiagent Systems



Verification and Secure Systems  
(BSI-certified Evaluation Center)

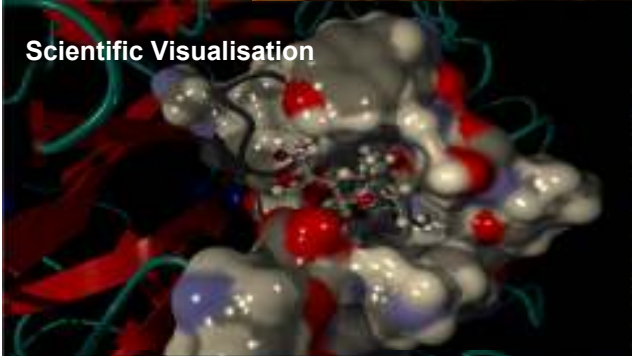


Physically-Based Image Synthese



# ASR Research Topics

Scientific Visualisation



GIS and Geo Visualization



Reconstruction of Cultural Heritage



Future City Planning and Management



Large 3D Models and Environments



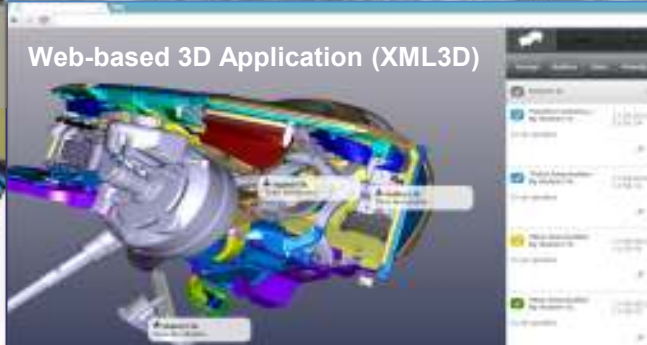
Large Visualization Systems



Intelligent Human Simulation in Production



Web-based 3D Application (XML3D)

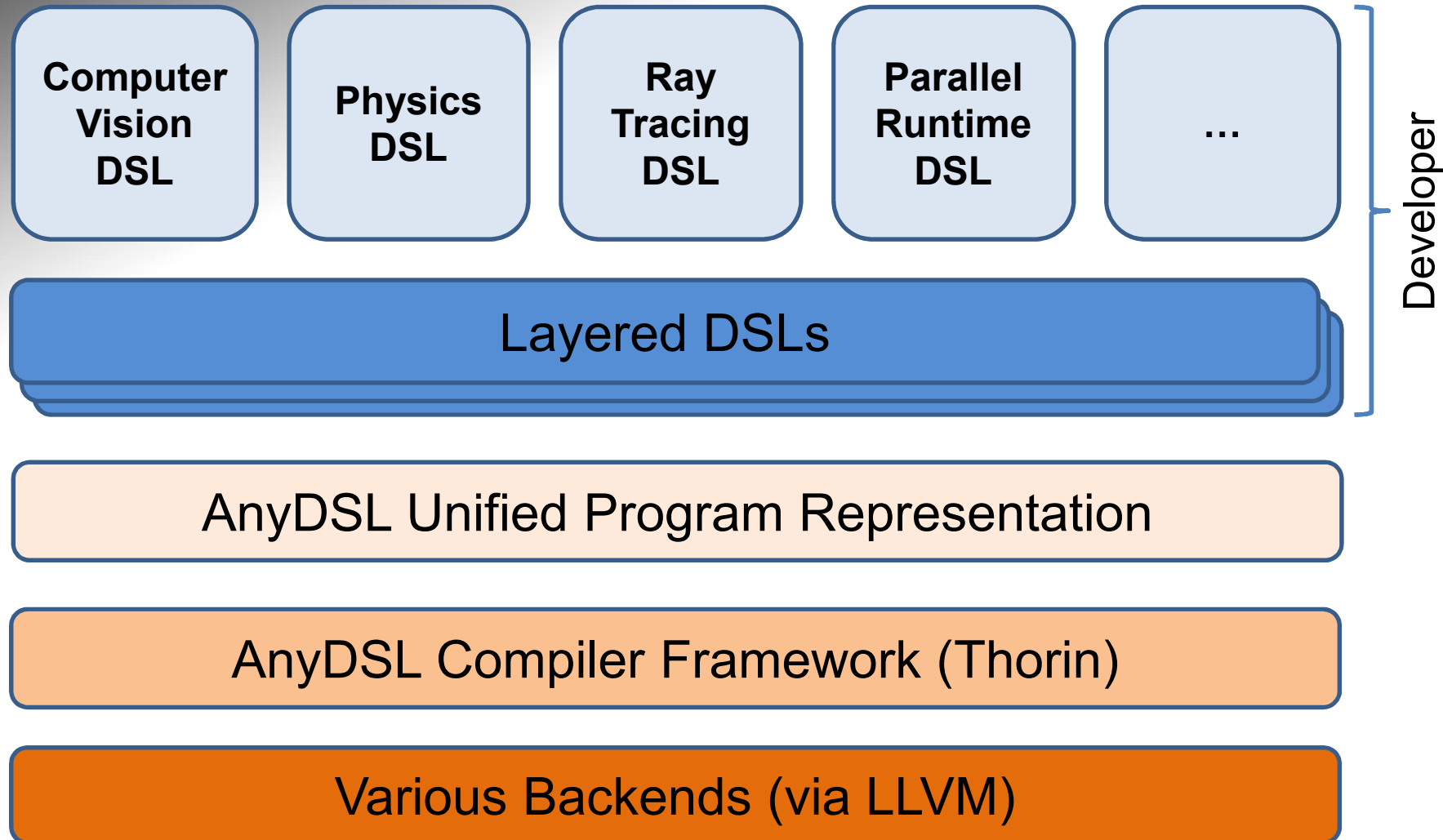


Distributed Visualization on the Internet





# AnyDSL Compiler Framework



# Intelligent Human Simulation, e.g. in Production Environments





# Collaborative Robotics and Simulated Reality





# Autonomous Driving: Training using Synthetic Sensor Data





# Digital Reality: Using Synthetic Data to Train Autonomous Systems

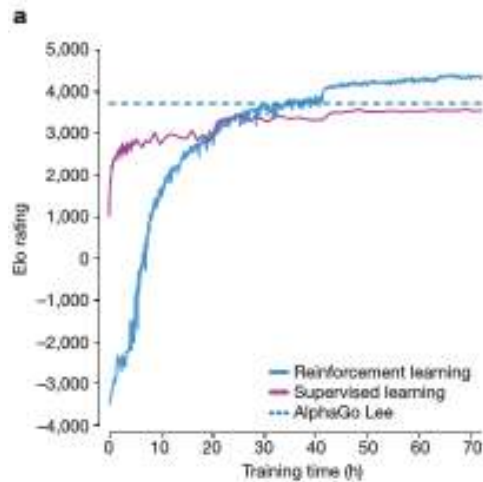




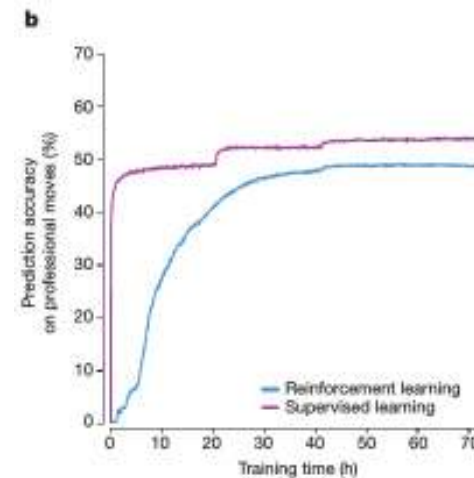
# Playing Go – From Scratch



- Paper from Google DeepMind (Nov 2017, in Nature)
  - Given: Rules + Deep-Learning + Simulation
  - Training via Reinforcement-Learning



Quality of Gameplay



Prediction of Human Moves

- But in reality we do not know the (complex) rules!!



# Autonomous Driving: The Problem



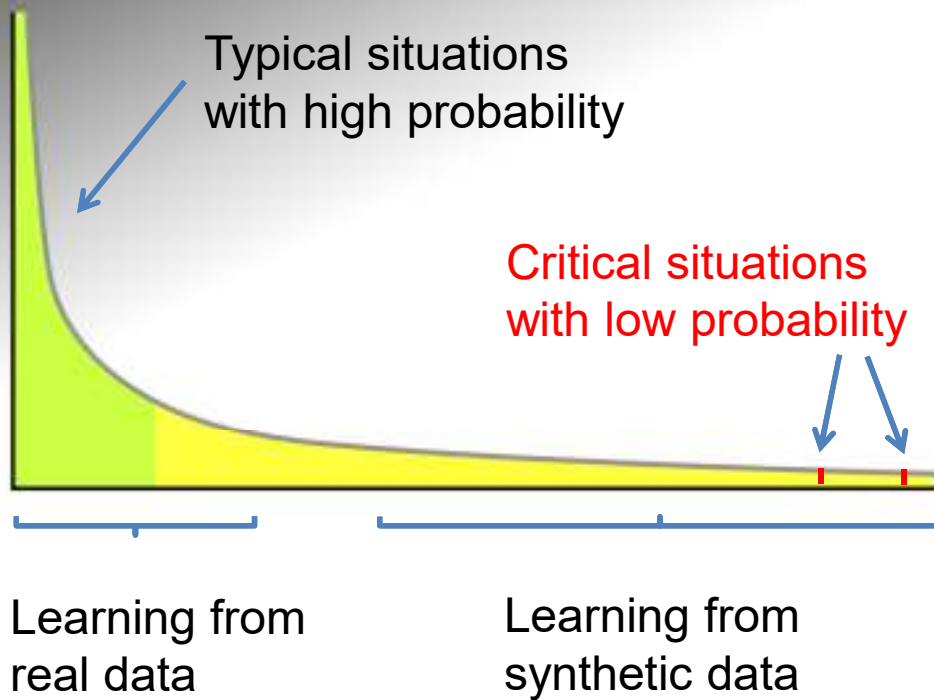
- **Our World is extremely complex**
  - Geometry, Appearance, Motion, Weather, Environment, ...
- **Systems must make accurate and reliable decisions**
  - Especially in *Critical Situations*
  - Increasingly making use of (deep) machine learning
- **Learning of critical situations is essentially impossible**
  - Too little data even for “normal” situations
  - Critical situations rarely happen in reality – per definition!
  - Extremely high-dimensional models

➔ **Goal: Scalable Learning from *synthetic* input data**

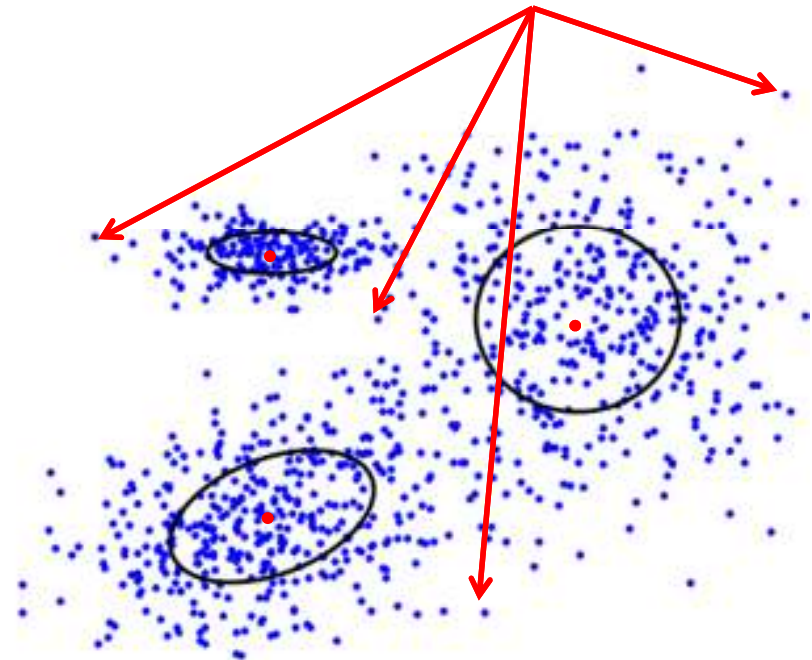
- Continuous benchmarking & validation (“Virtual Crash-Test”)



# Autonomous Driving: The Problem



Goal: Validation of correct behavior by covering high variability of input data

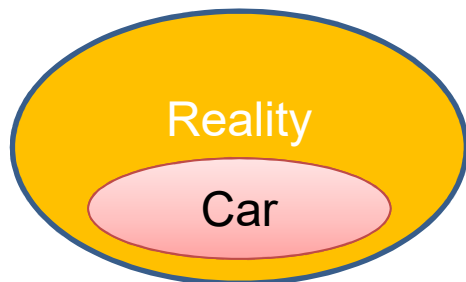


## Learning for Long-Tail Distributions



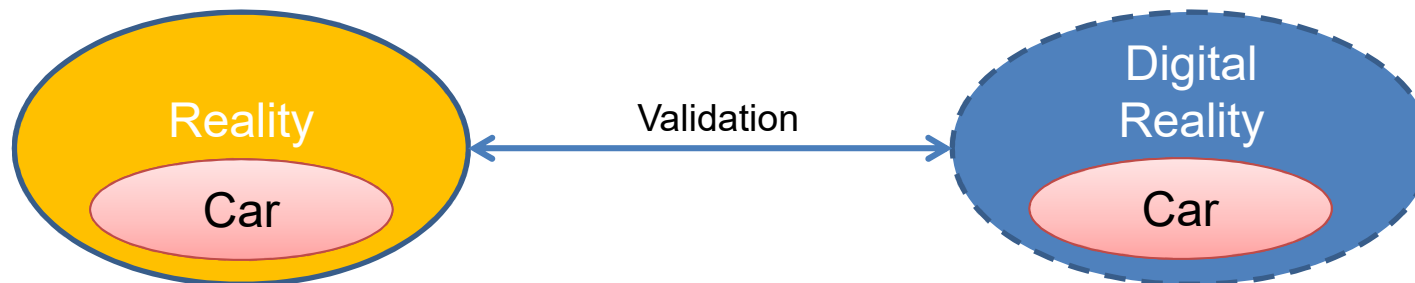
# Reality

- **Training and Validation in Reality (e.g. Driving)**
  - Difficult, costly, and non-scalable



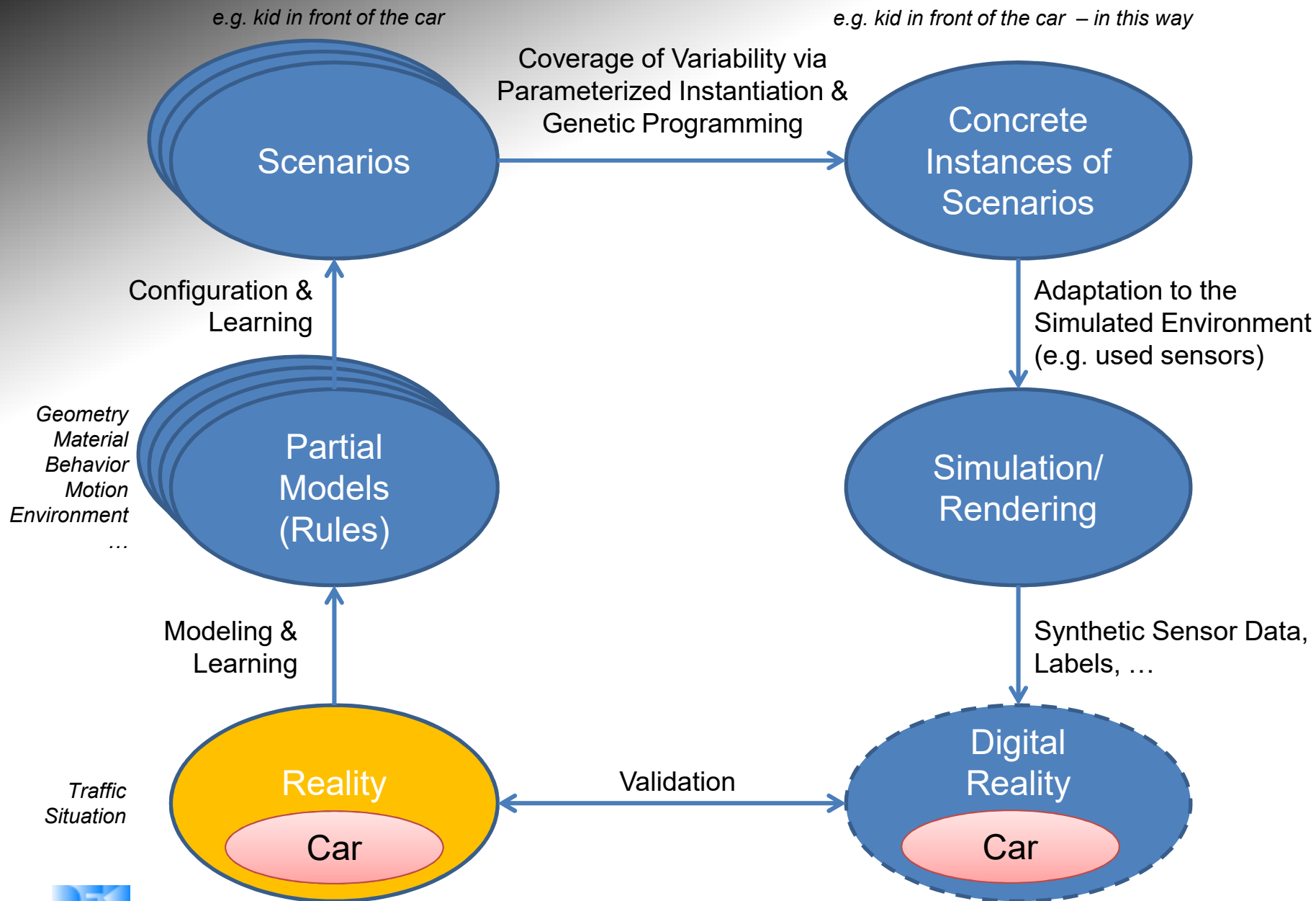
# Digital Reality

- **Training and Validation in the *Digital Reality***
  - Arbitrarily scalable (given the right platform)
  - But: Where to get the models and the training data from?

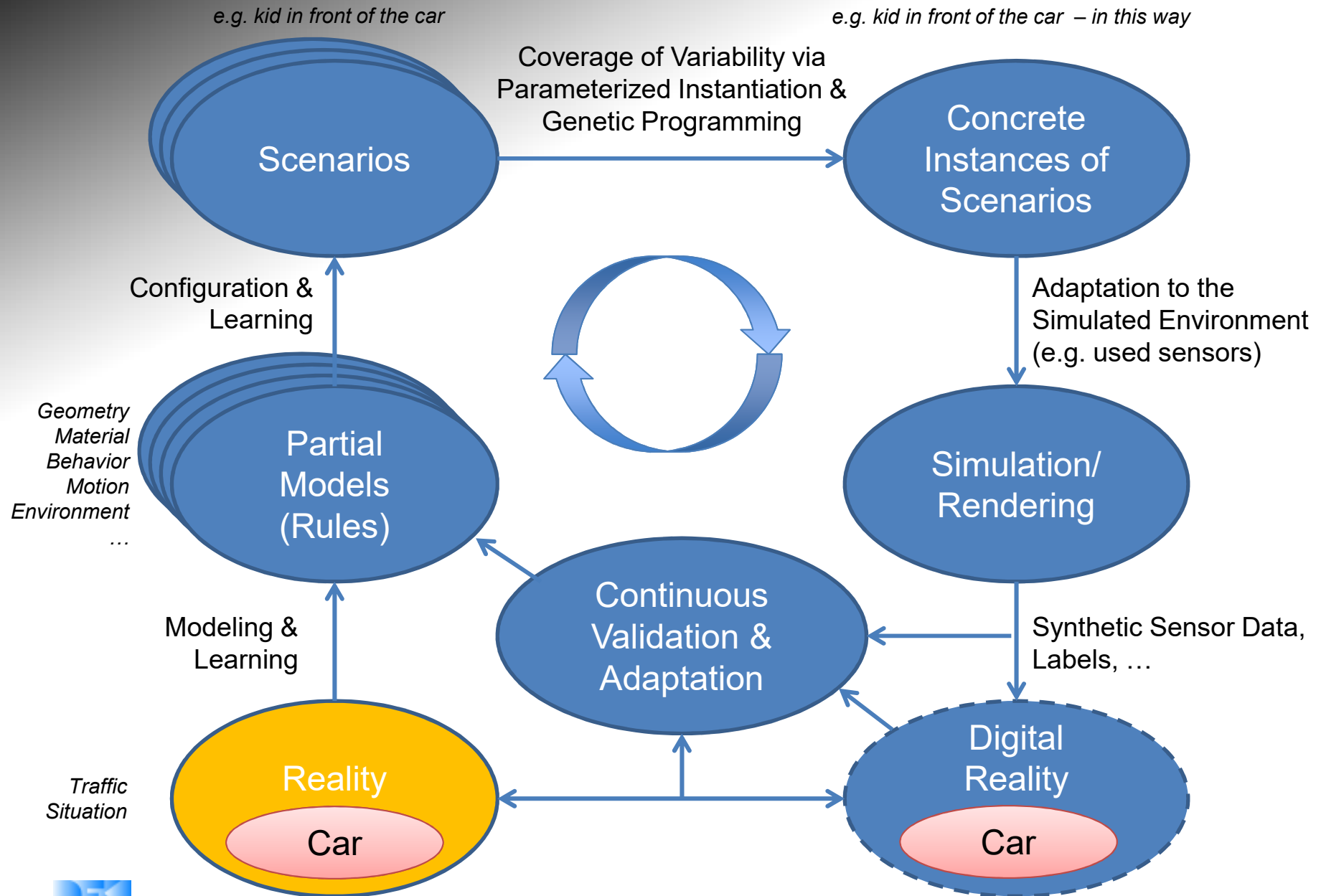




# Digital Reality: Training



# Digital Reality: Training Loop



# AI für Autonomous Driving



- **Requirements and Challenges**
  - **Learning of *critical situations***
    - *Creating proper models of the real world* (via learning)
    - *Generating* the required input data (via models)
    - *Covering the required variability* of the input data
    - Requirements on the *size, accuracy and robustness* of the data?
  - **Benchmarking** the development processes
    - *Reproducible and standardized* test scenarios
    - *Scalable and fast* simulation, rendering, and learning
    - *Open architecture* for integrating different models & simulations
  - **Validating** the learned behavior for autonomous driving
    - *Calibrating* synthetic data against real data
    - *Identifying and adapting insufficient and missing models*
    - Setting up a *"Virtual TÜV"* for autonomous vehicles (systems?)

# REACT Project



- **BMBF-funded Project at DFKI**
  - Autonomous Driving: Modeling, Learning & Simulation Environment for Pedestrian Behavior in Critical Situations
- **Exploring Key Challenges**
  - *Motion Models and Motion Synthesis for Pedestrians*
  - *Modeling and Simulating High-Level Behavior*
  - *Hybrid Deep Learning for Agent-Based Simulations*
  - Automated Creation & Evaluation of Critical Situations
  - High-Performance Deep Learning (w/ AnyDSL)

# Digital Reality for Autonomous Driving (DFKI)





# Digital Reality for Autonomous Systems



# Using PreScan Data (TASS) for Semantic Segmentation



# Initial Scenario: Autonomous Breaking System (Euro NCAP)



- **Autonomous breaking test conducted by ADAC**
  - Significant efforts invested in tests in 2016



Images from: [https://www.adac.de/infotestrat/tests/crash-test/notbremsassistent\\_2016/default.aspx?ComponentId=250194&SourcePageld=31956](https://www.adac.de/infotestrat/tests/crash-test/notbremsassistent_2016/default.aspx?ComponentId=250194&SourcePageld=31956)

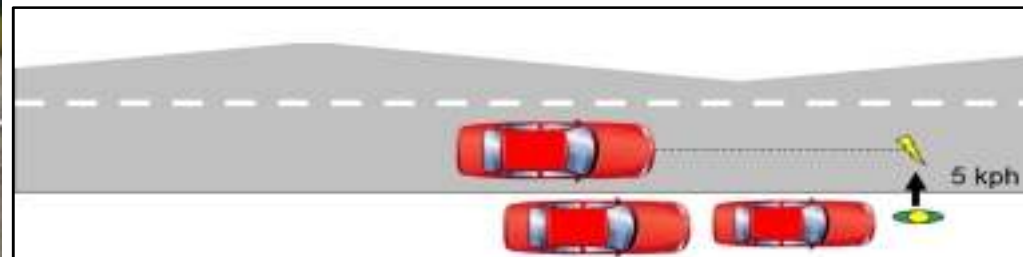
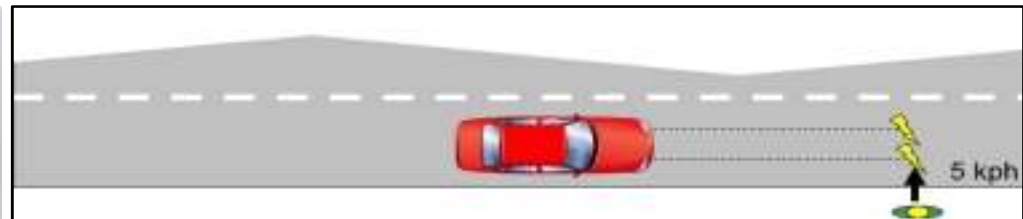




# Initial Scenario: Autonomous Breaking System (Euro NCAP)



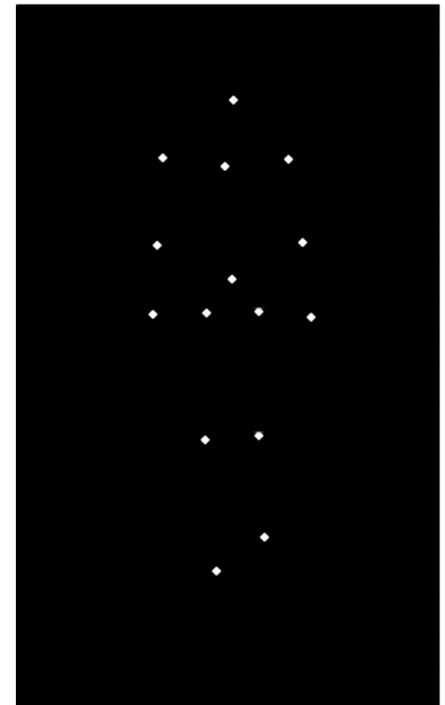
- **Insufficient Results in Recent Test by ADAC (2016)**
  - Problems: Night, speed, moving legs, only forward looking, ...
  - But even difficult cases were handled by at least some cars
- **Important for Pedestrian Protection (30% of deaths)**
  - Potentially strong impact with relatively simple setup
  - Easier tests, wider coverage, less false positives, ...



# Challenges: e.g. Recognition of Subtle Motions



- **Long history in motion research (>40 years)**
  - E.g. Gunnar Johansson's Point Light Walkers (1974)
  - Significant interdisciplinary research (e.g. psychology)
- **Humans can easily discriminate different styles**
  - E.g. gender, age, weight, mood, ...
  - Based on minimal information
- **Can we teach machines the same?**
  - Detect if pedestrian will cross the street
  - Parameterized motion model & style transfer
  - Predictive models & physical limits







# Digital Reality: Research Environment



# Projects in AI and Application Areas (only ASR)



- **Deep Learning**
  - **High-Performance Deep-Learning on heterogeneous HW**, new ExCluster project
  - **Large-Scale Deep-Learning Framework** (HP-DLF), with FhG-ITWM, TU Dresden
  - **Deep-Learning Training Center**, at UdS and DFKI
  - **Deep-Learning Competence Center**, at UdS and DFKI (submitted)
- **Computational Sciences**
  - **TransRegio SFB, TR244** (preliminary approval), jointly with UdS, TU Ilmenau, TU Karlsruhe (KIT)
  - **SFB „3D Microstructure Evolution“** (first review), jointly with MS, CS, and Math at UdS
  - **Learning Sensor Systems** (BMBF), jointly with FhG, U. Würzburg, U. Bamberg
  - **Understanding peta-byte data sets from SKA using model-based simulation** (BMBF proposal)
  - **Computational Sciences**: Need for AI in engineering and natural sciences (e.g. DPG and DGM)
- **Autonomous Driving**
  - **Motion Synthesis for Learning Pedestrian Behavior** (BMW/VW, Intel)
  - **Dreams4Cars**, EU project, together with IUI and RIC
  - **VDA Lead Initiative „Autonomous Driving“** (in all 3 planned projects: AI, V+V, SetLevel4to5)
- **Strategic Research Agenda**
  - **Excellence Cluster proposal „Digital Reality“**, SL Informatics Campus (final proposal submitted)
  - **EU “AI-on-Demand Platform”** (to be submitted)
  - **EU Flagship proposal “Humane AI”** (to be submitted)

# OpenDS



- **Example for highly visible automotive DFKI platform**
  - Open Source driving simulation platform
  - Validated tasks for psychological driver distraction research
  - Internationally widely used in research and industry
    - More than 10k registered users
    - Including: Google, Bosch, Continental, Honda, TomTom, Nuance, ...
    - Including: CMU, Stanford, Berkeley, MIT, TUM, TU-Berlin, ...
  - Also used for driver education (e.g. developing countries)
  - USP: Highly flexible infrastructure for research

# DFKI Competence Center Autonomous Driving (CCAD)



- **Thematic Research Center at DFKI**
  - Cutting across research of several research areas at DFKI
  - Exploiting DFKI-internal synergies
  - Increased visibility in research and industry
  - One-Stop-Shop for external contacts & collaborations
  - Common platform and infrastructure projects
- **Addressing Strategic Interest in Autonomous Driving**

# Next Steps



- **Setting up network between industry & academia**
  - DFKI established as coordinator with large industry network
- **Academia:**
  - Short-term validation of the general approach and incr. results
  - Long-term research work on key challenges
  - Partner with focus on one of the partial models
  - Integration and networking between partners
- **Industry:**
  - Creation of initial models, acquisition of real data, validation
  - Integration into their development processes
- **Collaboration Framework**
  - Direct and publically funded activities (EU, national, etc.)
  - *Open architecture for learning from simulated, synthetic data*



# National AI Activities



- **New German Platform for AI: “Learning Systems”**
  - Exchange between research, industry, and society
- **New German AI research initiative**
  - New government: More money for research (3,5% GDP)
  - “National Masterplan for AI”, no details yet
- **German-French AI Collaboration**
  - Planned at the highest level (Macron/Merkel)
  - Details still being defined
  - Budget of may be as large as 2x 250 M€

# Future of AI



- **AI as a *fundamental game changer* in many areas**
  - Cars, robots, virt. assistants, urban planning, energy mgmt., ...
  - Nat. sciences, data analytics, social, finance, ...
  - Needs scientists and experts from many different fields
- **Common approach and challenges**
  - Simultaneously learn models & good actions (given models)
  - Requires large-scale learning, simulation, collaboration
- **Need for a joint research platform & community**
  - We have done this before: Human Genome project & CERN
  - Can we learn from these approaches?

# „CERN for AI“



- **Mission:**
  - Collaborative, scientific effort to accelerate and consolidate the development and uptake of AI for the benefit all humans and our environment
  - Continuously improve our understanding of the world around us and use this information to explore and evaluate better ways to act and interact in this world
  - Provide a transparent, open, and flexible platform supporting a wide range of research capabilities while facilitating transfer and exchange with industry
  - Broadly discuss the policies and consequences of using AI
- **Our Vision: „Human<sup>e</sup> AI“**



# Current AI Activities in EU



- **EU Flagship on “Human<sup>e</sup> AI” (aka. “CERN for AI”)**
  - “Towards AI Systems that Augment Human Intelligence by Understanding Us and the World Around Us”
    - Enhancing human capabilities instead of replacing them
    - Empowering humans instead of telling them what to do
    - Explainable, transparent, validated, trustworthy systems
    - Include at the core values, ethics, social, and other aspects
  - Organizing the AI community in the EU
    - Focus on fundamental research – *with strong impact on economy/society*
  - 10 years, 100 M€/a, starting 2019/2020
- **EU Call “AI-on-Demand Platform” (first step)**
  - Organizing the AI community in the EU
    - Focus on SW platform for non-experts
  - 3 years, one consortium, 20 M€, starting 2018
  - 2 follow-up projects planned for 2020

# Conclusions



- **Goal: Ability to Create a “Digital Reality”**
  - Machine Learning is the best known method
  - Still insufficient for many (critical) situations
- **Learning from Synthetic (and Real) Data**
  - Requires learning, modeling, simulation, and validation
- **Big Challenges Ahead**
  - Many promising partial results – but largely islands
  - Requires closer collaboration of industry & academia
  - Need for strategic agenda and investments (“CERN for AI”)
- **AI a Central Component of Future Systems**
  - Fundamental changes coming across domains
  - Need to address issues early on (values, ethics, social, ...)